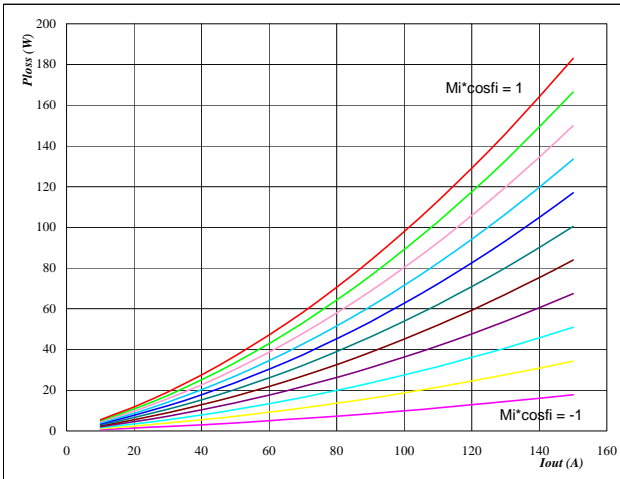


**General conditions**
**3phase SPWM**

$V_{GEon}$	=	15 V
$V_{GEoff}$	=	-15 V
$R_{gon}$	=	4 $\Omega$
$R_{goff}$	=	4 $\Omega$

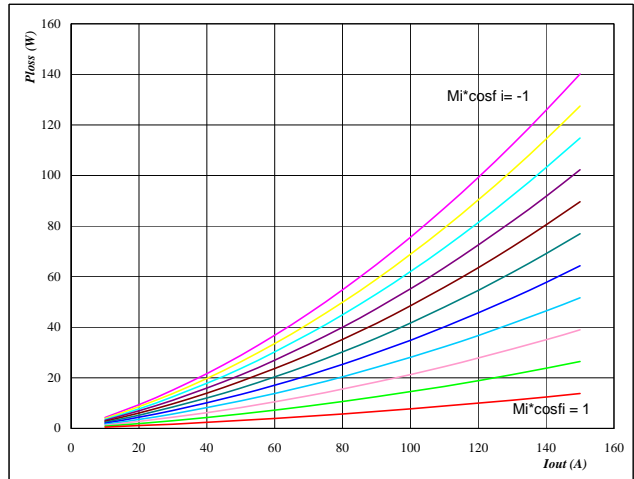
**Figure 1**
**IGBT**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 
 $M_i \cdot \cos\phi$  from -1 to 1 in steps of 0,2

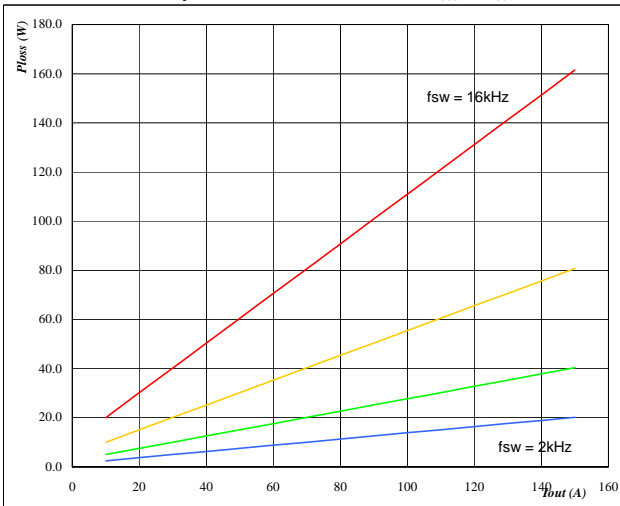
**Figure 2**
**FRED**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 
 $M_i \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 3**
**IGBT**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$

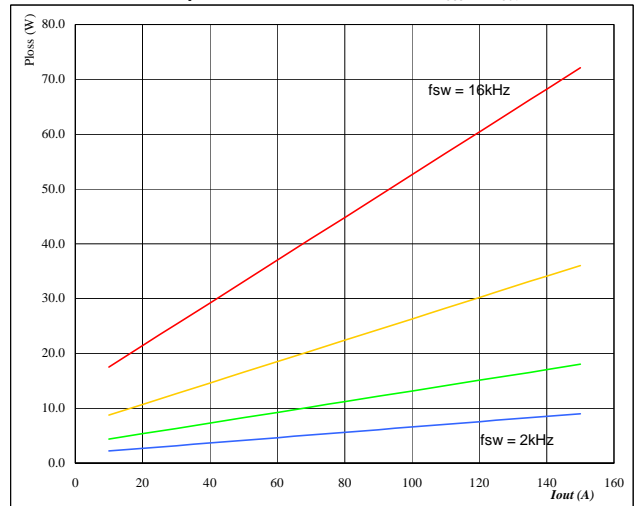

**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

DC link = 600 V

 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 4**
**FRED**
**Typical average switching loss as a function of output current**

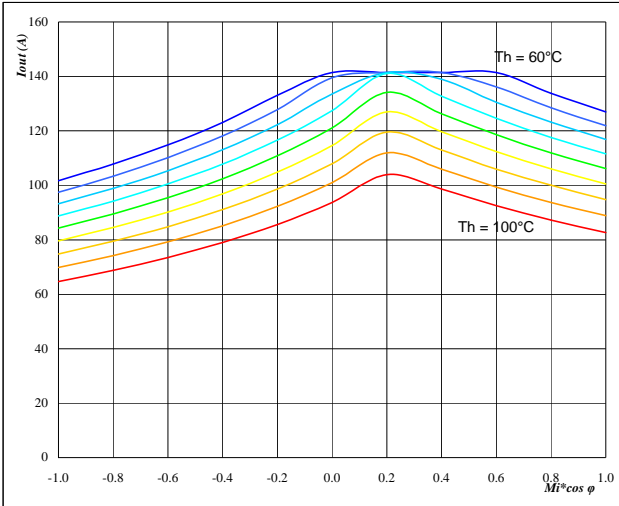
$$P_{loss} = f(I_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

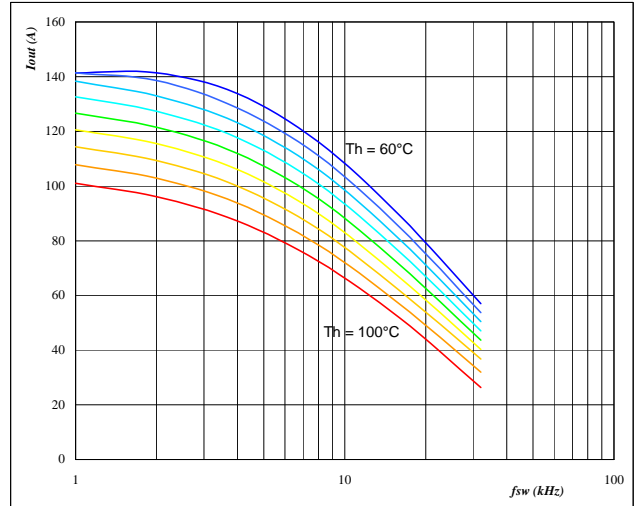
DC link = 600 V

 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

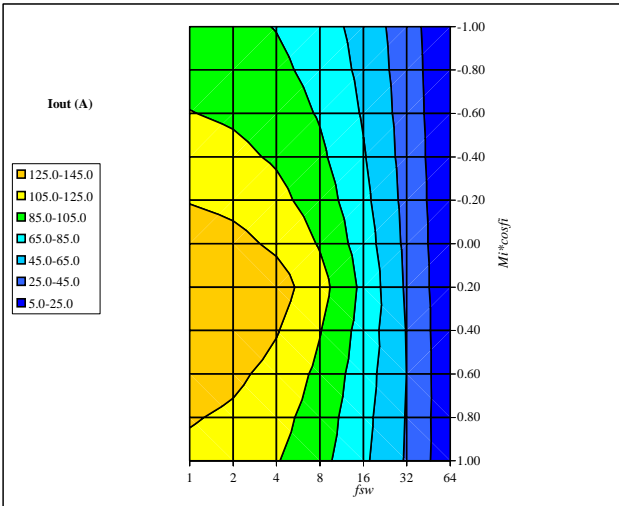
**Figure 5** Phase

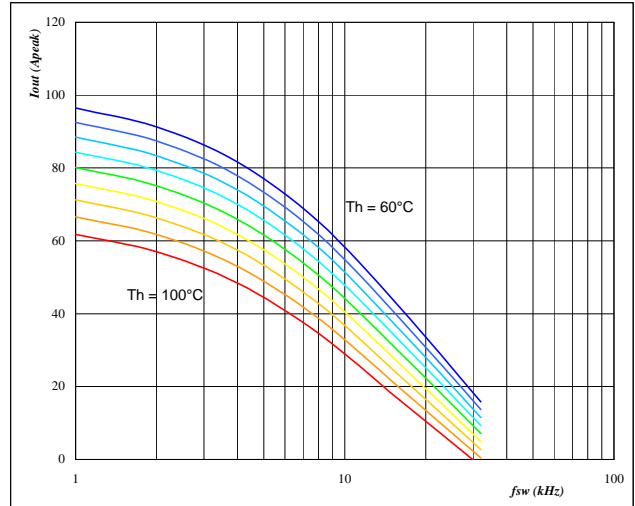
**Typical available 50Hz output current as a function  $Mi \cdot \cos \phi$**   
 $I_{out} = f(Mi \cdot \cos \phi)$ 

**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $f_{sw} = 4 \text{ kHz}$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 6** Phase

**Typical available 50Hz output current as a function of switching frequency**  
 $I_{out} = f(f_{sw})$ 

**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $Mi \cdot \cos \phi = 0.8$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 7** Phase

**Typical available 50Hz output current as a function of  $Mi \cdot \cos \phi$  and switching frequency**  
 $I_{out} = f(f_{sw}, Mi \cdot \cos \phi)$ 

**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h = 80 \text{ } ^\circ\text{C}$ 
**Figure 8** Phase

**Typical available 0Hz output current as a function of switching frequency**  
 $I_{outpeak} = f(f_{sw})$ 

**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C  
 $Mi = 0$

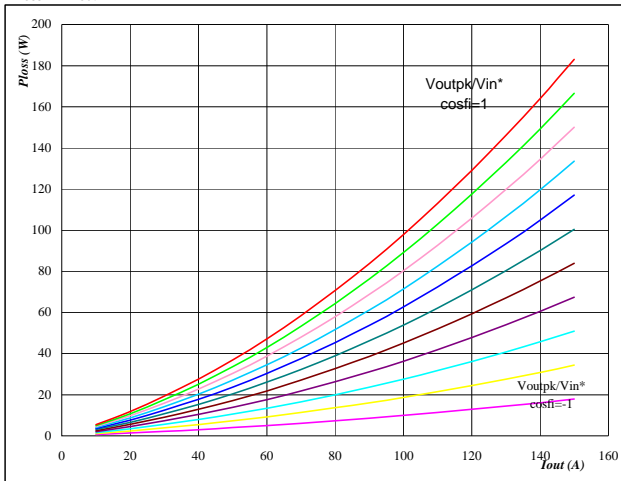


**General conditions**

<b>Half Bridge SPWM</b>	
$V_{GEon}$	= 15 V
$V_{GEoff}$	= -15 V
$R_{gon}$	= 4 $\Omega$
$R_{goff}$	= 4 $\Omega$

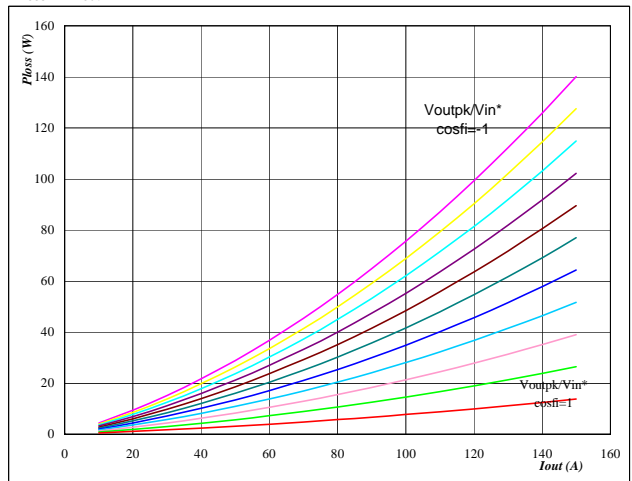
**Figure 1**
**IGBT**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 
 $M_i \cdot \cos\phi_i$  from -1 to 1 in steps of 0,2

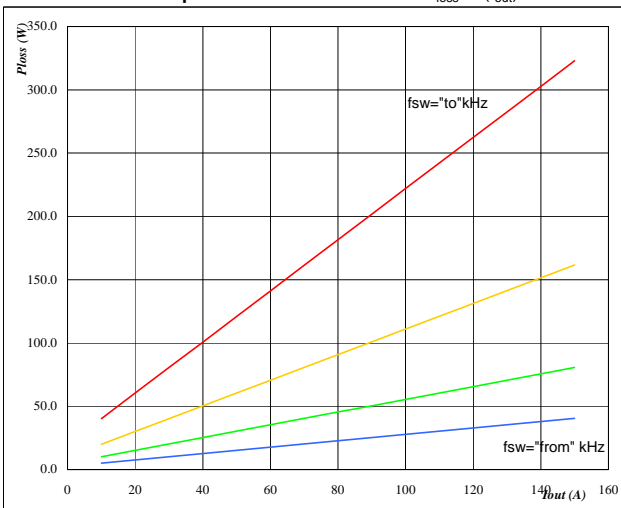
**Figure 2**
**FRED**
**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 
 $M_i \cdot \cos\phi_i$  from -1 to 1 in steps of 0,2

**Figure 3**
**IGBT**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$

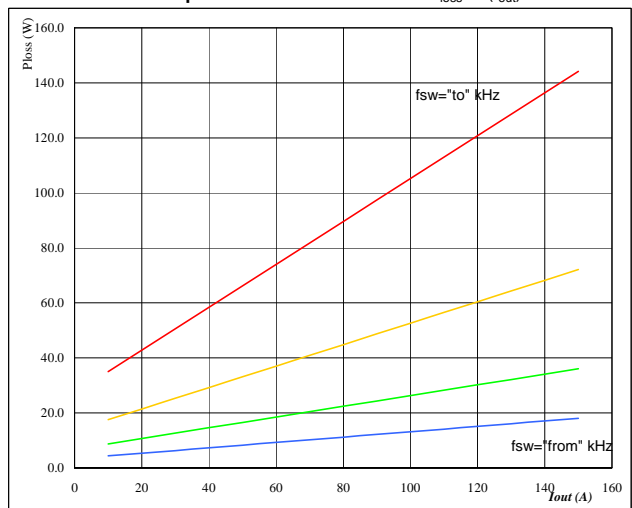

**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

DC link = 600 V

fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 4**
**FRED**
**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$


**At**
 $T_j = 125 \text{ } ^\circ\text{C}$ 

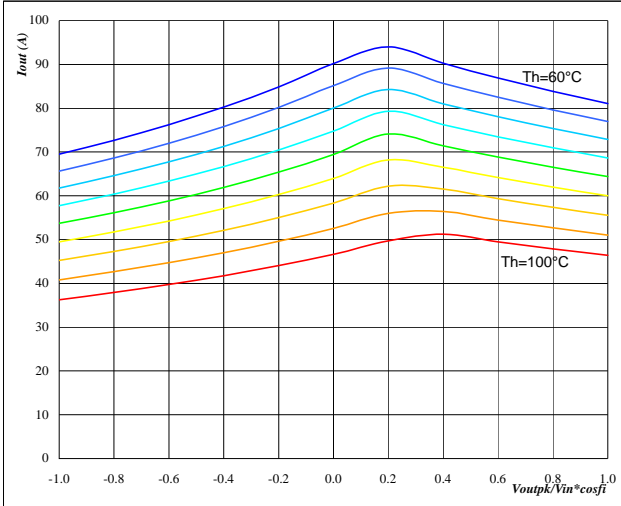
DC link = 600 V

fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 5** Phase

**Typical available 50Hz output current as a function  $Mi \cdot \cos\phi_i$** 

$$I_{out} = f(Mi \cdot \cos\phi_i)$$

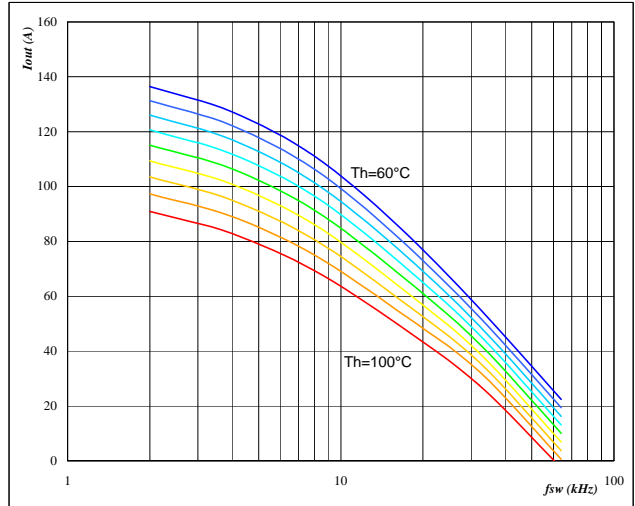


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $f_{sw} = 18 \text{ kHz}$   
 Th from 60 °C to 100 °C in steps of 5 °C

**Figure 6** Phase

**Typical available 50Hz output current as a function of switching frequency**

$$I_{out} = f(f_{sw})$$

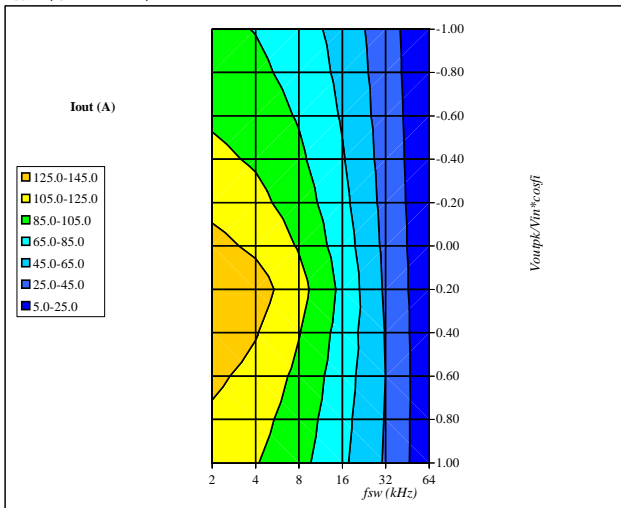


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $Mi \cdot \cos\phi_i = 1$   
 Th from 60 °C to 100 °C in steps of 5 °C

**Figure 7** Phase

**Typical available 50Hz output current as a function of  $V_{outpk}/V_{in} \cdot \cos\phi_i$  and switching frequency**

$$I_{out} = f(f_{sw}, Mi \cdot \cos\phi_i)$$

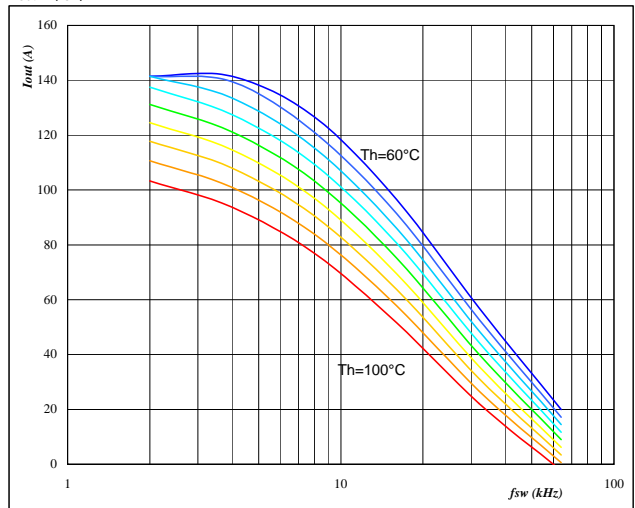


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h = 80 \text{ } ^\circ\text{C}$

**Figure 8** Phase

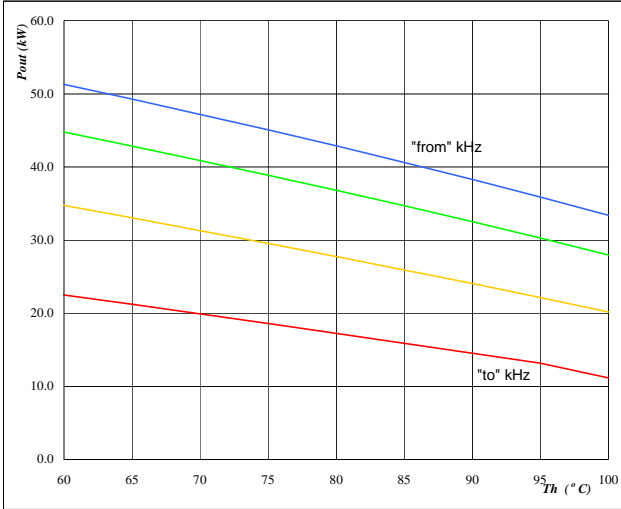
**Typical available 0Hz output current as a function of switching frequency**

$$I_{out} = f(f_{sw})$$



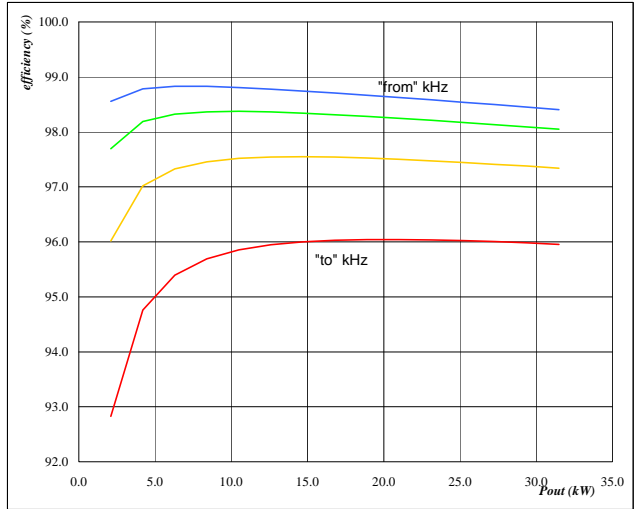
**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $Mi \cdot \cos\phi_i = 0$   
 Th from 60 °C to 100 °C in steps of 5 °C

**Figure 9** Inverter

**Typical available peak output power as a function of heatsink temperature**  
 $P_{out}=f(T_h)$ 


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos\phi_i = 1$   
 fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 10** Inverter

**Typical efficiency as a function of output power**  
 efficiency=f( $P_{out}$ )


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos\phi_i = 1$   
 fsw from 4 kHz to 32 kHz in steps of factor 2

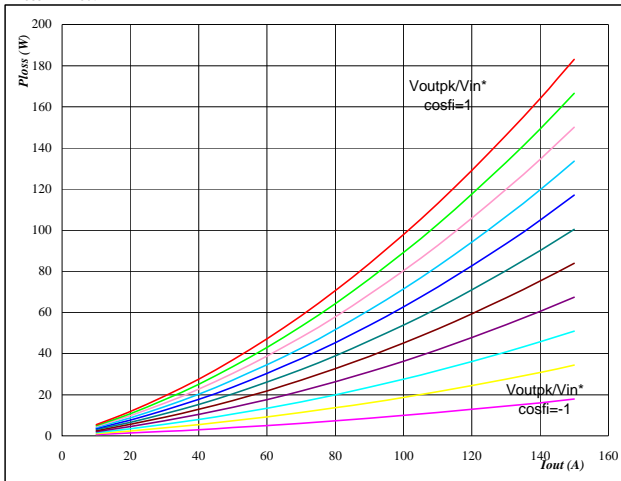
**General conditions**
**H Bridge SPWM**

$V_{GEon}$	=	15 V
$V_{GEoff}$	=	-15 V
$R_{gon}$	=	4 $\Omega$
$R_{goff}$	=	4 $\Omega$

**Figure 1** IGBT

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

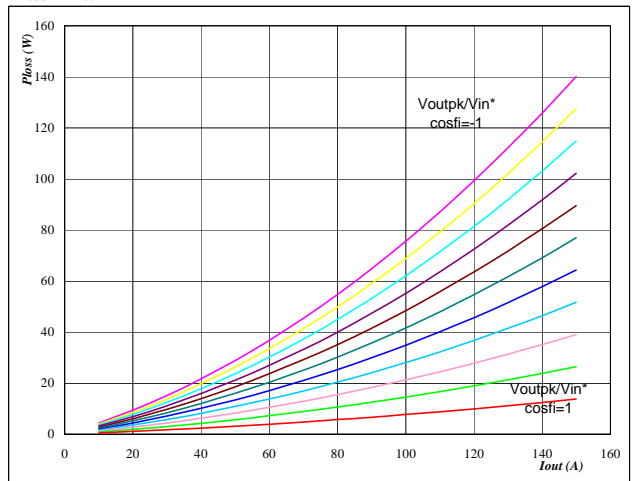


At  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 Mi\*cosfi from -1 to 1 in steps of 0,2

**Figure 2** FRED

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

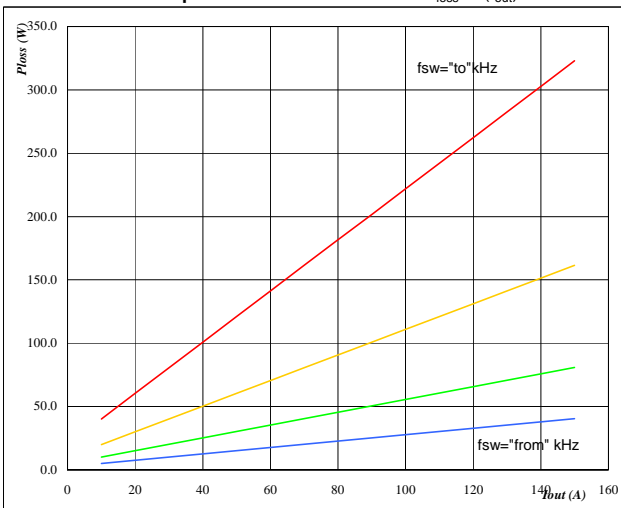


At  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 Mi\*cosfi from -1 to 1 in steps of 0,2

**Figure 3** IGBT

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$

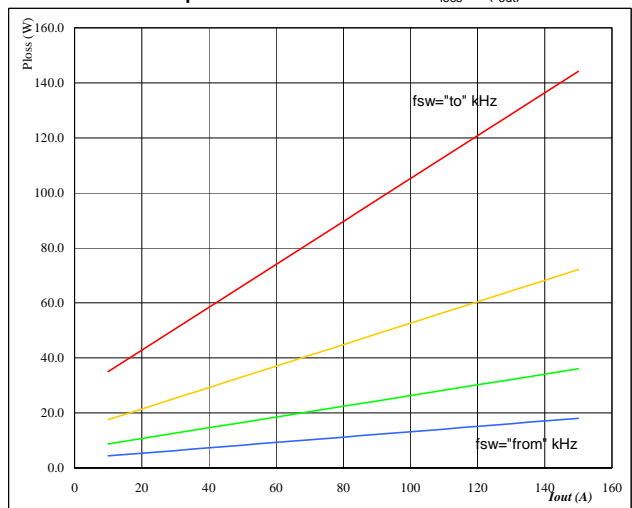


At  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 fsw from 4 kHz to 32 kHz in steps of factor 2

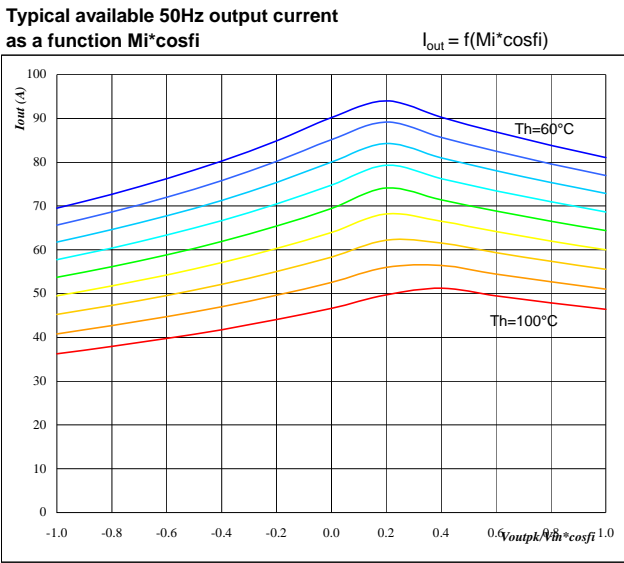
**Figure 4** FRED

**Typical average switching loss as a function of output current**

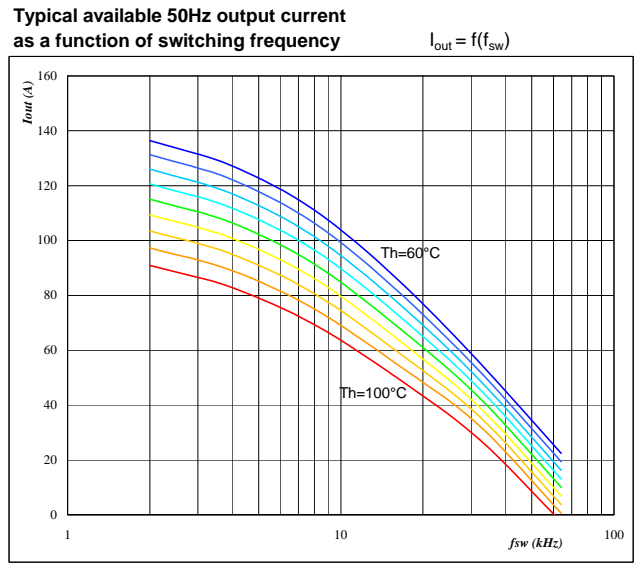
$$P_{loss} = f(I_{out})$$



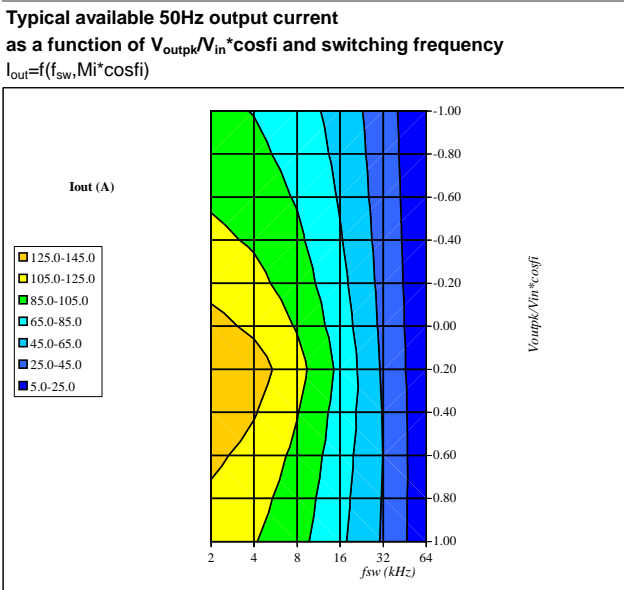
At  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 5** Phase


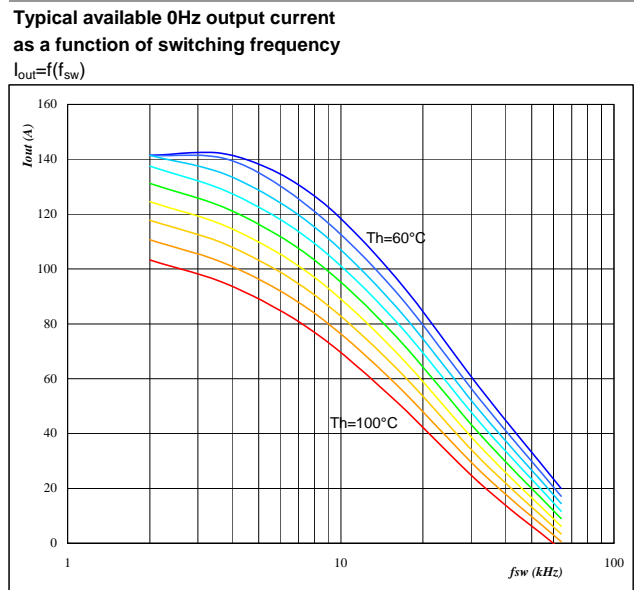
**At**  
 $T_j = 125 \text{ } ^\circ C$   
 DC link = 600 V  
 $f_{sw} = 40 \text{ kHz}$   
 Th from 60 °C to 100 °C in steps of 5 °C

**Figure 6** Phase


**At**  
 $T_j = 125 \text{ } ^\circ C$   
 DC link = 600 V  
 $Mi \cdot \cos\phi_i = 1$   
 Th from 60 °C to 100 °C in steps of 5 °C

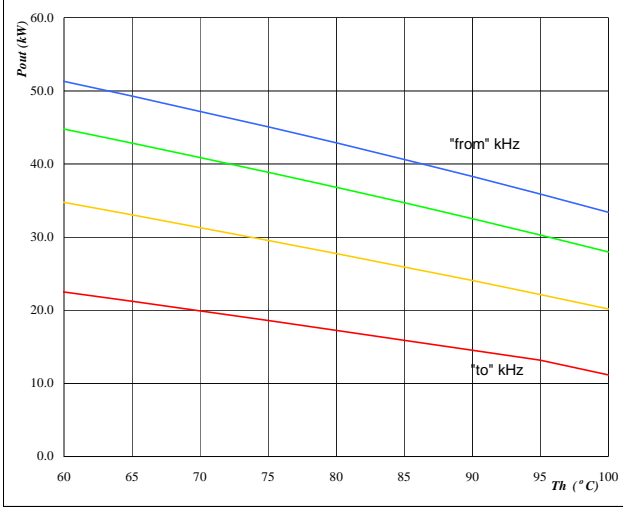
**Figure 7** Phase


**At**  
 $T_j = 125 \text{ } ^\circ C$   
 DC link = 600 V  
 $T_h = 80 \text{ } ^\circ C$

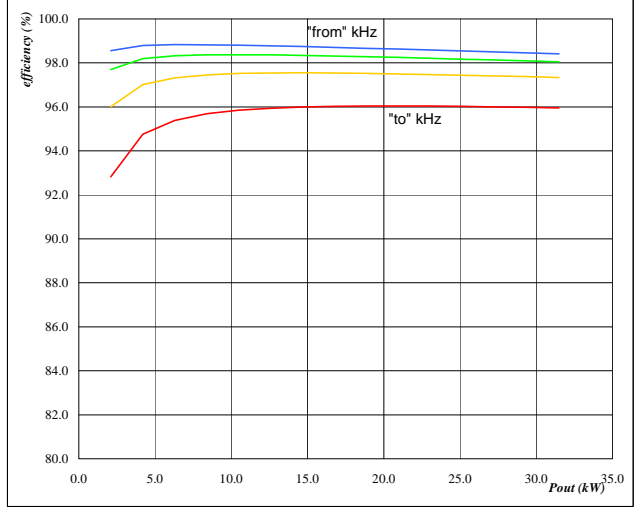
**Figure 8** Phase


**At**  
 $T_j = 125 \text{ } ^\circ C$   
 DC link = 600 V  
 $Mi \cdot \cos\phi_i = 0$   
 Th from 60 °C to 100 °C in steps of 5 °C



**Figure 9** Inverter
**Typical available peak output power as a function of heatsink temperature**  
 $P_{out}=f(T_h)$ 


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos\phi_i = 1$   
 fsw from 4 kHz to 32 kHz in steps of factor 2

**Figure 10** Inverter
**Typical efficiency as a function of output power**  
 $\text{efficiency}=f(P_{out})$ 


**At**  
 $T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos\phi_i = 1$   
 fsw from 4 kHz to 32 kHz in steps of factor 2

**PRODUCT STATUS DEFINITIONS**

Datasheet Status	Product Status	Definition
Target	Formative or In Design	This datasheet contains the design specifications for product development. Specifications may change in any manner without notice. The data contained is exclusively intended for technically trained staff.
Preliminary	First Production	This datasheet contains preliminary data, and supplementary data may be published at a later date. Vincotech reserves the right to make changes at any time without notice in order to improve design. The data contained is exclusively intended for technically trained staff.
Final	Full Production	This datasheet contains final specifications. Vincotech reserves the right to make changes at any time without notice in order to improve design. The data contained is exclusively intended for technically trained staff.

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2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.