

Vincotech
flow PACK 2

Output Inverter Application

1200 V / 150 A
General conditions
3phase SPWM

$$V_{\text{GOn}} = 15 \text{ V}$$

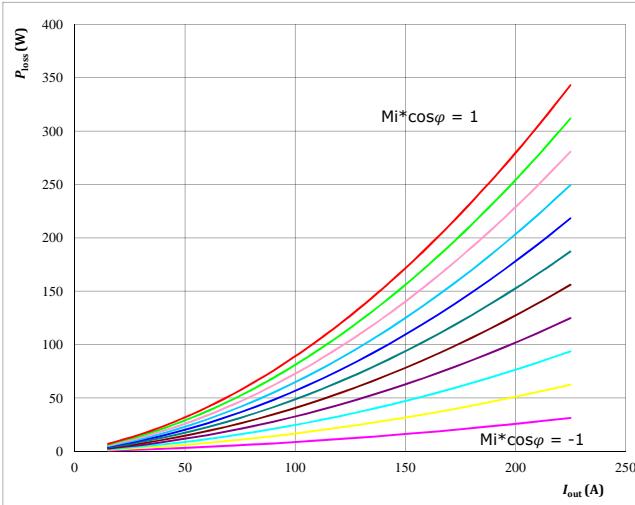
$$V_{\text{GOff}} = -15 \text{ V}$$

$$R_{\text{gon}} = 2 \Omega$$

$$R_{\text{goff}} = 2 \Omega$$

figure 1.
IGBT
Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

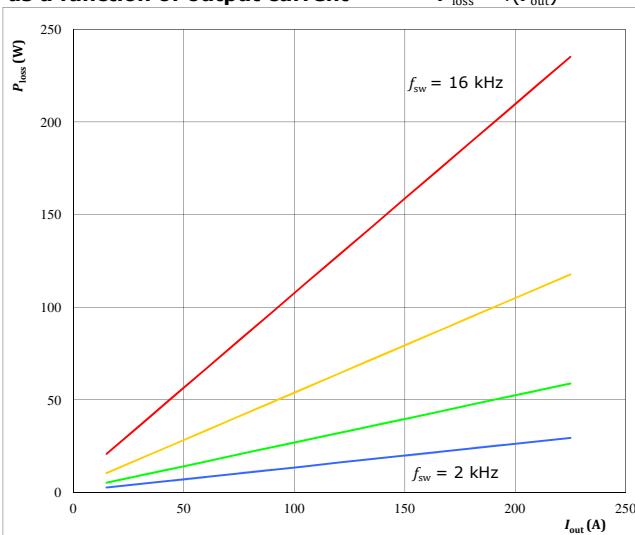

At

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $Mi \cdot \cos\varphi$ from -1 to 1 in steps of 0,2

figure 3.
IGBT
Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$


At

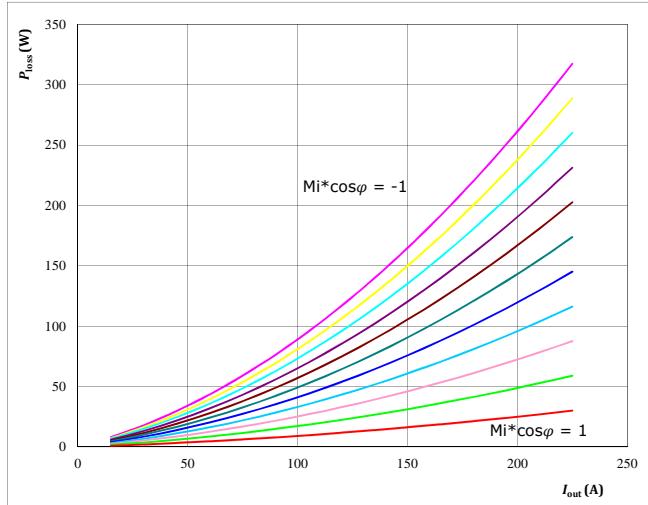
$$T_j = 125 \text{ } ^\circ\text{C}$$

$$\text{DC-link} = 600 \text{ V}$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

figure 2.
FWD
Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

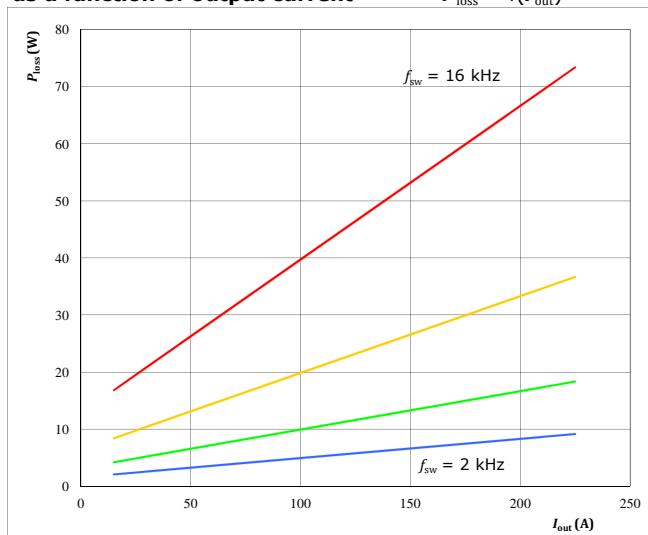

At

$$T_j = 125 \text{ } ^\circ\text{C}$$

 $Mi \cdot \cos\varphi$ from -1 to 1 in steps of 0,2

figure 4.
FWD
Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$


At

$$T_j = 125 \text{ } ^\circ\text{C}$$

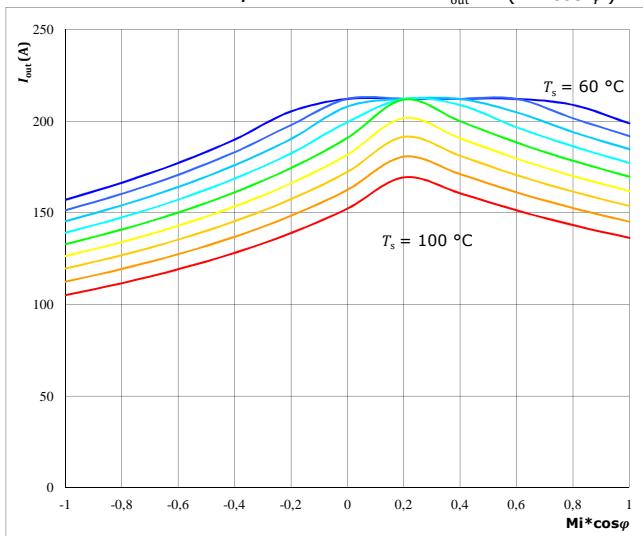
$$\text{DC-link} = 600 \text{ V}$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

figure 5.**Phase**

**Typical available 50 Hz output current
as a function $M_i \cos \varphi$**

$$I_{\text{out}} = f(M_i \cos \varphi)$$

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

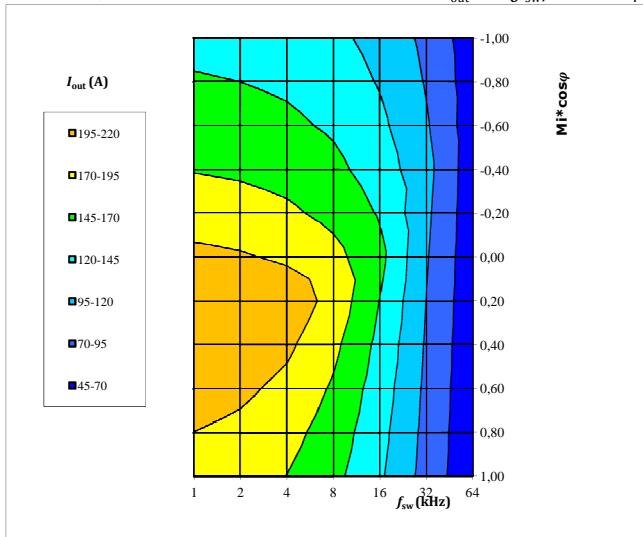
$$\text{DC-link} = 600 \text{ } \text{V}$$

$$f_{\text{sw}} = 4 \text{ } \text{kHz}$$

T_s from 60 °C to 100 °C in steps of 5 °C

figure 7.**Phase**

**Typical available 50 Hz output current as a function of
 $M_i \cos \varphi$ and switching frequency** $I_{\text{out}} = f(f_{\text{sw}}, M_i \cos \varphi)$

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

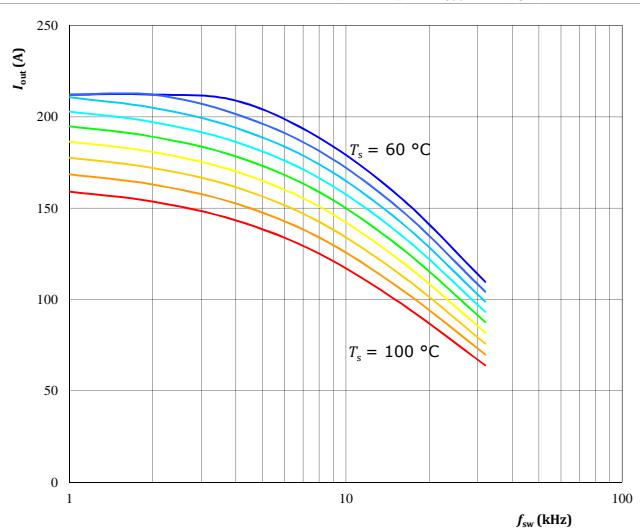
$$\text{DC-link} = 600 \text{ } \text{V}$$

$$T_s = 80 \text{ } ^\circ\text{C}$$

figure 6.**Phase**

Typical available 50 Hz output current

as a function of switching frequency $I_{\text{out}} = f(f_{\text{sw}})$

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

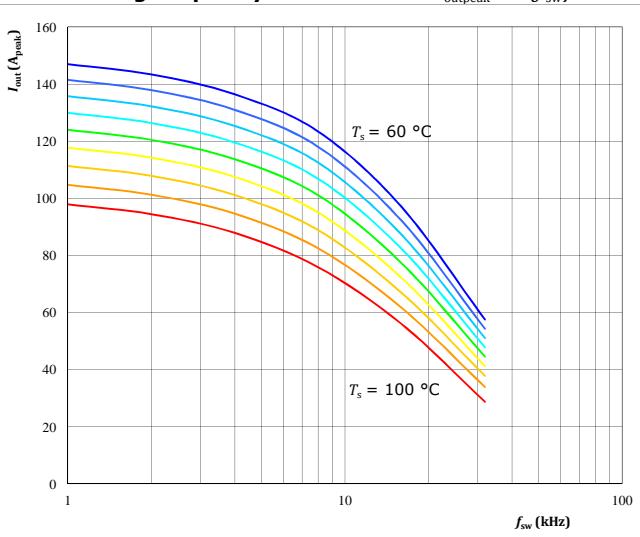
$$\text{DC-link} = 600 \text{ } \text{V}$$

$$M_i \cos \varphi = 0,8$$

T_s from 60 °C to 100 °C in steps of 5 °C

figure 8.**Phase**

**Typical available 50 Hz output current as a function
of switching frequency** $I_{\text{outpeak}} = f(f_{\text{sw}})$

**At**

$$T_j = 125 \text{ } ^\circ\text{C}$$

$$\text{DC-link} = 600 \text{ } \text{V}$$

$$M_i = 0$$

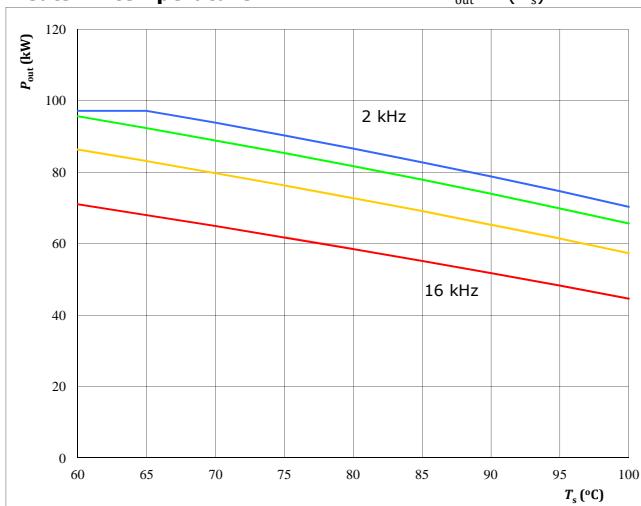
T_s from 60 °C to 100 °C in steps of 5 °C

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figure 9.
Inverter
Typical available peak output power as a function of heatsink temperature

$$P_{\text{out}} = f(T_s)$$


At

$$T_j = 125 \quad ^\circ\text{C}$$

$$\text{DC-link} = 600 \quad \text{V}$$

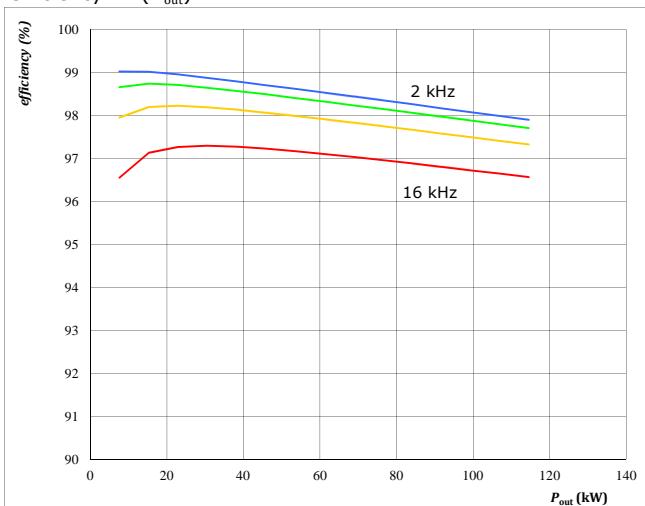
$$M_i = 1$$

$$\cos \varphi = 0,80$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

figure 10.
Inverter
Typical efficiency as a function of output power

$$\text{efficiency} = f(P_{\text{out}})$$


At

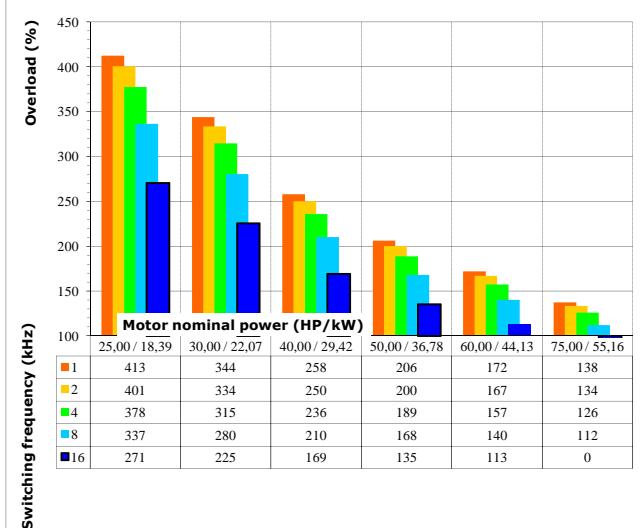
$$T_j = 125 \quad ^\circ\text{C}$$

$$\text{DC-link} = 600 \quad \text{V}$$

$$M_i = 1$$

$$\cos \varphi = 0,80$$

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

figure 11.
Inverter
Typical available overload factor as a function of
motor power and switching frequency
 $P_{\text{peak}} / P_{\text{nom}} = f(P_{\text{nom}}, f_{\text{sw}})$

At

$$T_j = 125 \quad ^\circ\text{C}$$

$$\text{DC-link} = 600 \quad \text{V}$$

$$M_i = 1$$

$$\cos \varphi = 0,8$$

$$T_s = 80 \quad ^\circ\text{C}$$

$$\text{Motor eff} = 0,85$$

 f_{sw} from 1 kHz to 16 kHz in steps of factor 2