

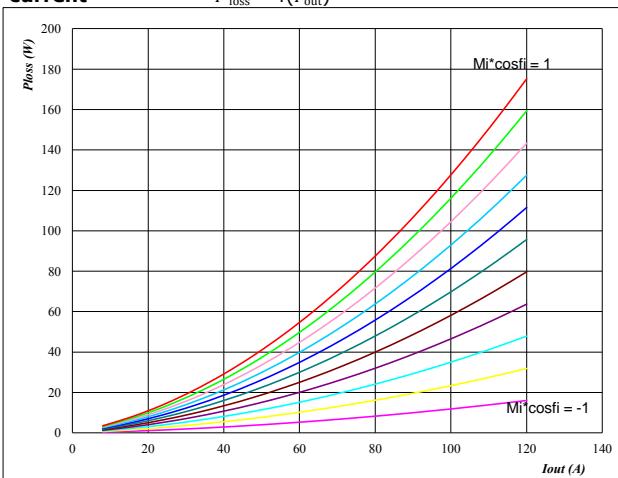
General conditions

3phase SPWM	
$V_{G\text{eon}}$	= 15 V
$V_{G\text{off}}$	= -15 V
$R_{g\text{on}}$	= 4 Ω
$R_{g\text{off}}$	= 4 Ω

Figure 1

IGBT

Typical average static loss as a function of output current
 $P_{\text{loss}} = f(I_{\text{out}})$



At

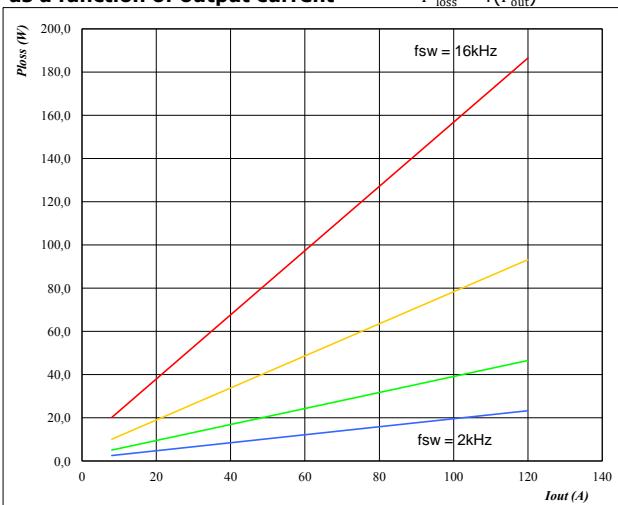
 $T_j = 150^\circ\text{C}$

Mi*cosphi from -1 to 1 in steps of 0,2

Figure 3

IGBT

Typical average switching loss
 as a function of output current
 $P_{\text{loss}} = f(I_{\text{out}})$



At

 $T_j = 150^\circ\text{C}$

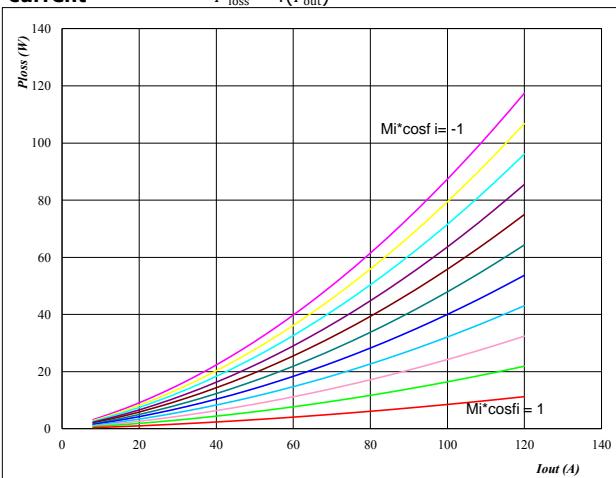
DC link = 600 V

 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 2

FWD

Typical average static loss as a function of output current
 $P_{\text{loss}} = f(I_{\text{out}})$



At

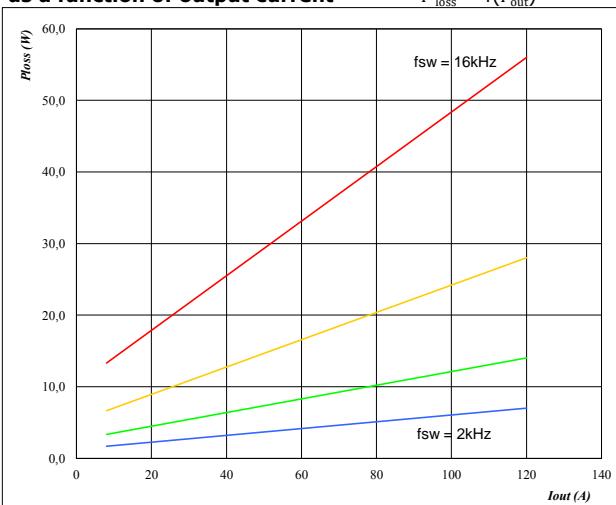
 $T_j = 150^\circ\text{C}$

Mi*cosphi from -1 to 1 in steps of 0,2

Figure 4

FWD

Typical average switching loss
 as a function of output current
 $P_{\text{loss}} = f(I_{\text{out}})$



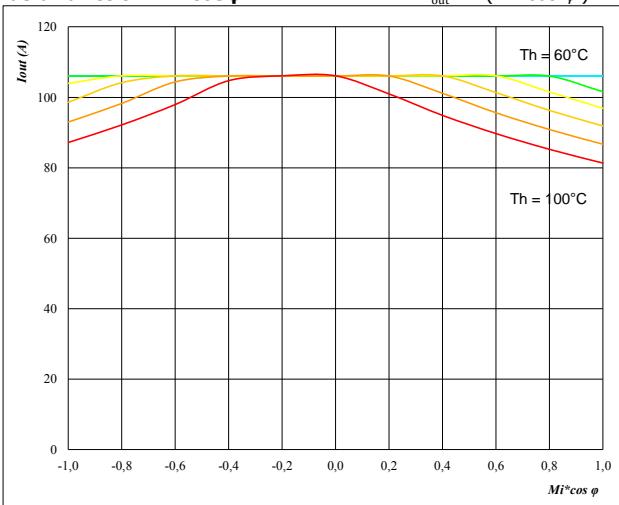
At

 $T_j = 150^\circ\text{C}$

DC link = 600 V

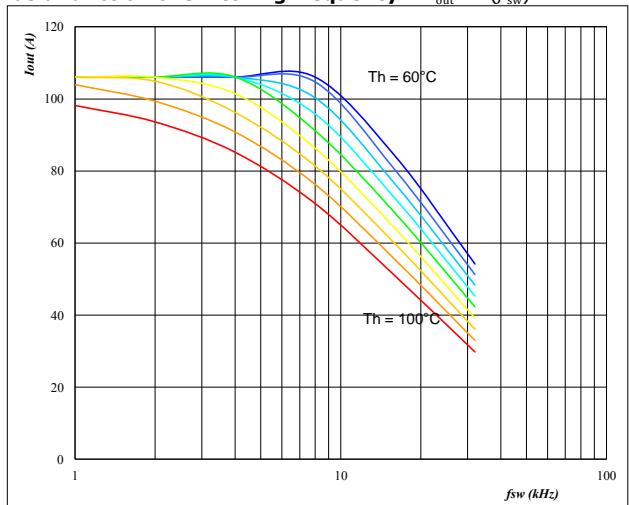
 f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 5 Phase
Typical available 50Hz output current as a function $M_i \cdot \cos \varphi$



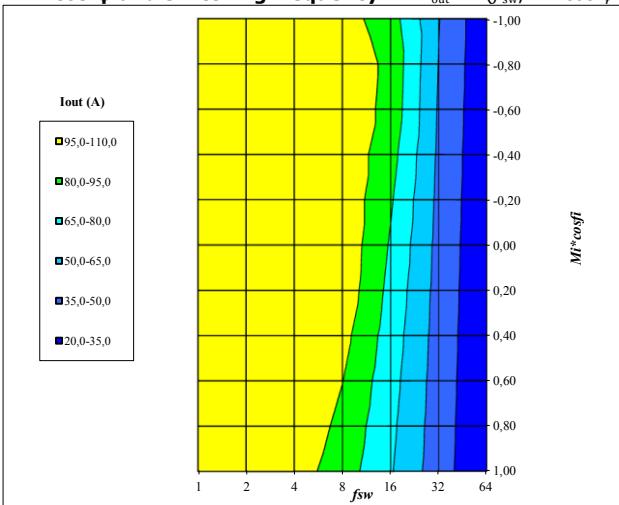
At
 $T_j = 150^\circ\text{C}$
DC link = 600 V
 $f_{sw} = 4 \text{ kHz}$
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 6 Phase
Typical available 50Hz output current as a function of switching frequency



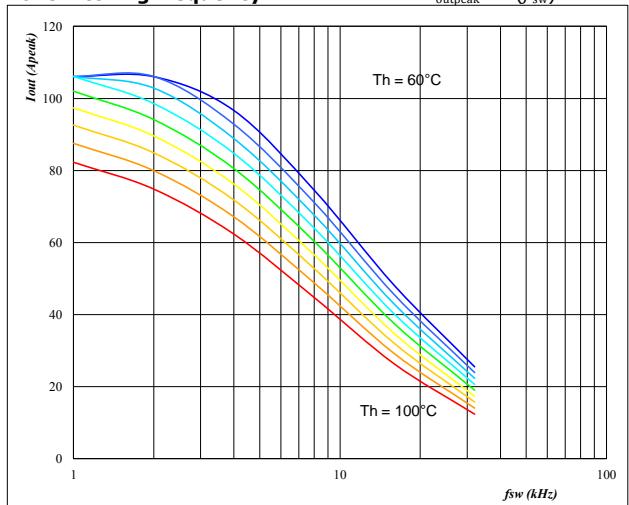
At
 $T_j = 150^\circ\text{C}$
DC link = 600 V
 $M_i \cdot \cos \varphi : 0,8$
 T_h from 60 °C to 100 °C in steps of 5 °C

Figure 7 Phase
Typical available 50Hz output current as a function of $M_i \cdot \cos \varphi$ and switching frequency



At
 $T_j = 150^\circ\text{C}$
DC link = 600 V
 $T_h = 80^\circ\text{C}$

Figure 8 Phase
Typical available 0Hz output current as a function of switching frequency



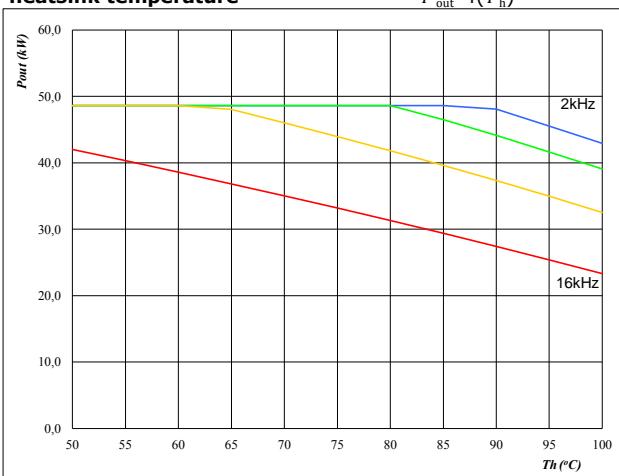
At
 $T_j = 150^\circ\text{C}$
DC link = 600 V
 T_h from 60 °C to 100 °C in steps of 5 °C
 $M_i = 0$

Figure 9

Inverter

Typical available peak output power as a function of heatsink temperature

$$P_{out} = f(T_h)$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

$$Mi = 1$$

$$\cos \varphi = 0,80$$

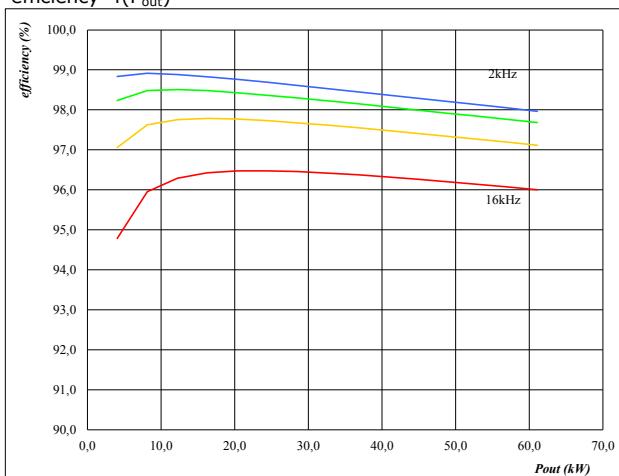
f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 10

Inverter

Typical efficiency as a function of output power

$$\text{efficiency} = f(P_{out})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

$$Mi = 1$$

$$\cos \varphi = 0,80$$

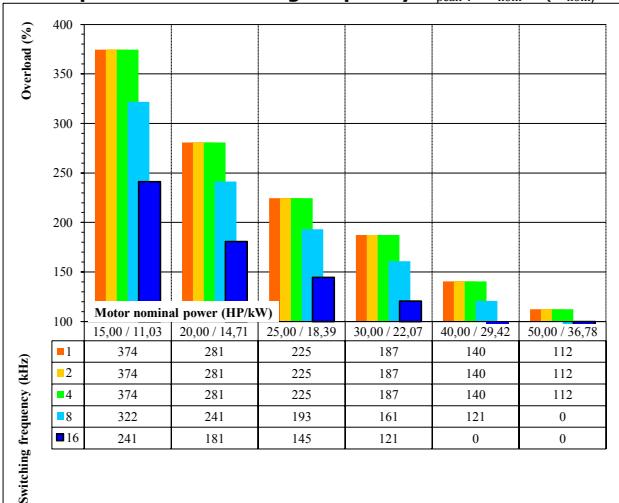
f_{sw} from 2 kHz to 16 kHz in steps of factor 2

Figure 11

Inverter

Typical available overload factor as a function of motor power and switching frequency

$$P_{peak} / P_{nom} = f(P_{nom}, f_{sw})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

$$Mi = 1$$

$$\cos \varphi = 0,8$$

f_{sw} from 1 kHz to 16 kHz in steps of factor 2

$$T_h = 80 \text{ } ^\circ\text{C}$$

$$\text{Motor eff} = 0,85$$