

**General conditions**
**3phase SPWM**

$$V_{GEon} = 15 \text{ V}$$

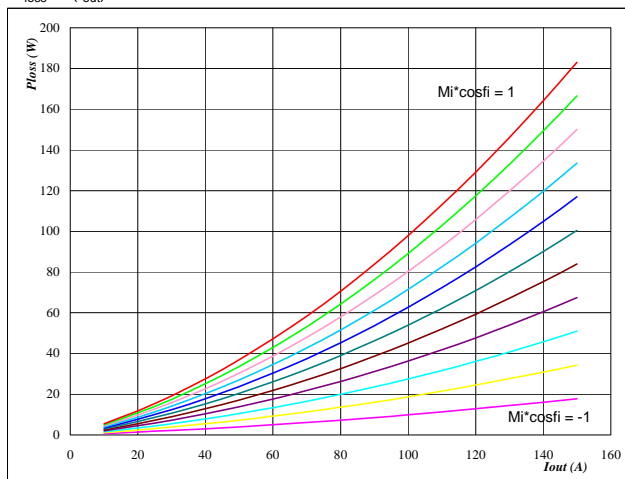
$$V_{GEoff} = -15 \text{ V}$$

$$R_{gon} = 4 \text{ } \Omega$$

$$R_{goff} = 4 \text{ } \Omega$$

**Figure 1**
**IGBT**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

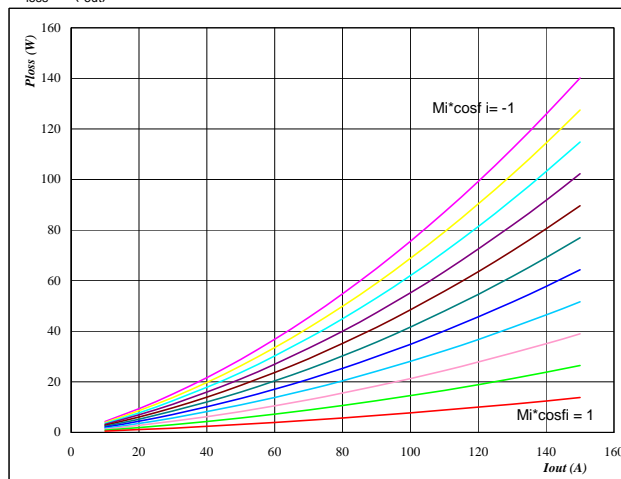

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $M_i \cdot \cos \phi$  from -1 to 1 in steps of 0,2

**Figure 2**
**FRED**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

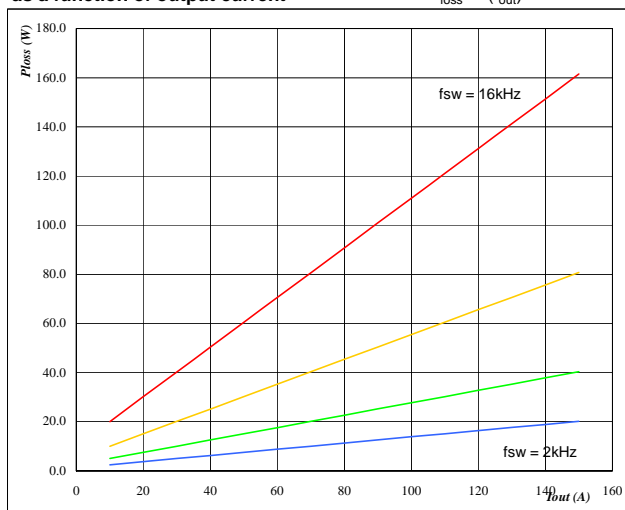

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $M_i \cdot \cos \phi$  from -1 to 1 in steps of 0,2

**Figure 3**
**IGBT**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**

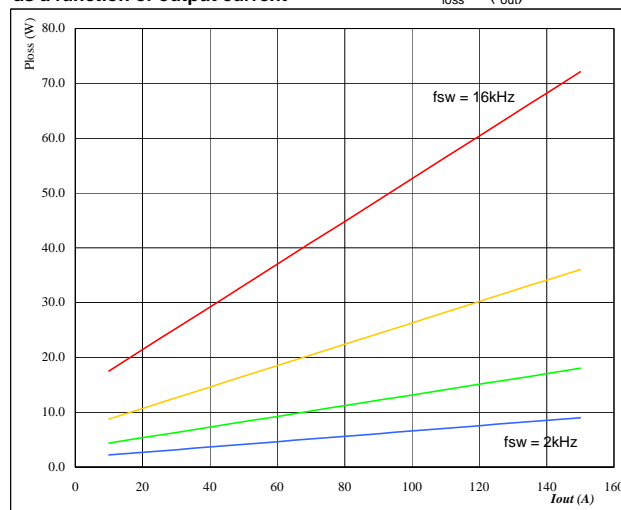
$$T_j = 125 \text{ } ^\circ\text{C}$$

DC link = 600 V

 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 4**
**FRED**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

DC link = 600 V

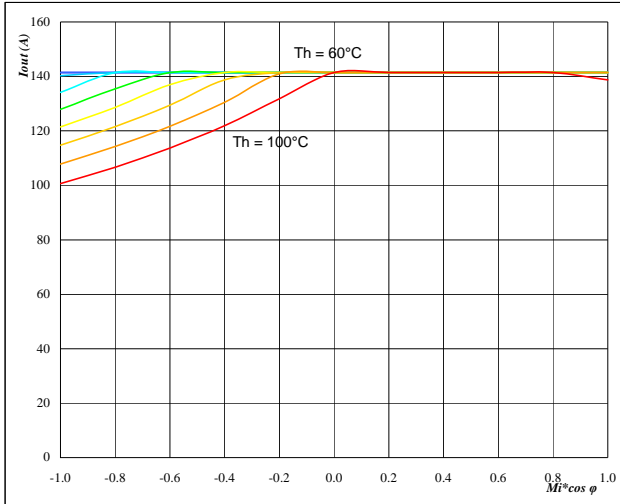
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 5**

Phase

**Typical available 50Hz output current  
as a function  $Mi \cdot \cos \varphi$** 

$$I_{out} = f(Mi \cdot \cos \varphi)$$


**At**

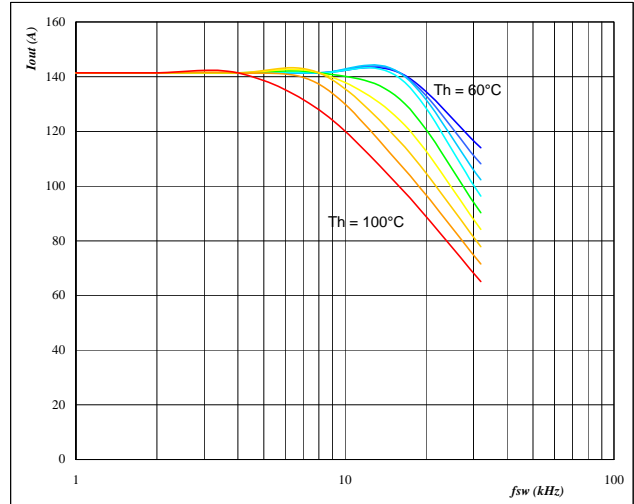
$T_j = 125$  °C  
 DC link = 600 V  
 $f_{sw} = 4$  kHz  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 6**

Phase

**Typical available 50Hz output current  
as a function of switching frequency**

$$I_{out} = f(f_{sw})$$


**At**

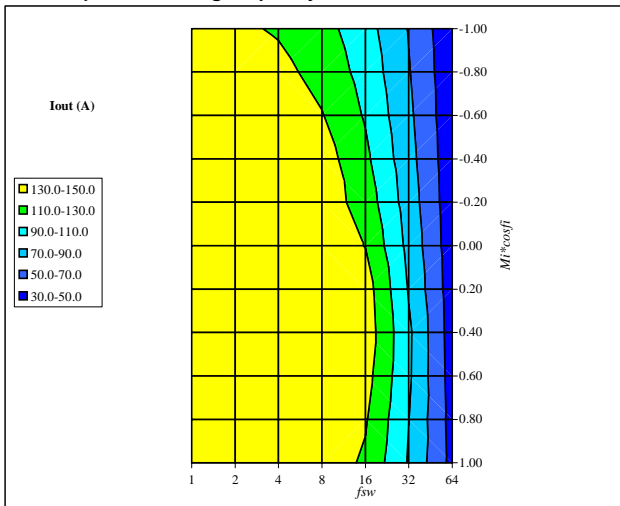
$T_j = 125$  °C  
 DC link = 600 V  
 $Mi \cdot \cos \varphi = 0.8$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 7**

Phase

**Typical available 50Hz output current as a function  
of  $Mi \cdot \cos \varphi$  and switching frequency**

$$I_{out} = f(f_{sw}, Mi \cdot \cos \varphi)$$


**At**

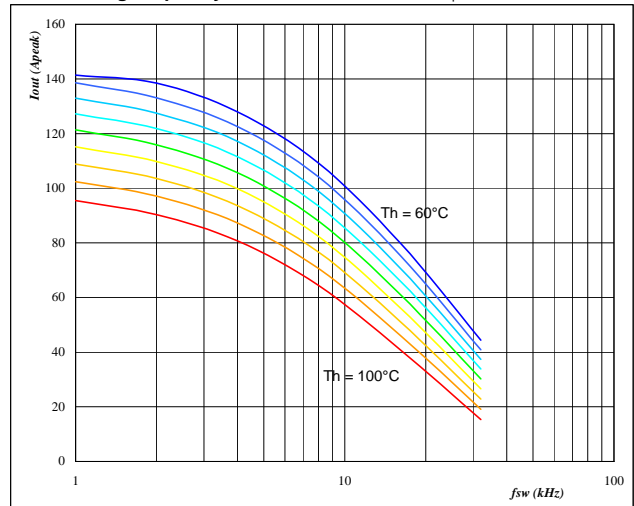
$T_j = 125$  °C  
 DC link = 600 V  
 $T_h = 80$  °C

**Figure 8**

Phase

**Typical available 0Hz output current as a function  
of switching frequency**

$$I_{outpeak} = f(f_{sw})$$


**At**

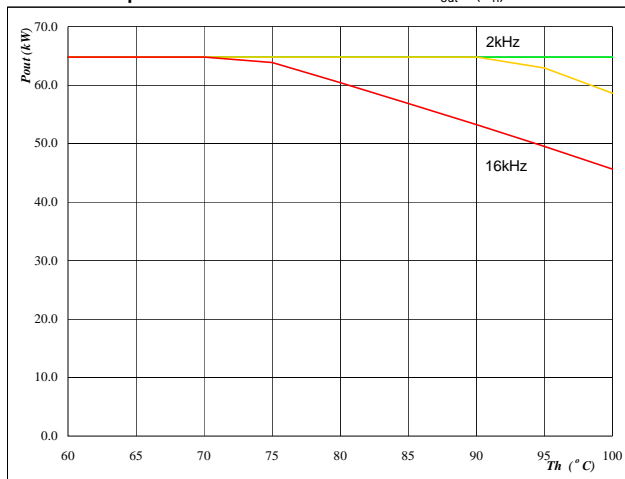
$T_j = 125$  °C  
 DC link = 600 V  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C  
 $Mi = 0$

**Figure 9**

Inverter

**Typical available peak output power as a function of heatsink temperature**

$$P_{out}=f(T_h)$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

DC link = 600 V

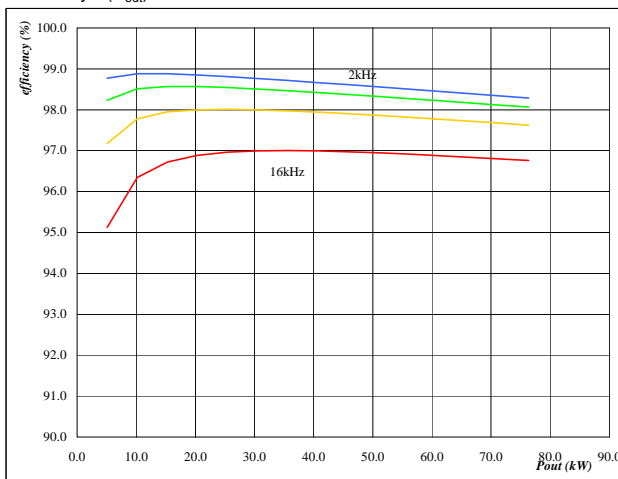
 $M_i = 1$ 
 $\cos \varphi = 0.80$ 
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 10**

Inverter

**Typical efficiency as a function of output power**

$$\text{efficiency}=f(P_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

DC link = 600 V

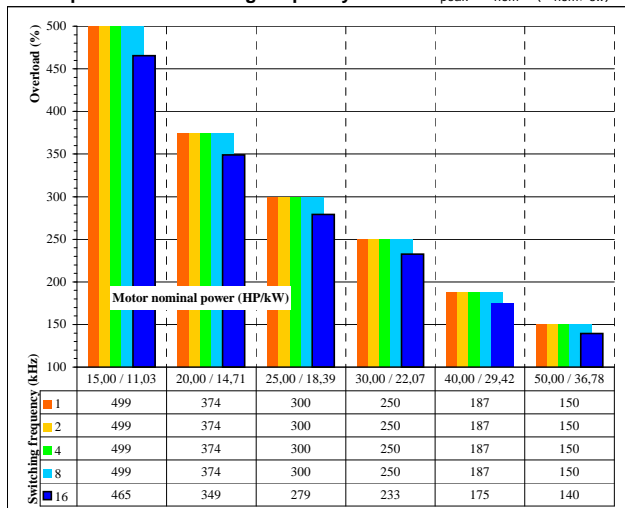
 $M_i = 1$ 
 $\cos \varphi = 0.80$ 
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 11**

Inverter

**Typical available overload factor as a function of motor power and switching frequency**

$$P_{peak} / P_{nom}=f(P_{nom},f_{sw})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

DC link = 600 V

 $M_i = 1$ 
 $\cos \varphi = 0.8$ 
 $f_{sw}$  from 1 kHz to 16kHz in steps of factor 2

 $T_h = 80 \text{ } ^\circ\text{C}$ 

Motor eff = 0.85

**General conditions**
**Half Bridge SPWM**

$$V_{GEon} = 15 \text{ V}$$

$$V_{GEoff} = -15 \text{ V}$$

$$R_{gon} = 4 \text{ } \Omega$$

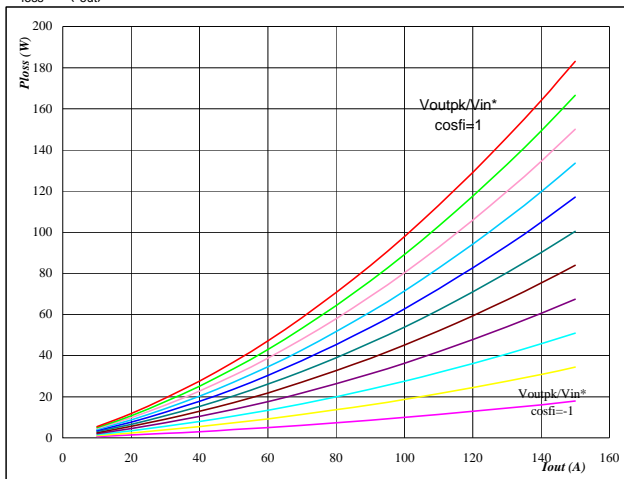
$$R_{goff} = 4 \text{ } \Omega$$

**Figure 1**

IGBT

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

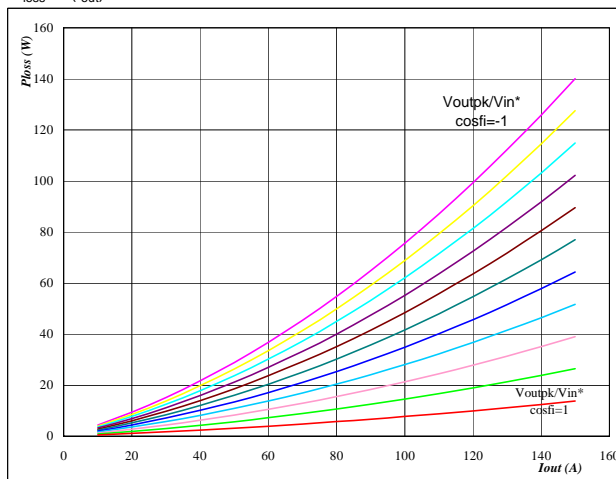
Mi\*cosfi from -1 to 1 in steps of 0,2

**Figure 2**

FRED

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

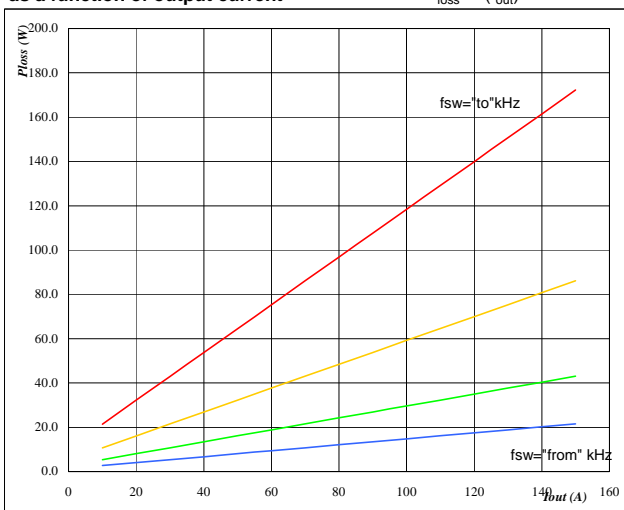
Mi\*cosfi from -1 to 1 in steps of 0,2

**Figure 3**

IGBT

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

DC link = 320 V

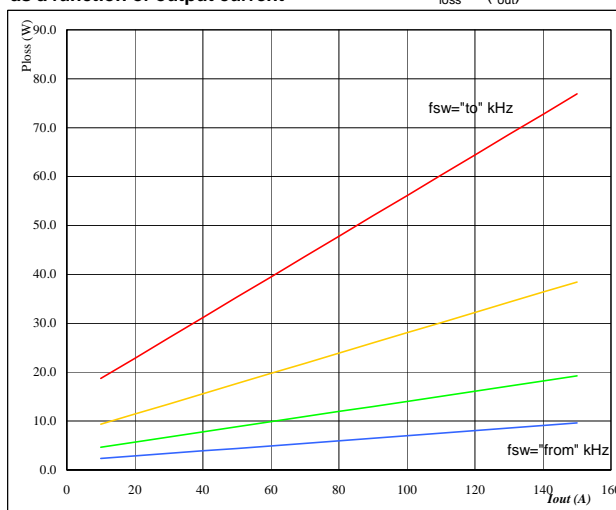
fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 4**

FRED

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

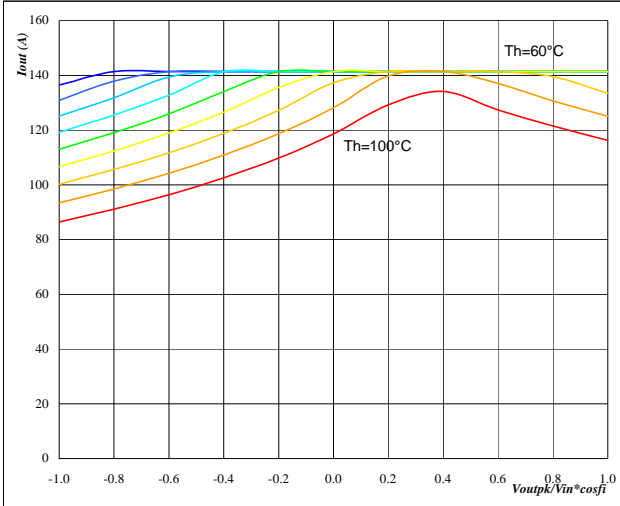
DC link = 320 V

fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 5** Phase

Typical available 50Hz output current  
as a function  $Mi \cdot \cos \phi_i$

$$I_{out} = f(Mi \cdot \cos \phi_i)$$

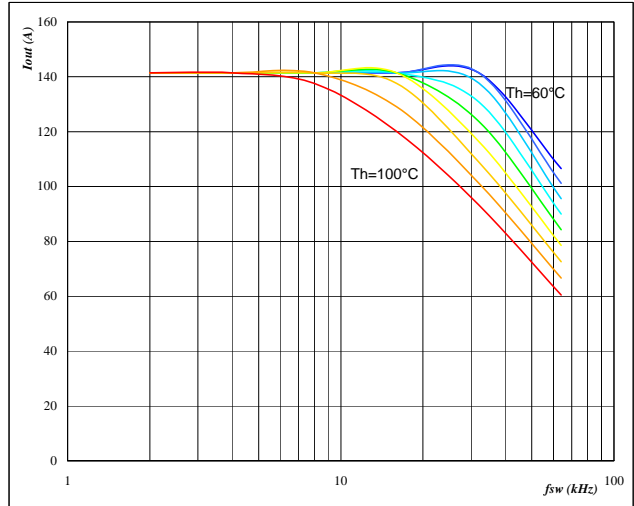


At  
 $T_j = 125$  °C  
DC link = 320 V  
 $f_{sw} = 18$  kHz  
Th from 60 °C to 100 °C in steps of 5 °C

**Figure 6** Phase

Typical available 50Hz output current  
as a function of switching frequency

$$I_{out} = f(f_{sw})$$

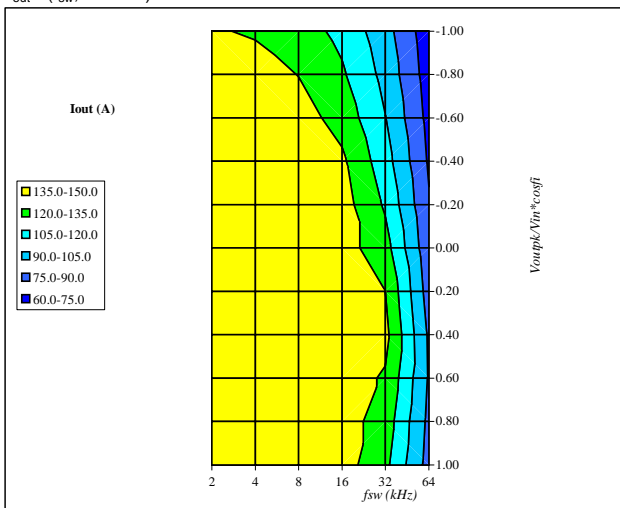


At  
 $T_j = 125$  °C  
DC link = 320 V  
 $Mi \cdot \cos \phi_i = 1$   
Th from 60 °C to 100 °C in steps of 5 °C

**Figure 7** Phase

Typical available 50Hz output current  
as a function of  $V_{outpk}/V_{in} \cdot \cos \phi_i$  and switching frequency

$$I_{out} = f(f_{sw}, Mi \cdot \cos \phi_i)$$

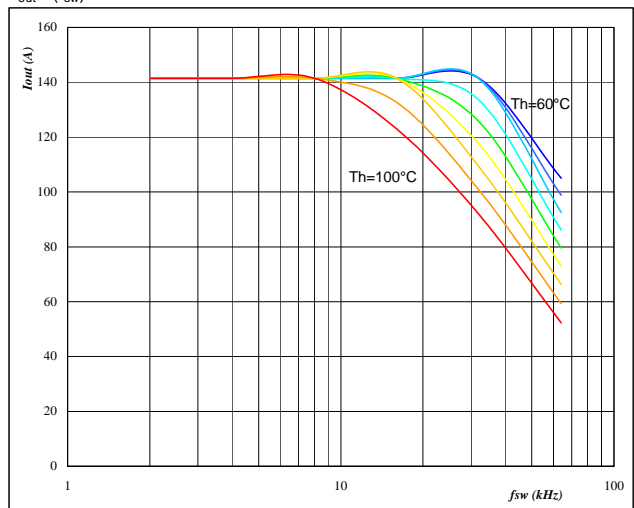


At  
 $T_j = 125$  °C  
DC link = 320 V  
 $T_h = 80$  °C

**Figure 8** Phase

Typical available 0Hz output current  
as a function of switching frequency

$$I_{out} = f(f_{sw})$$



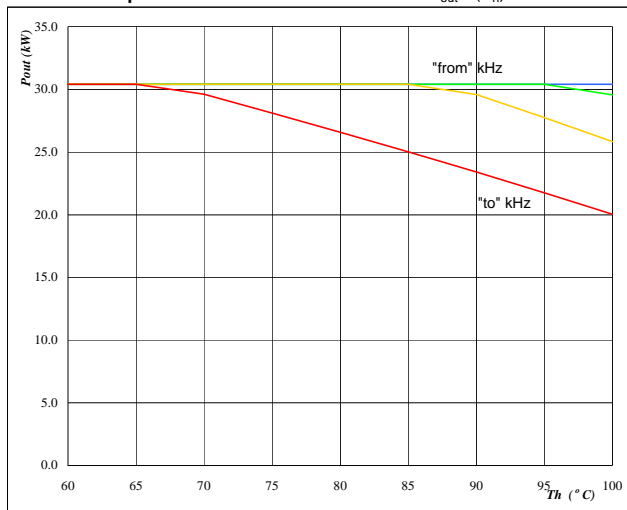
At  
 $T_j = 125$  °C  
DC link = 320 V  
 $Mi \cdot \cos \phi_i = 0$   
Th from 60 °C to 100 °C in steps of 5 °C

**Figure 9**

Inverter

**Typical available peak output power as a function of heatsink temperature**

$$P_{out} = f(T_h)$$


**At**

Tj = 125 °C

DC link = 320 V

Mi = 1

cosfi = 1

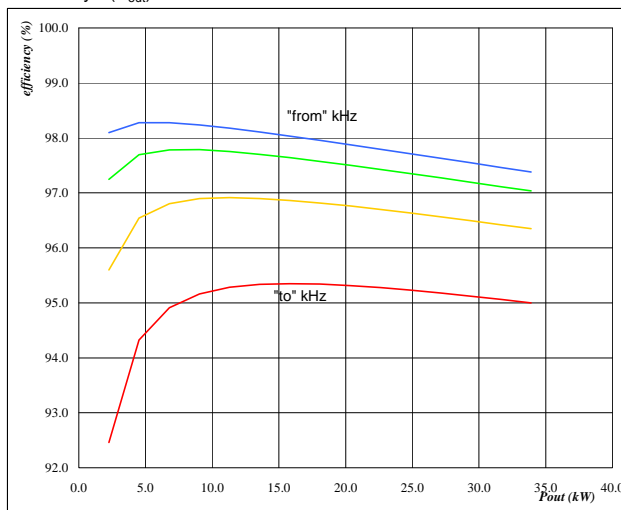
fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 10**

Inverter

**Typical efficiency as a function of output power**

$$\text{efficiency} = f(P_{out})$$


**At**

Tj = 125 °C

DC link = 320 V

Mi = 1

cosfi = 1

fsw from 4 kHz to 32 kHz in steps of factor 2

**General conditions**
**H Bridge SPWM**

$$V_{GEon} = 15 \text{ V}$$

$$V_{GEoff} = -15 \text{ V}$$

$$R_{gon} = 4 \text{ } \Omega$$

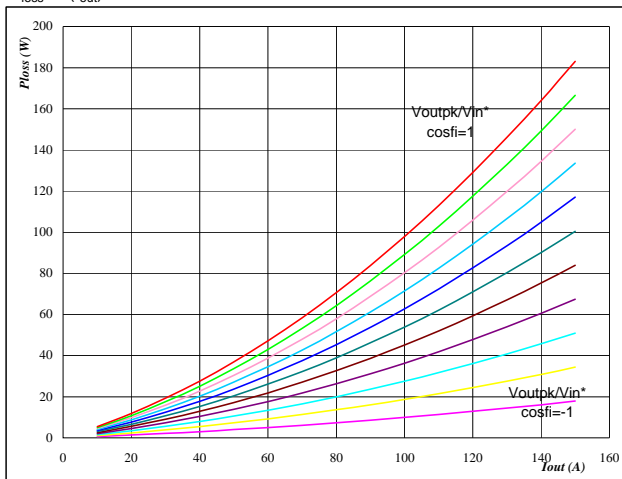
$$R_{goff} = 4 \text{ } \Omega$$

**Figure 1**

IGBT

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

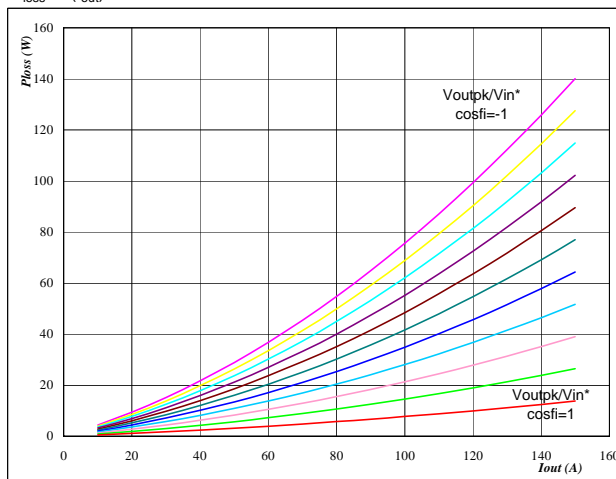
Mi\*cosfi from -1 to 1 in steps of 0,2

**Figure 2**

FRED

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

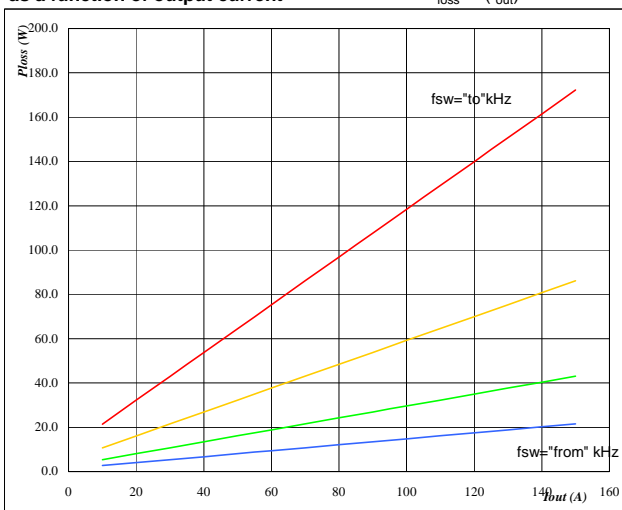
Mi\*cosfi from -1 to 1 in steps of 0,2

**Figure 3**

IGBT

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

DC link = 600 V

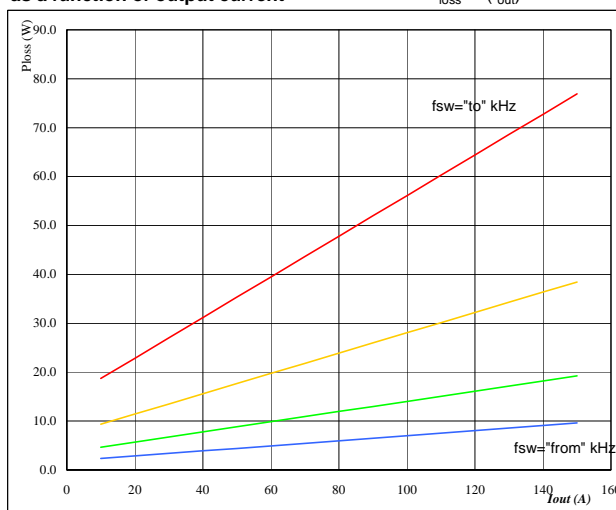
fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 4**

FRED

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$



At

$$T_j = 125 \text{ } ^\circ\text{C}$$

DC link = 600 V

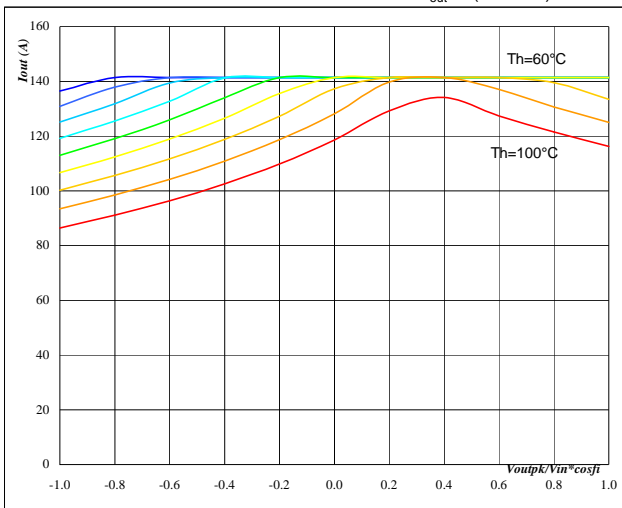
fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 5**

Phase

**Typical available 50Hz output current  
as a function  $M_i \cdot \cos \phi_i$** 

$$I_{out} = f(M_i \cdot \cos \phi_i)$$


**At**
 $T_j = 125$  °C

DC link = 600 V

fsw = 40 kHz

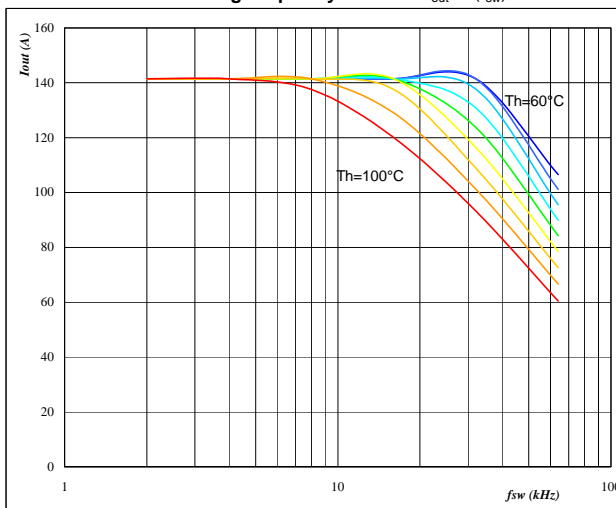
Th from 60 °C to 100 °C in steps of 5 °C

**Figure 6**

Phase

**Typical available 50Hz output current  
as a function of switching frequency**

$$I_{out} = f(f_{sw})$$


**At**
 $T_j = 125$  °C

DC link = 600 V

 $M_i \cdot \cos \phi_i = 1$ 

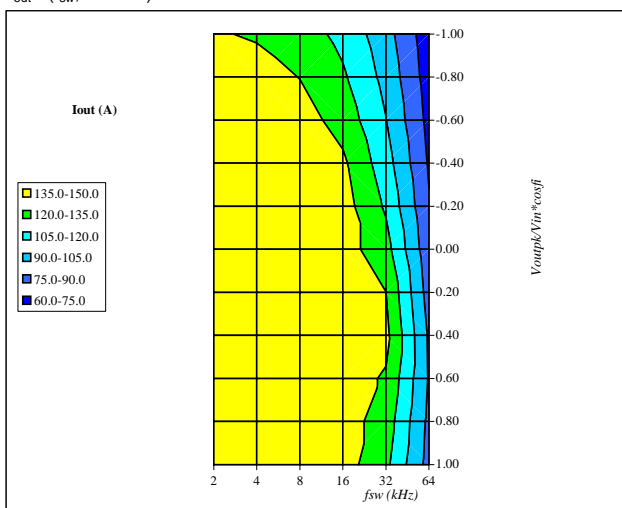
Th from 60 °C to 100 °C in steps of 5 °C

**Figure 7**

Phase

**Typical available 50Hz output current  
as a function of  $V_{outpk}/V_{in} \cdot \cos \phi_i$  and switching frequency**

$$I_{out} = f(f_{sw}, M_i \cdot \cos \phi_i)$$


**At**
 $T_j = 125$  °C

DC link = 600 V

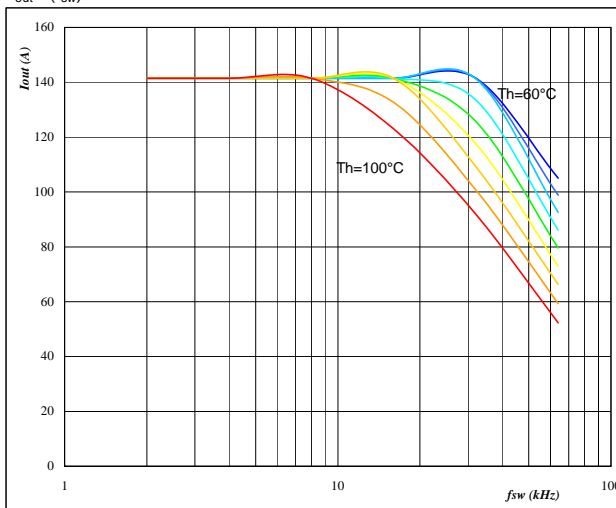
 $T_h = 80$  °C

**Figure 8**

Phase

**Typical available 0Hz output current  
as a function of switching frequency**

$$I_{out} = f(f_{sw})$$


**At**
 $T_j = 125$  °C

DC link = 600 V

 $M_i \cdot \cos \phi_i = 0$ 

Th from 60 °C to 100 °C in steps of 5 °C

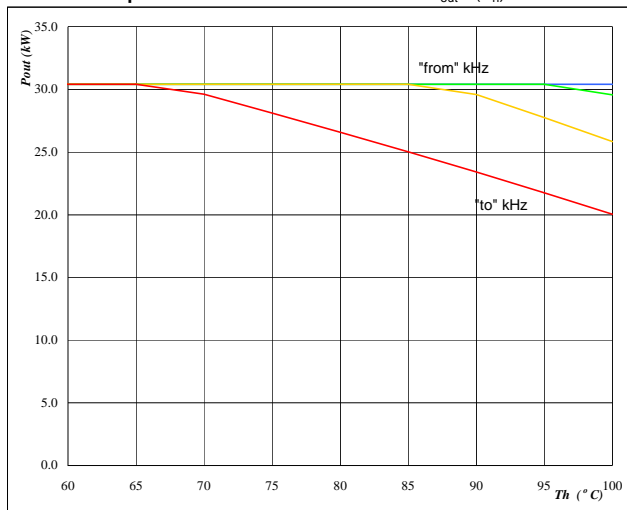


**Figure 9**

Inverter

**Typical available peak output power as a function of heatsink temperature**

$$P_{out}=f(T_h)$$


**At**

Tj = 125 °C

DC link = 600 V

Mi = 1

cosfi = 1

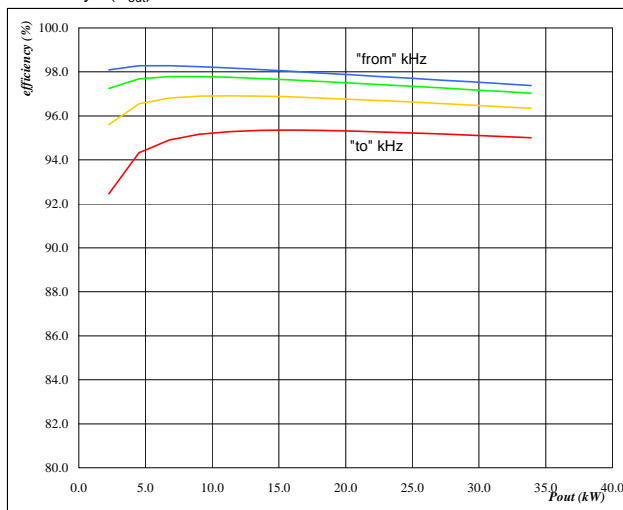
fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 10**

Inverter

**Typical efficiency as a function of output power**

$$\text{efficiency}=f(P_{out})$$


**At**

Tj = 125 °C

DC link = 600 V

Mi = 1

cosfi = 1

fsw from 4 kHz to 32 kHz in steps of factor 2

**PRODUCT STATUS DEFINITIONS**

| Datasheet Status | Product Status         | Definition   |
|------------------|------------------------|--|
| Target           | Formative or In Design | This datasheet contains the design specifications for product development. Specifications may change in any manner without notice. The data contained is exclusively intended for technically trained staff.   |
| Preliminary      | First Production       | This datasheet contains preliminary data, and supplementary data may be published at a later date. Vincotech reserves the right to make changes at any time without notice in order to improve design. The data contained is exclusively intended for technically trained staff. |
| Final            | Full Production        | This datasheet contains final specifications. Vincotech reserves the right to make changes at any time without notice in order to improve design. The data contained is exclusively intended for technically trained staff.  |

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2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.