

## MiniSKiiP® 1 PIM

## Inverter Application

1200 V / 15 A

## General conditions

3phase SPWM	
$V_{G\text{On}}$	= 15 V
$V_{G\text{Off}}$	= -15 V
$R_{g\text{on}}$	= 32 Ω
$R_{g\text{off}}$	= 32 Ω

figure 1.

IGBT

Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

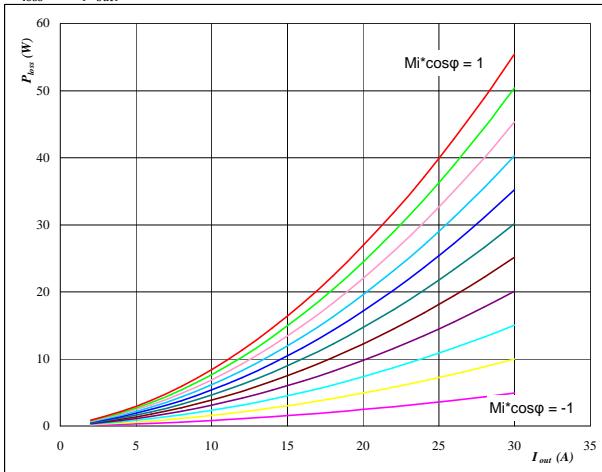
**At** $T_j = 150^\circ\text{C}$  $Mi \cdot \cos\varphi$  from -1 to 1 in steps of 0,2

figure 2.

FWD

Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

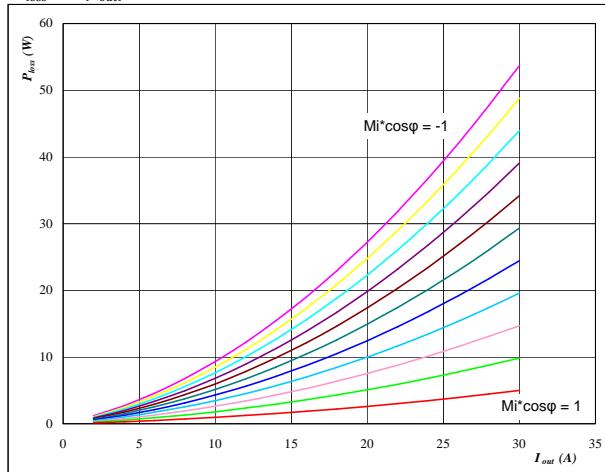
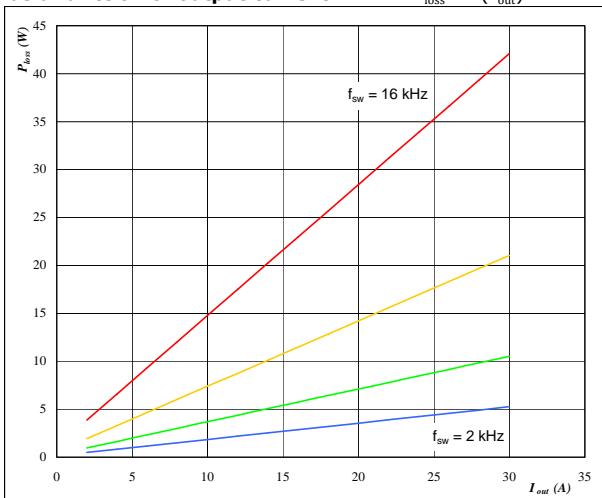
**At** $T_j = 150^\circ\text{C}$  $Mi \cdot \cos\varphi$  from -1 to 1 in steps of 0,2

figure 3.

IGBT

Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At** $T_j = 150^\circ\text{C}$ 

DC-link = 600 V

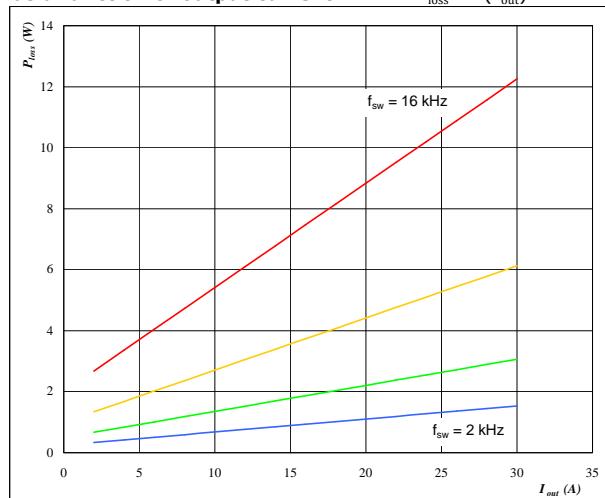
 $f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

figure 4.

FWD

Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At** $T_j = 150^\circ\text{C}$ 

DC-link = 600 V

 $f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

## MiniSKiiP® 1 PIM

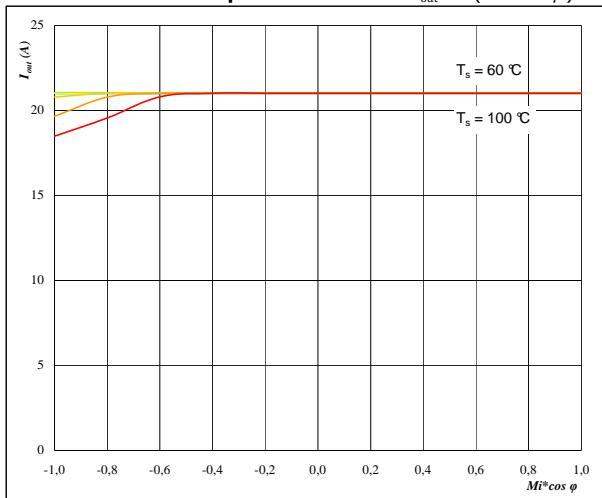
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figure 5.

**Typical available 50Hz output current  
as a function  $M_i \cos \varphi$**

$$I_{out} = f(M_i \cos \varphi)$$

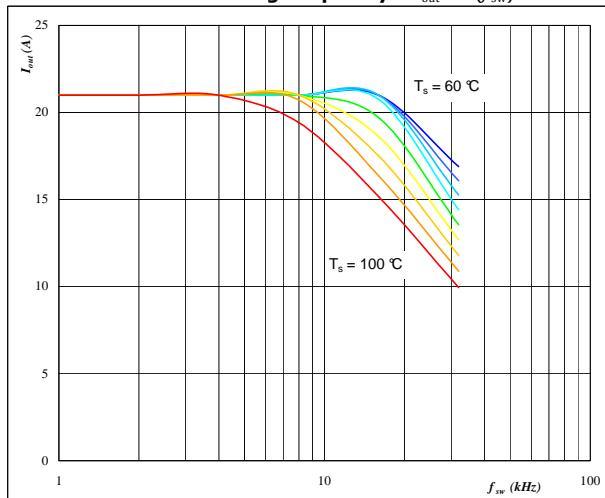


Phase

figure 6.

**Typical available 50Hz output current  
as a function of switching frequency**

$$I_{out} = f(f_{sw})$$



Phase

**At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

 $f_{sw} = 4 \text{ kHz}$  $T_s$  from  $60 \text{ } ^\circ\text{C}$  to  $100 \text{ } ^\circ\text{C}$  in steps of  $5 \text{ } ^\circ\text{C}$ **At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

 $Mi \cos \varphi = 0,8$  $T_s$  from  $60 \text{ } ^\circ\text{C}$  to  $100 \text{ } ^\circ\text{C}$  in steps of  $5 \text{ } ^\circ\text{C}$ 

figure 7.

**Typical available 50Hz output current as a function of  
 $Mi \cos \varphi$  and switching frequency**

Phase

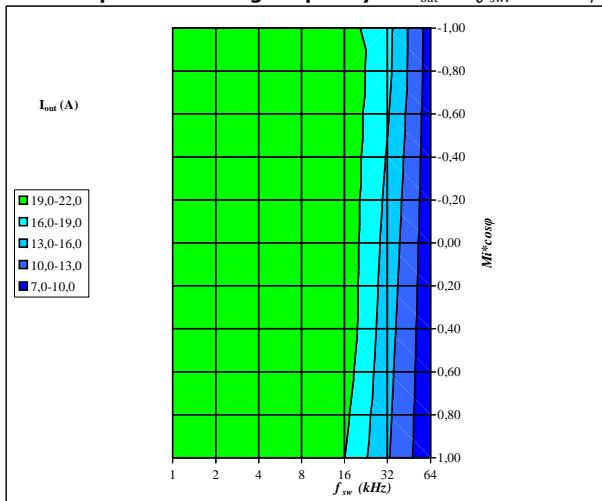
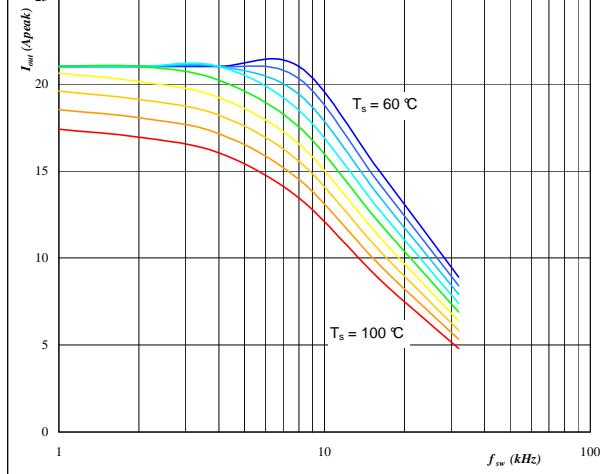


figure 8.

**Typical available 0Hz output current as a function  
of switching frequency**

Phase

$$I_{outpeak} = f(f_{sw})$$

**At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

 $T_s$  from  $60 \text{ } ^\circ\text{C}$  to  $100 \text{ } ^\circ\text{C}$  in steps of  $5 \text{ } ^\circ\text{C}$  $Mi = 0$ **At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

 $T_s = 80 \text{ } ^\circ\text{C}$

## MiniSKiiP® 1 PIM

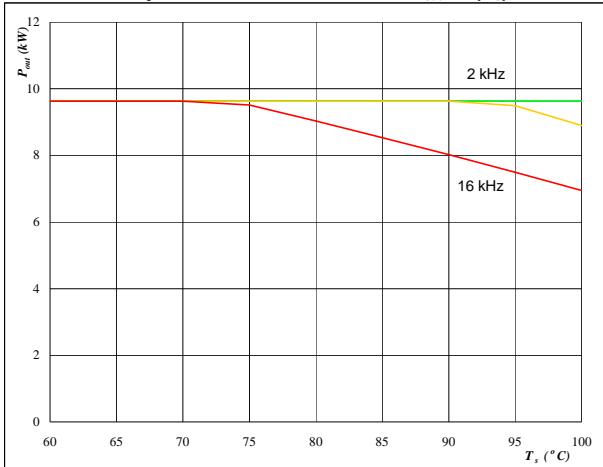
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figure 9.

Inverter

**Typical available peak output power as a function of heatsink temperature**

$$P_{out} = f(T_s)$$
**At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

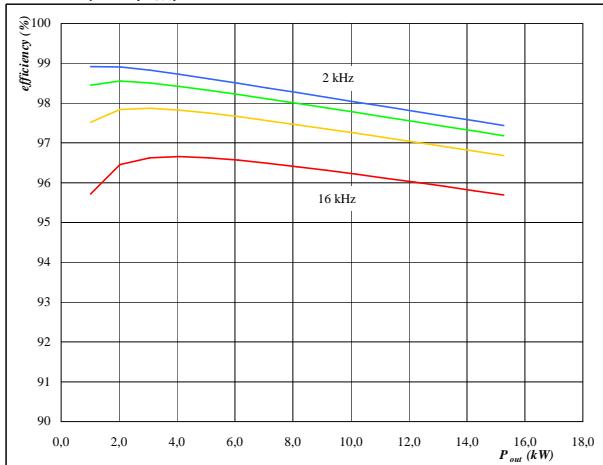
Mi = 1

 $\cos \varphi = 0,80$  $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

figure 10.

Inverter

**Typical efficiency as a function of output power**

$$\text{efficiency} = f(P_{out})$$
**At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

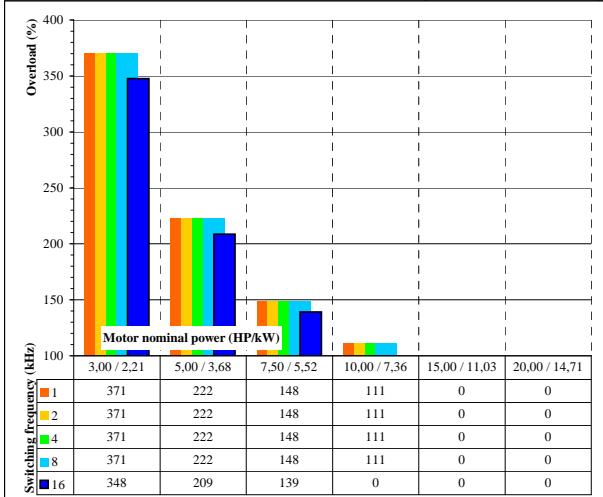
Mi = 1

 $\cos \varphi = 0,80$  $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

figure 11.

Inverter

**Typical available overload factor as a function of motor power and switching frequency**

$$P_{peak} / P_{nom} = f(P_{nom}, f_{sw})$$
**At** $T_j = 150 \text{ } ^\circ\text{C}$ 

DC-link = 600 V

Mi = 1

 $\cos \varphi = 0,8$  $f_{sw}$  from 1 kHz to 16 kHz in steps of factor 2 $T_s = 80 \text{ } ^\circ\text{C}$ 

Motor eff = 0,85