

Handling Instructions

for flow **OB** packages



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Rev. 05

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Table of Contents

1	General assembly instructions 5
2	Specification for PCBs
2.1	Specification for modules with solder pins
2.2	Required PCB cutouts for screwing holes7
3	Specification for module backside surface
4	Specification for heat sink
5	Specification for thermal interface materials10
5.1	OPTION 1: Thermal paste:
5.2	OPTION 2: Thermal foil:10
5.3	OPTION 3: Pre-applied thermal interface material11
6	Specification for fastening screws to the heat sink11
6.1	Screw with pre-assembled washers11
6.2	Mounting with automatic screwdriver11
7	Recommendation for soldering13
7.1	Wave soldering of modules with solder pins14
7.2	Hand soldering parameters14
8	ESD protection14
9	Environmental conditions14
9.1	Parameters of environment classes15
9.1.1	Climatic conditions15
9.1.2	Biological conditions16
9.1.3	Chemically active substances16
9.1.4	Mechanically active substances16
9.1.5	Mechanical Conditions16
9.2	Handling of trays
10	Disclaimer19



Table of Figures

1. Figure: Module	e with PCB and heat sink	. 5
2. Figure: Solder	pin diameter	. 6
3. Figure: PCB cu	Itouts for two-clip modules with solder pins	. 7
4. Figure: Scratc	h and etching hole dimensions	. 8
5. Figure: Polishe	ed surface	. 9
6. Figure: Discolo	pration of substrate	. 9
7. Figure: Finger	print on the surface	. 9
8. Figure: Therm	al paste honeycomb pattern	10
9. Figure: Recom	mended thermal foil dimensions	10
10. Figure: Record	mmended torque and speed curve	12
11. Figure: Plate	d through hole, good soldering	13
12. Figure: Exam	ples of discolored solder pins	13
13. Figure: Typic	al profile for wave soldering	14
	of trays	

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Revision History

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1 General assembly instructions

The *flow*0B type modules have to be mounted *first* to PCB, and afterwards fixed to heat sink. The electrical connections between module and PCB are made by soldering. It is also required to fix the PCB to the heat sink with threaded spacers. The number and the position of the fixing points depend on the design of the circuit and location of different masses like capacitors or inductors and the environment of the system. General recommendation cannot be given.



1. Figure: Module with PCB and heat sink

The distance between the top surface of the heat sink and the bottom plane of the PCB is defined by the module type, which can be 12 mm or 17 mm.

Recommendation for spacer height:

- 12^{-0.1} mm
- 17^{-0.1} mm

During the handling process, special care should be taken with the solder pins, especially if the pins get stuck due to bent pins or tight hole diameter.

Important!

During the assembly process, solder pins must not be pushed! During the handling process, special care should be taken with the solder pins, especially if the pins get stuck due to bent pins or tight hole diameter.

The tension of the pin must not exceed ± 5 N at a maximum substrate temperature of 100 °C.



2 Specification for PCBs

- Printed board material meets the requirements of IEC 61249-2-7;
- The number of conductive layers is not limited.

2.1 Specification for modules with solder pins

- The module must be fixed to the PCB with 2 screws (type BN82428, D=2.5 mm and L=6 mm) before soldering the pins into the PCB. Mounting torque: 0.4 Nm.
- After screwing, all pins must be soldered into the PCB. The hole diameters on the PCB has to be designed according to the soldering pin diameter which is \emptyset 1±0.05 mm. For further dimensions or 3D model please contact your local sales manager.



2. Figure: Solder pin diameter



2.2 Required PCB cutouts for screwing holes



3. Figure: PCB cutouts for two-clip modules with solder pins

In the keepout area it is not allowed to be any PCB component between module and PCB.



3 Specification for module backside surface

The module backside is important for the thermal management of the power module. Imperfection is allowed if it does not lead to an R_{th} increase of >2% (assembled acc. VIN instruction). Acceptance criteria for module backside surface:

Polishing (see figure 5.):

- Polishing have to be accepted
- Polishing of modules with Ni plated surface is acceptable if copper doesn't become visible (if the copper is visible, see criteria for scratches)

Steps, Flash (see figure 4.):

• Max height of 10 µm

Scratches (see figure 4.):

- Max depth of 300 µm
- Max width of 600 μm
- The scratched area must not exceed 5 % of the total substrate surface.

Etching holes (see figure 4.):

- Max diameter of 1000 μm and max. depth of 300 μm
- Max diameter of 2000 μm and max depth of 250 μm

Other (see figure 6, 7.):

• Discolorations and fingerprints are only surface imperfections (cosmetic) and do not affect the module's functionality

Depth & diameter of etching holes



Depth & width of scratches

4. Figure: Scratch and etching hole dimensions







6. Figure: Discoloration of substrate



7. Figure: Fingerprint on the surface

4 Specification for heat sink

The whole heat sink surface under the module must be plane, clean and free of particles.

- The flatness tolerance should be: < 25 μ m in general.
- In case the thermal paste thicker than 50 μm the flatness tolerance can be < 50 μm. (A flatness tolerance specifies a tolerance zone defined by two parallel planes within which the surface must lie.)
- The surface roughness should be less than: $R_z < 10 \ \mu m$.
- Heat sink surface imperfections should be within the values described for the module backside surface (please refer to section 3).



5 Specification for thermal interface materials

5.1 **OPTION 1:** Thermal paste:

- A. Apply a homogeneous layer of thermal conductive paste over the whole backside of the module, with a roller or spatula.
- B. Apply thermal paste in a honeycomb pattern, seen on 8. Figure: The preferred technology for paste application is screen printing. For a drawing of the pattern please contact your local sales representative.

The recommended thermal paste thickness is 55 μm ± 15 μm in this case.

Thermal paste thicker than recommended will increase thermal resistance ($R_{\rm th}$).



8. Figure: Thermal paste honeycomb pattern

5.2 **OPTION 2: Thermal foil:**

- A thermal foil comprising of an aluminium core layer and two outer layers of phase change material should be used.
- The total thickness of the foil has to be less than 80 μ m. Thicker foils could cause the ceramic substrate to break and increase the thermal resistance.
- Recommended foil type: ALC5 or ALF5 (Boyd Corporation)
- Recommended foil dimensions: see below.



9. Figure: Recommended thermal foil dimensions

- The thickness of the foil is less than 80 µm.
- Material of the foil is aluminum, covered with a phase change material.



5.3 OPTION 3: Pre-applied thermal interface material

- The modules may have already been pre-printed with thermal interface material.
- For types which can be supplied with pre-applied TIM please contact your local sales representative.

6 Specification for fastening screws to the heat sink

- Screws M4 (recommended screw type DIN 7984)
- Min. depth of the screw in the heat sink: 6 mm
- Flat washer ISO 7092 (DIN 433)
- Spring washer DIN127 or DIN 128
- Mounting torque: $2 \text{ Nm} < M_{s} < 2.2 \text{ Nm}$

A torque wrench shall be used to tighten the mounting screws at the specified torque as excessive torque may result in damage or degradation of the device. The inaccuracy of torque wrench tightening method can range up to ± 12 %. This has to be taken into account to prevent over-tightening the fastener.

Due to excessive temperature fluctuations washers should be used to prevent the loosening of the screws. After accurate tightening of the screws the spring washer exerts a constant force on the joint. The flat washer distributes this force on the plastic surface.

6.1 Screw with pre-assembled washers

Screws with pre-assembled washers (SEMS or kombi screws) combine the screw and the washers into a single component. These screws eliminate the need to slip the washers into place by hand, boosting the speed and efficiency of the assembly process. The specifications of these screws are provided below:

- Screw size M4 according to DIN 6900 (ISO 10644; JIS B1188)
- Flat washer according to DIN 6902 Type C (ISO 10673 Type S; JIS B1256)
- Split lock spring washer according to DIN 6905 (JIS B1251)
- Mounting torque range: $2 \text{ Nm} < M_{s} < 2.2 \text{ Nm}$

6.2 Mounting with automatic screwdriver

For a fast, reliable and repeatable screwing process an automatic screwdriver with two stage tightening method is recommended. The screwdriver starts fast in the first stage and slows down after the first target torque is reached to accurately tighten the screw to the final target. For torque and speed recommendations see below the curves (*10. Figure:*) and values:

Torque

- Cycle start: 0.3 Nm
- First target: 0.5 Nm
- Final tq min.: 1.6 Nm
- Final target: 1.8 Nm
- Final tq max.: 2 Nm



Speed

- Soft start speed: 96 rpm -_
- Step 1 speed: max. 650 rpm _
- Step 2 speed: max. 12 rpm



10. Figure: Recommended torque and speed curve



7 Recommendation for soldering

• Plated through holes should exhibit a vertical solder fill of 100 %, with a fully formed fillet on the solder side and evidence of 100 % wetting on the component side lead, barrel and pad.



11. Figure: Plated through hole, good soldering

• The solder pins of the *flow OB* modules are plated with a nickel underlayer and a continuous tin finish to promote solderability. The tin finish can be discolored due to production process or storage conditions. This is merely a cosmetic imperfection and does not influence the solderability of pins. Different solder pins on the same module may exhibit different levels of discoloration as shown in the examples in *12. Figure:* .



12. Figure: Examples of discolored solder pins





7.1 Wave soldering of modules with solder pins

13. Figure: Typical profile for wave soldering

7.2 Hand soldering parameters

•	Max, s	older iron	temperature:	350 °C
•	Thur. 5			JJ0 C

- Max. contact time with component lead: 10 s З
- Number of heat cycles:

8 ESD protection

Modules are sensitive to electrostatic discharge which can damage or destroy sensitive semiconductors. All modules are ESD protected in the shipment box by semi conductive plastic trays. During the handling and assembly of the modules it is recommended to wear a conductive grounded wrist band and ensure a conductive grounded working place.

Please take into consideration the following standards for handling electrostatic-sensitive devices: EN61340-5-1, ANSI S20.20

9 **Environmental conditions**

The modules can be subjected to environmental conditions characterized by the following classes:

1K2 / 1B1 / 1C1 / 1S2 / 1M2 Storage:



Transportation: 2K2 / 2B1 / 2C1 / 2S1 / 2M2

Operation: 3K3

These classes are defined in the IEC 60721-3-1 and IEC 60721-3-2 and IEC 60721-3-3 standards. The modules with wire pins have 1 year shelf life with the given storage conditions.

Flammability classification of the plastic material for *flow* 0B are V-0 and 5-VA (self-extinguishing, no dripping of flaming particles) according to UL 94, IEC 60695-11-10 and IEC 60695-11-20 test methods.

9.1 **Parameters of environment classes**

The parameters detailed below are for informative purposes only. This section does not substitute the above mentioned standards. Please read the IEC 60721-3-1 and IEC 60721-3-2 standards for the description of the environment classes.

9.1.1 Climatic conditions

1K2 Air temperature: 5 °C to 40 °C Humidity: 5 % to 85 % RH but max. 1 g/m3 to 25 g/m3 absolute Rate of change of temperature: 0.5 °C/min Air pressure: 70 kPa to 106 kPa Solar radiation: 700 W/m2 Movement of surrounding air: 1 m/s Condensation: No Precipitation: No Water from other sources than rain: No Formation of ice and frost: No 2K2 Temperature: -25 °C to 60 °C ±25 °C Change of temperature air/air: Relative combined humidity not max. 75 % (at 30 °C temperature) with rapid temperature changes: combined Relative humidity with rapid temperature changes: No Low air pressure: 70 kPa Change of air pressure: No Solar radiation: 700 W/m2 Movement of surrounding air: No Precipitation: No Heat radiation: No Water from other sources than rain: No Wetness: No 3K3 5% to 85% Relative humidity: Absolute humidity: 1 g/m3 to 25 g/m3 Condensation: No Precipitation: No



Formation of ice: No

9.1.2 Biological conditions

1B1

Flora and fauna: Negligible

2B1

Flora and fauna: No

9.1.3 Chemically active substances

1C1

Sea and road salts: areas.)	No (Salt mist may be present in sheltered locations of coastal
Sulphur dioxide:	0.1 mg/m3
Hydrogen sulphide:	0.01 mg/m3
Chlorine:	0.01 mg/m3
Hydrogen chloride:	0.01 mg/m3
Hydrogen fluoride:	0.003 mg/m3
Ammonia:	0.3 mg/m3
Ozone:	0.01 mg/m3
Nitrogen oxides:	0.1 mg/m3 (Expressed in equivalent values of Nitrogen dioxide.)

2C2

Sea salts: Sulphur dioxide: Hydrogen sulphide: Nitrogen oxides: dioxide.)	none 0.1 mg/m3 0.01 mg/m3 0.1 mg/m3 (Expressed	in	the	equivalent	values	of	Nitrogen
Ozone:	0.01 mg/m3						
Hydrogen chloride:	0.1 mg/m3						
Hydrogen fluoride:	0.003 mg/m3						
Ammonia:	0.3 mg/m3						

9.1.4 Mechanically active substances

1S2

Sand:30 mg/m3Dust (suspension):0.2 mg/m3Dust (sedimentation):1.5 mg/(m2h)2S1Sand in air:NoDust (sedimentation):No

9.1.5 Mechanical Conditions

1M2

Stationary vibration, sinusoidal Frequency range: 2 Hz to 9 Hz



displacement amplitude: 1.5 mm Frequency range: 9 Hz to 200 Hz peak acceleration: 5 m/s2 Non stationary vibration, including shock Shock response spectrum type L peak acceleration: 40 m/s² Static load: 5 kPa 2M2* Stationary vibration sinusoidal Frequency range: 2 Hz to 9 Hz displacement amplitude: 3.5 mm Frequency range: 9 Hz to 200 Hz peak acceleration: 10 m/s2 200 Hz to 500 Hz Frequency range: peak acceleration: 15 m/s2 Stationary vibration, random Acceleration $1 \text{ m}^2/\text{s}^3$ spectral density: Frequency range: 10 Hz to 200 Hz, and Acceleration spectral density: $0.3 \text{ m}^2/\text{s}^3$ 200 Hz to 2000 Hz Frequency range: The later range can be neglected transporting with vehicles with high damping. Non stationary vibration, including shock Shock response spectrum type I. peak acceleration: 100 m/s² and Shock response spectrum type II. peak acceleration: 300 m/s² *Free fall: weight and drop height deviate from 2M2 tested acc. to internal standard: F23047-A1004-S000-01-76 **Specimen Weight Drop Heights [mm]** Standard Level Extra Level [kg] up to 9,5 kg 760 460 over 9,5 to 18,6 kg 310 610 over 18,6 to 27,7 kg 200 460 over 27,7 kg 200 310 Number of Drops 3 7 Around any of the edges. Toppling Rolling, pitching Angle: ±35°

Period:8 s35° may occur for short time periods but 22.5° may persist permanently.Acceleration 20 m/s^2 Static load:10 kPa



9.2 Handling of trays

The modules are transported in layer of trays and every layer has to be rotated on each other by 180° to guarantee that all the modules are safe. This is also valid any time after unpacking. *14. Figure* shows the trays in wrong and in good positioning.



14. Figure: Layer of trays



10 Disclaimer

The information and recommendations in this document are based on standards and common engineering practices. Customer specific applications and specifications may require additional processes and tests that may supersede those recommended in this document.

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