

General conditions

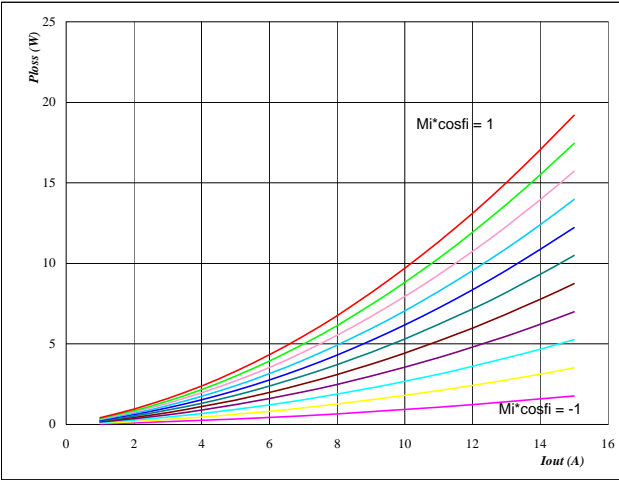
3phase SPWM

$V_{GEon} = 15\text{ V}$   
 $V_{GEoff} = -15\text{ V}$   
 $R_{gon} = 64\ \Omega$   
 $R_{goff} = 64\ \Omega$

Figure 1 IGBT

Typical average static loss as a function of output current

$P_{loss} = f(I_{out})$

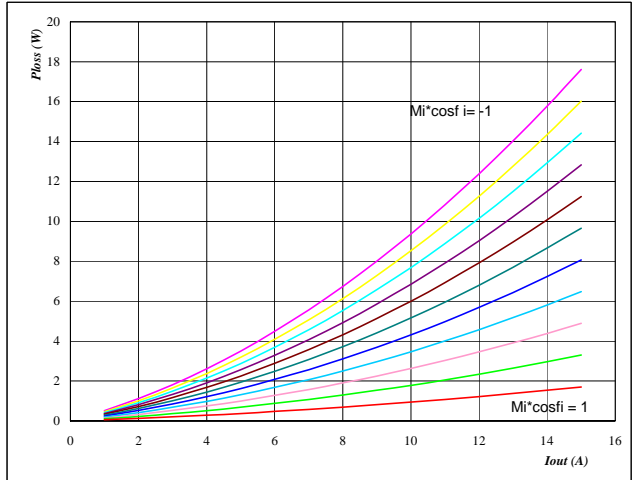


$T_j = 125\ \text{°C}$   
 $M_i \cdot \cos\phi$  from -1 to 1 in steps of 0,2

Figure 2 FWD

Typical average static loss as a function of output current

$P_{loss} = f(I_{out})$

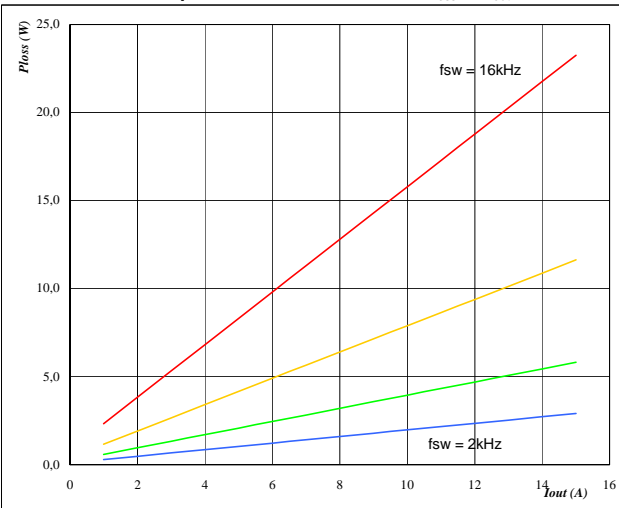


$T_j = 125\ \text{°C}$   
 $M_i \cdot \cos\phi$  from -1 to 1 in steps of 0,2

Figure 3 IGBT

Typical average switching loss as a function of output current

$P_{loss} = f(I_{out})$

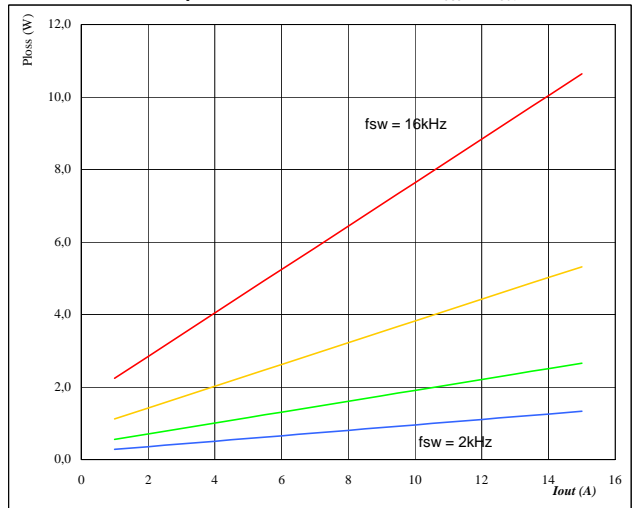


$T_j = 125\ \text{°C}$   
 DC link = 600 V  
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

Figure 4 FWD

Typical average switching loss as a function of output current

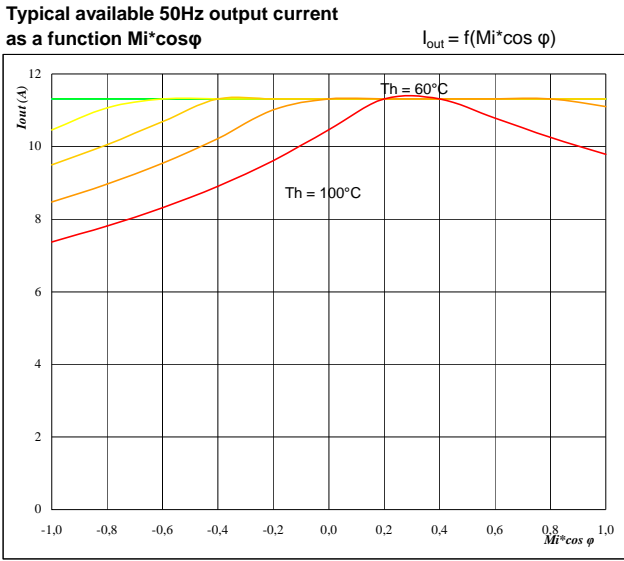
$P_{loss} = f(I_{out})$



$T_j = 125\ \text{°C}$   
 DC link = 600 V  
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

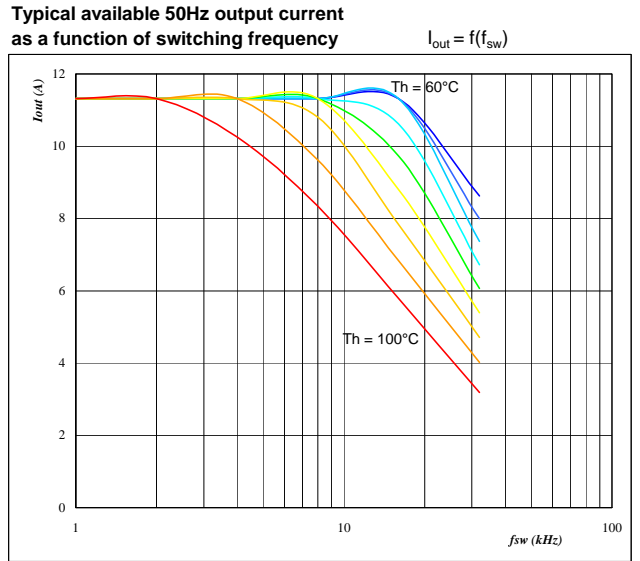
MiniSkiip 0 Output Inverter Application 1200V/8A

Figure 5 Phase



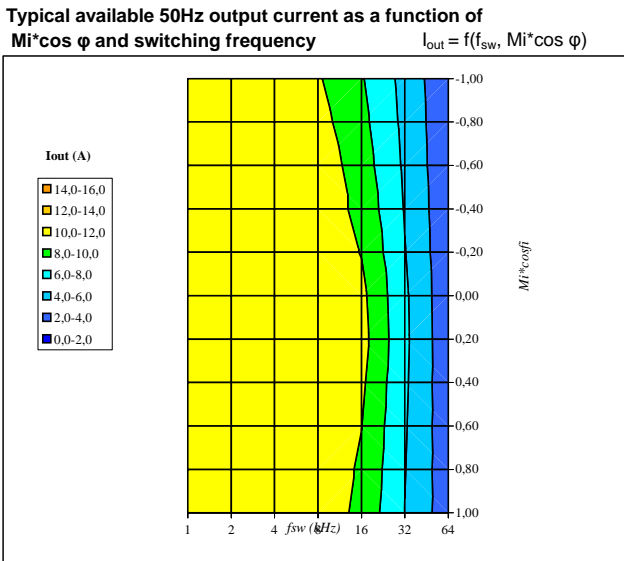
$T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $f_{sw} = 4 \text{ kHz}$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

Figure 6 Phase



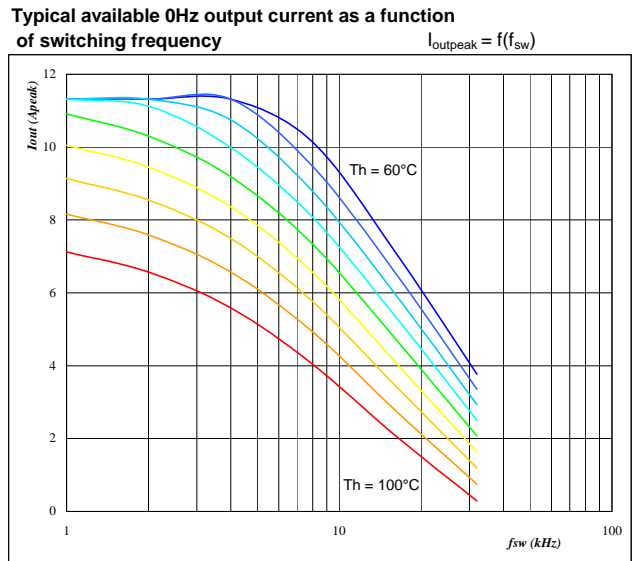
$T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $Mi \cdot \cos \phi = 0,8$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

Figure 7 Phase



$T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h = 80 \text{ } ^\circ\text{C}$

Figure 8 Phase

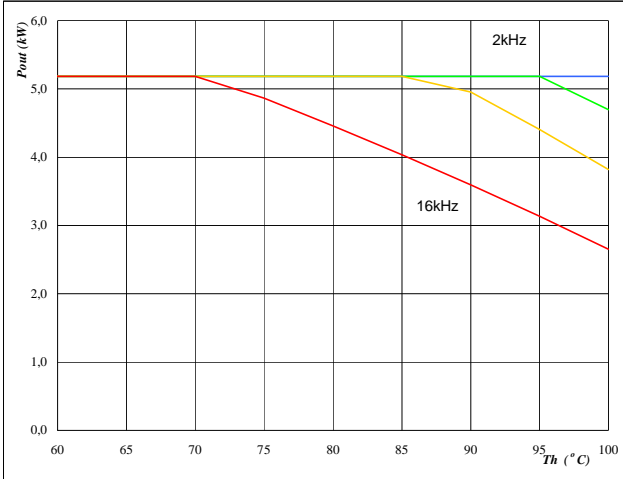


$T_j = 125 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C  
 $Mi = 0$

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Figure 9 Inverter

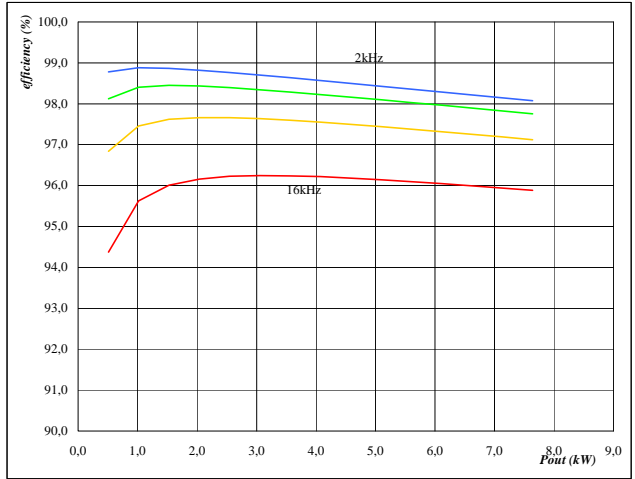
Typical available peak output power as a function of heatsink temperature  $P_{out}=f(T_h)$



$T_j = 125 \text{ } ^\circ\text{C}$   
DC link = 600 V  
Mi = 1  
cos  $\varphi = 0,80$   
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

Figure 10 Inverter

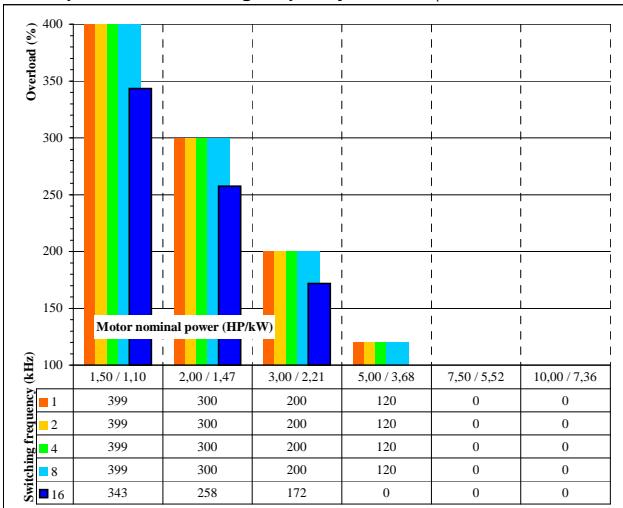
Typical efficiency as a function of output power  $\text{efficiency}=f(P_{out})$



$T_j = 125 \text{ } ^\circ\text{C}$   
DC link = 600 V  
Mi = 1  
cos  $\varphi = 0,80$   
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

Figure 11 Inverter

Typical available overload factor as a function of motor power and switching frequency  $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$



$T_j = 125 \text{ } ^\circ\text{C}$   
DC link = 600 V  
Mi = 1  
cos  $\varphi = 0,8$   
 $f_{sw}$  from 1 kHz to 16kHz in steps of factor 2  
 $T_h = 80 \text{ } ^\circ\text{C}$   
Motor eff = 0,85