

General conditions

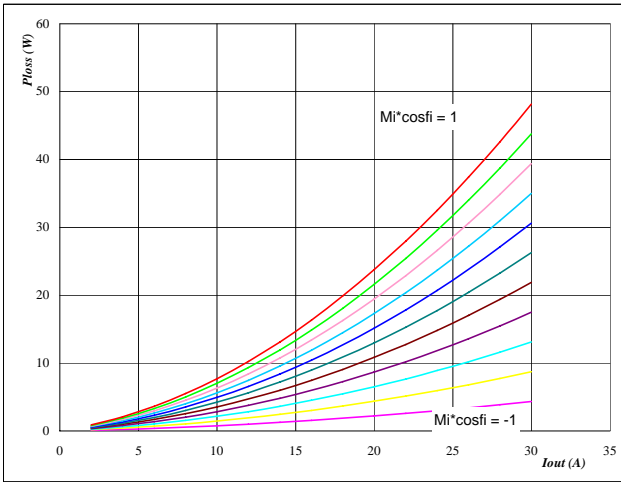
3phase SPWM

$V_{GEon} = 15\text{ V}$
 $V_{GEoff} = -15\text{ V}$
 $R_{gon} = 32\ \Omega$
 $R_{goff} = 32\ \Omega$

Figure 1 IGBT

Typical average static loss as a function of output current

$P_{loss} = f(I_{out})$

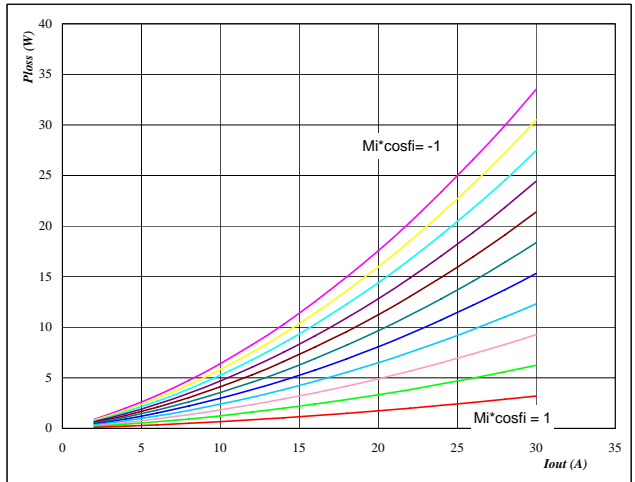


$T_j = 150\ \text{°C}$
 $Mi \cdot \cos\phi_i$ from -1 to 1 in steps of 0,2

Figure 2 FRED

Typical average static loss as a function of output current

$P_{loss} = f(I_{out})$

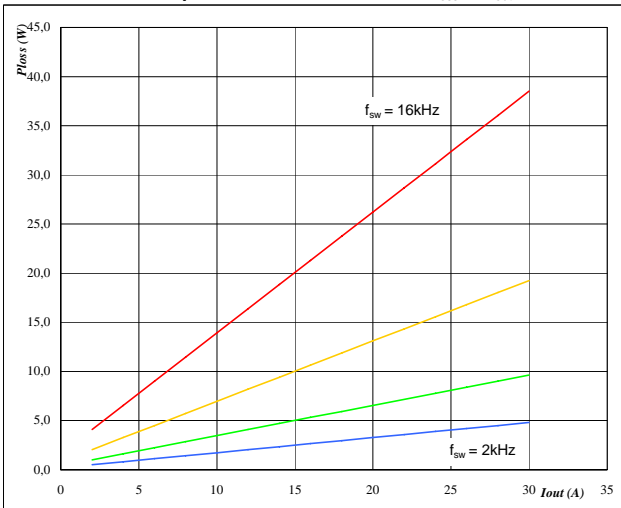


$T_j = 150\ \text{°C}$
 $Mi \cdot \cos\phi_i$ from -1 to 1 in steps of 0,2

Figure 3 IGBT

Typical average switching loss as a function of output current

$P_{loss} = f(I_{out})$

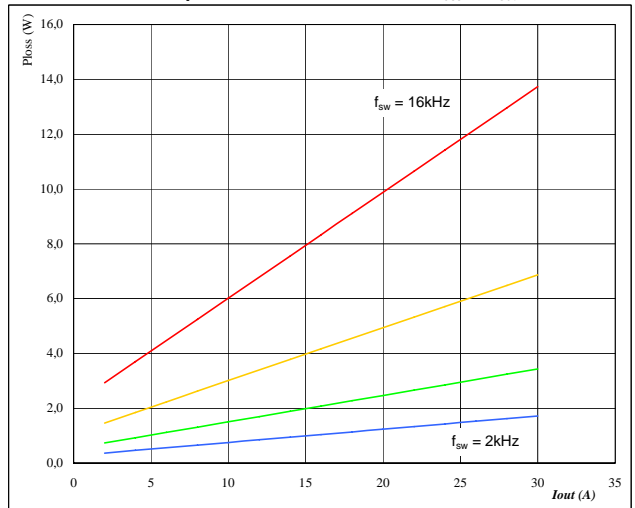


$T_j = 150\ \text{°C}$
 DC link = 600 V
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 4 FRED

Typical average switching loss as a function of output current

$P_{loss} = f(I_{out})$

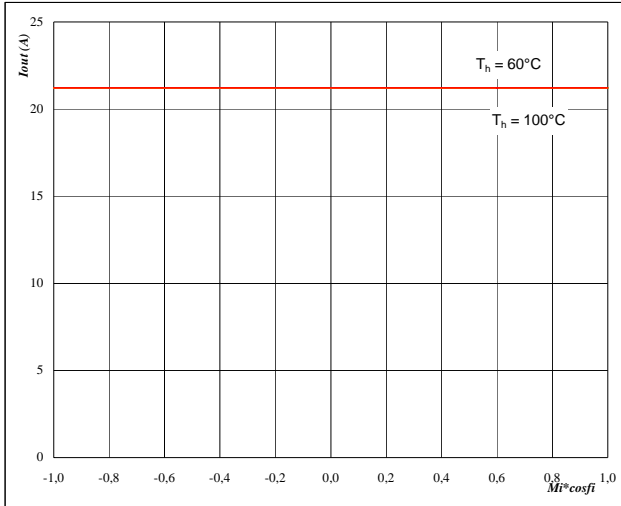


$T_j = 150\ \text{°C}$
 DC link = 600 V
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 5 Phase

Typical available 50Hz output current as a function $Mi \cdot \cos\phi$

$$I_{out} = f(Mi \cdot \cos\phi)$$

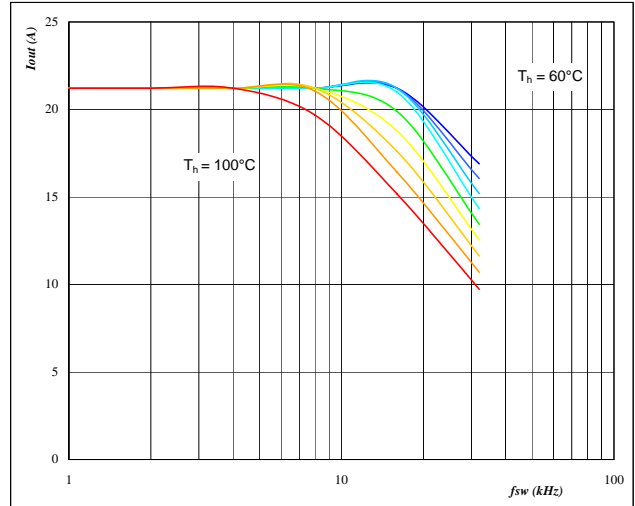


$T_j = 150^\circ\text{C}$
DC link = 600 V
 $f_{sw} = 4$ kHz
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 6 Phase

Typical available 50Hz output current as a function of switching frequency

$$I_{out} = f(f_{sw})$$

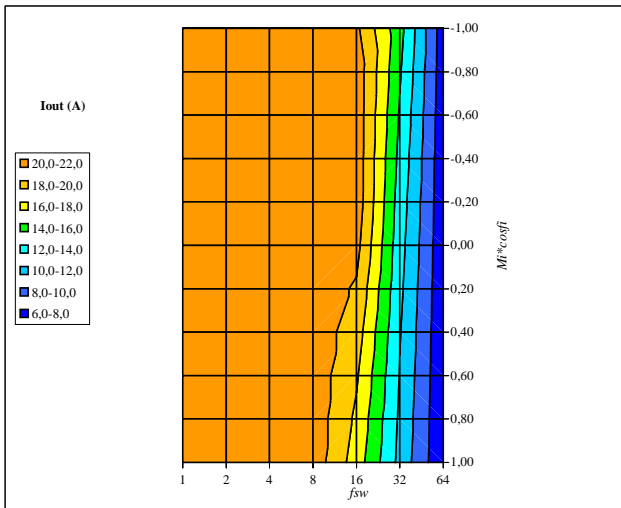


$T_j = 150^\circ\text{C}$
DC link = 600 V
 $Mi \cdot \cos\phi = 0,8$
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 7 Phase

Typical available 50Hz output current as a function of $Mi \cdot \cos\phi$ and switching frequency

$$I_{out} = f(f_{sw}, Mi \cdot \cos\phi)$$

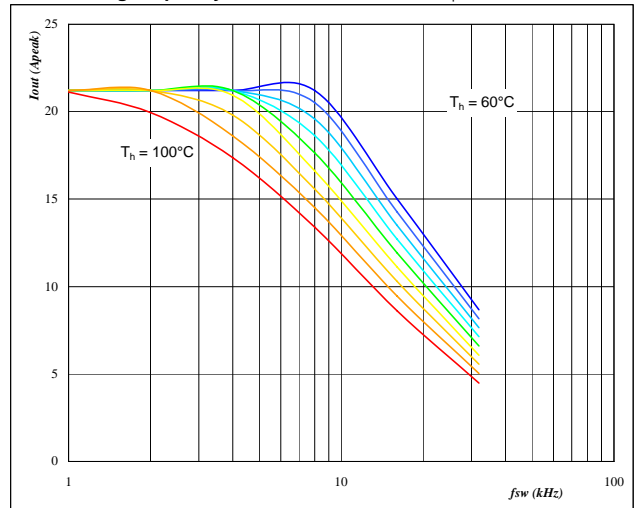


$T_j = 150^\circ\text{C}$
DC link = 600 V
 $T_h = 90^\circ\text{C}$

Figure 8 Phase

Typical available 0Hz output current as a function of switching frequency

$$I_{outpeak} = f(f_{sw})$$



$T_j = 150^\circ\text{C}$
DC link = 600 V
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 9 Inverter

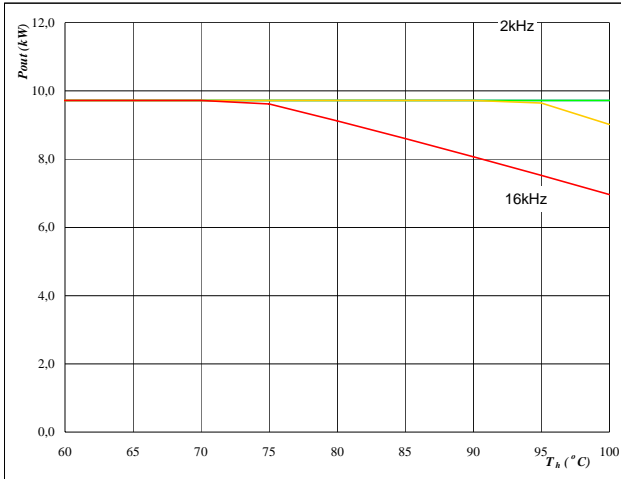
Typical available peak output power as a function of heatsink temperature
 $P_{out}=f(T_h)$

 $T_j = 150 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos\phi = 0,80$
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 10 Inverter

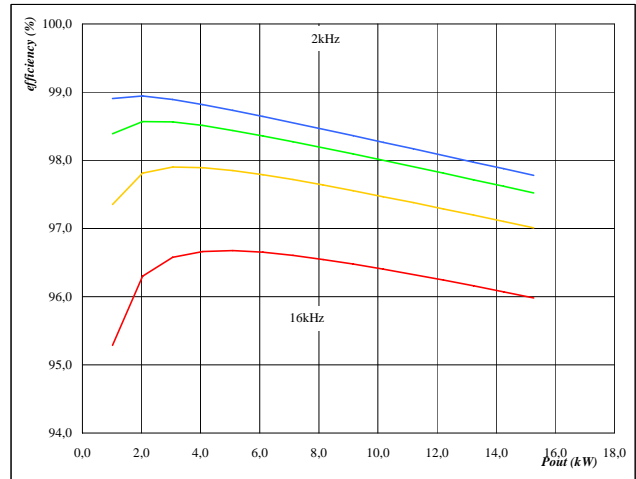
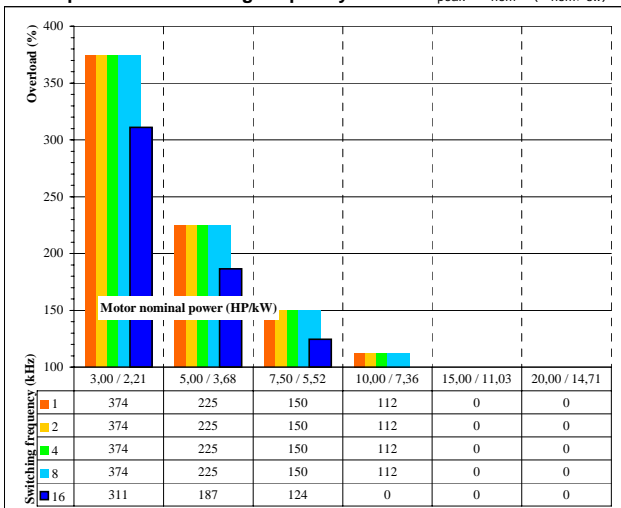
Typical efficiency as a function of output power
 $\text{efficiency}=f(P_{out})$

 $T_j = 150 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos\phi = 0,80$
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 11 Inverter

Typical available overload factor as a function of motor power and switching frequency
 $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$

 $T_j = 150 \text{ } ^\circ\text{C}$
 DC link = 600 V
 $M_i = 1$
 $\cos\phi = 0,8$
 f_{sw} from 1 kHz to 16 kHz in 2 steps
 $T_h = 90 \text{ } ^\circ\text{C}$
 Motor eff = 0,85