

General conditions

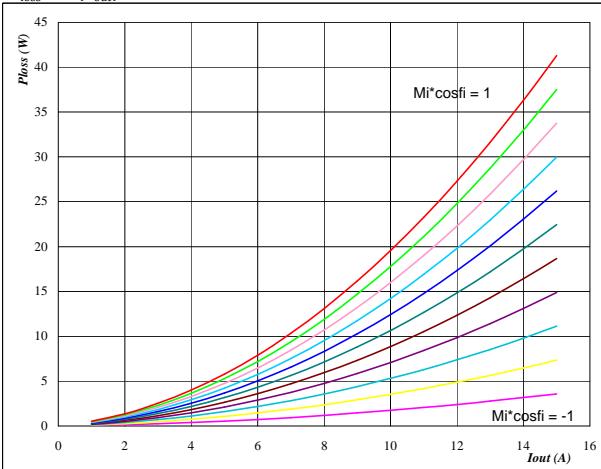
3phase SPWM	
$V_{G\text{On}}$	= 15 V
$V_{G\text{Off}}$	= 0 V
$R_{g\text{on}}$	= 64 Ω
$R_{g\text{off}}$	= 64 Ω

Figure 1

IGBT

Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

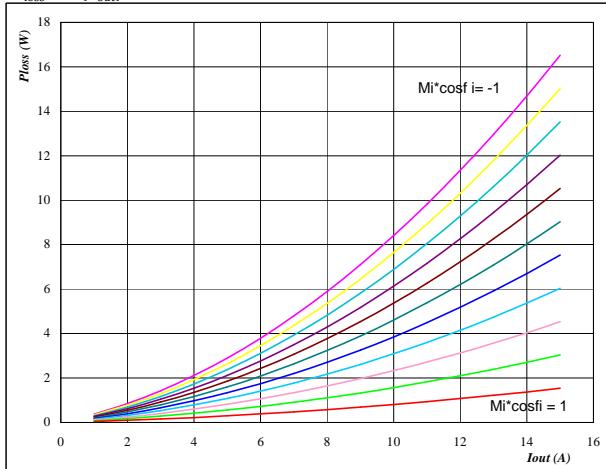
Mi*cosphi from -1 to 1 in steps of 0,2

Figure 2

FWD

Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

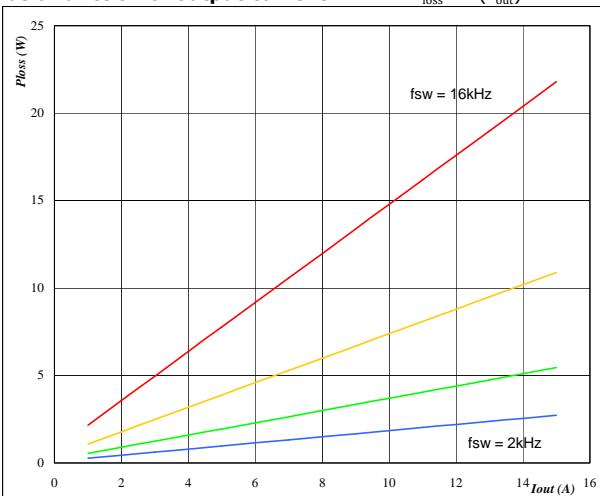
Mi*cosphi from -1 to 1 in steps of 0,2

Figure 3

IGBT

Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

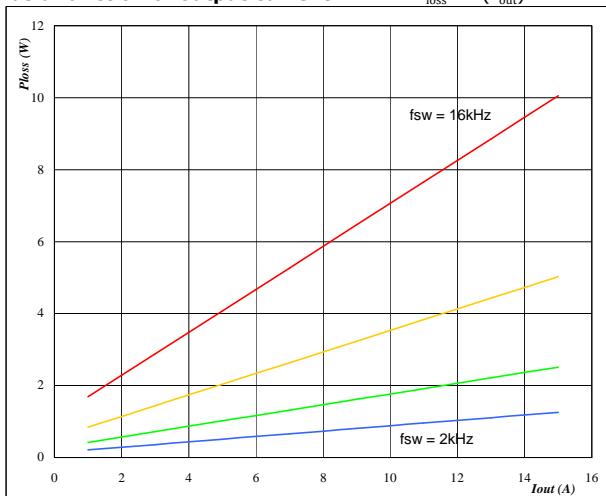
$$\text{DC-link} = 600 \text{ V}$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2**Figure 4**

FWD

Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

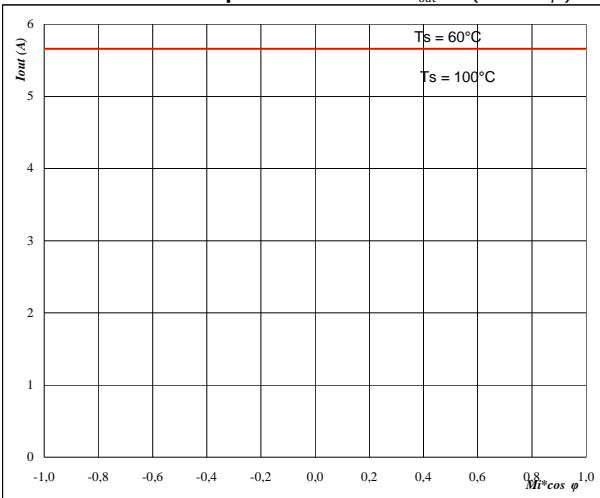
$$\text{DC-link} = 600 \text{ V}$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 5

Typical available 50Hz output current as a function $M_i \cos \varphi$

$$I_{\text{out}} = f(M_i \cos \varphi)$$

**At**

$T_j = 150 \text{ } ^\circ\text{C}$

DC-link = 600 V

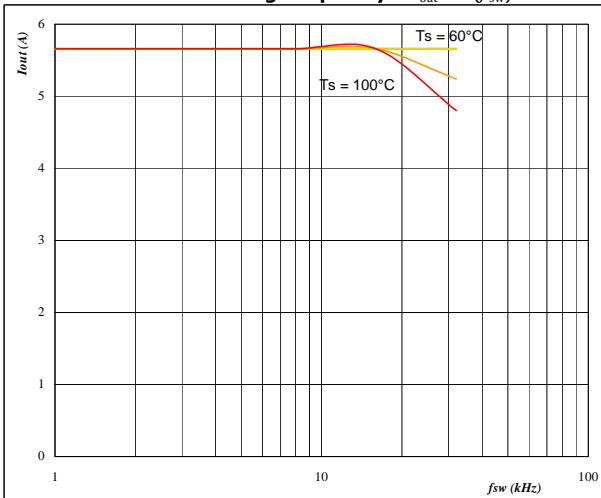
$f_{\text{sw}} = 4 \text{ kHz}$

T_s from $60 \text{ } ^\circ\text{C}$ to $100 \text{ } ^\circ\text{C}$ in steps of $5 \text{ } ^\circ\text{C}$

Phase**Figure 6**

Typical available 50Hz output current as a function of switching frequency

$$I_{\text{out}} = f(f_{\text{sw}})$$

**At**

$T_j = 150 \text{ } ^\circ\text{C}$

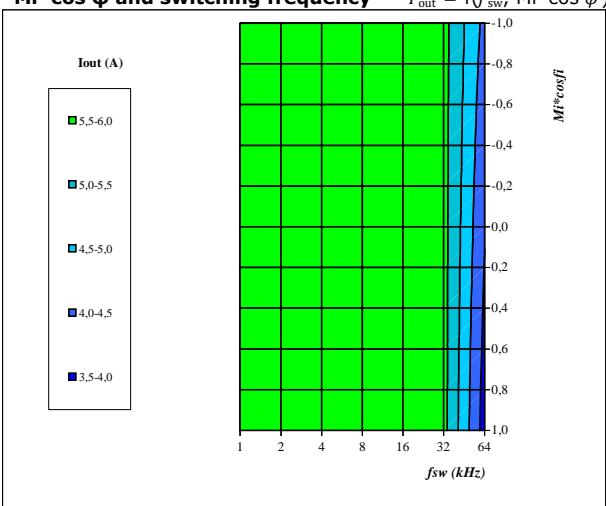
DC-link = 600 V

$M_i \cos \varphi = 0,8$

T_s from $60 \text{ } ^\circ\text{C}$ to $100 \text{ } ^\circ\text{C}$ in steps of $5 \text{ } ^\circ\text{C}$

Figure 7

Typical available 50Hz output current as a function of $M_i \cos \varphi$ and switching frequency

Phase**At**

$T_j = 150 \text{ } ^\circ\text{C}$

DC-link = 600 V

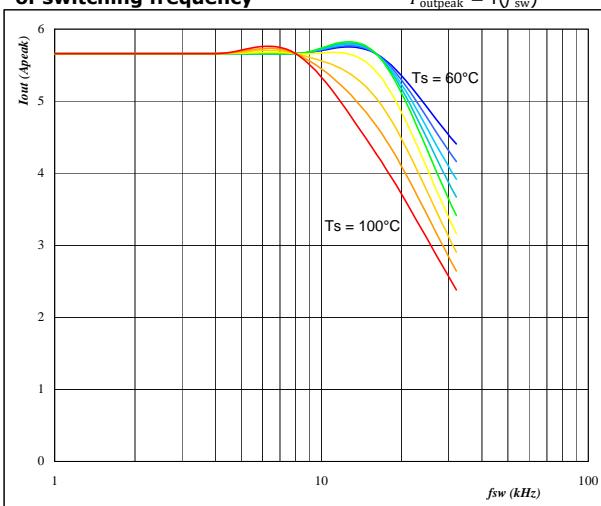
$T_s = 80 \text{ } ^\circ\text{C}$

Figure 8

Typical available 0Hz output current as a function of switching frequency

Phase

$$I_{\text{outpeak}} = f(f_{\text{sw}})$$

**At**

$T_j = 150 \text{ } ^\circ\text{C}$

DC-link = 600 V

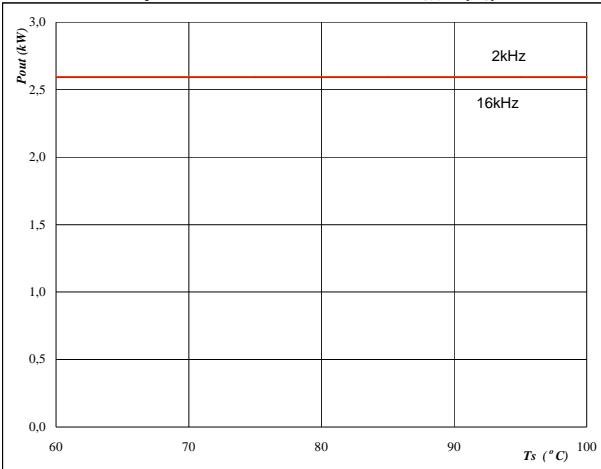
T_s from $60 \text{ } ^\circ\text{C}$ to $100 \text{ } ^\circ\text{C}$ in steps of $5 \text{ } ^\circ\text{C}$

$M_i = 0$

Figure 9

Inverter

Typical available peak output power as a function of heatsink temperature
 $P_{out}=f(T_s)$

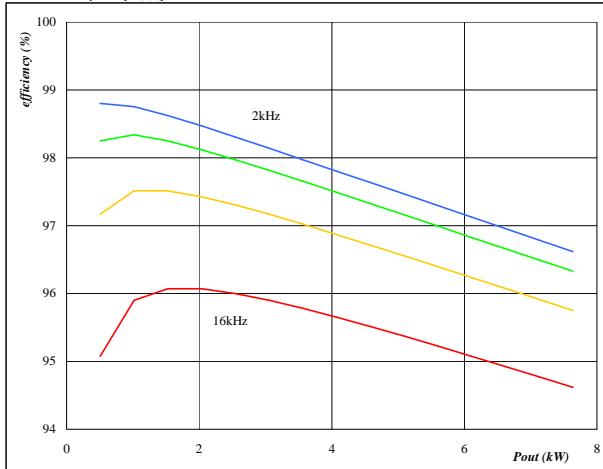
**At** $T_j = 150 \text{ } ^\circ\text{C}$

DC-link = 600 V

 $M_i = 1$ $\cos \varphi = 0,80$ f_{sw} from 2 kHz to 16 kHz in steps of factor 2**Figure 10**

Inverter

Typical efficiency as a function of output power
 $\text{efficiency}=f(P_{out})$

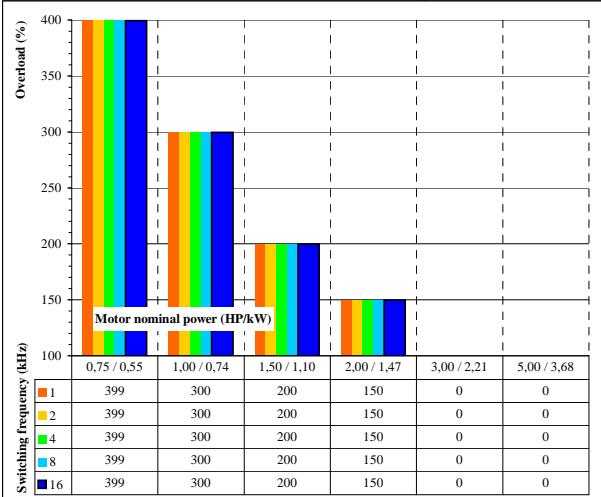
**At** $T_j = 150 \text{ } ^\circ\text{C}$

DC-link = 600 V

 $M_i = 1$ $\cos \varphi = 0,80$ f_{sw} from 2 kHz to 16 kHz in steps of factor 2**Figure 11**

Inverter

Typical available overload factor as a function of motor power and switching frequency
 $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$

**At** $T_j = 150 \text{ } ^\circ\text{C}$

DC-link = 600 V

 $M_i = 1$ $\cos \varphi = 0,8$ f_{sw} from 1 kHz to 16 kHz in steps of factor 2 $T_s = 80 \text{ } ^\circ\text{C}$

Motor eff = 0,85