

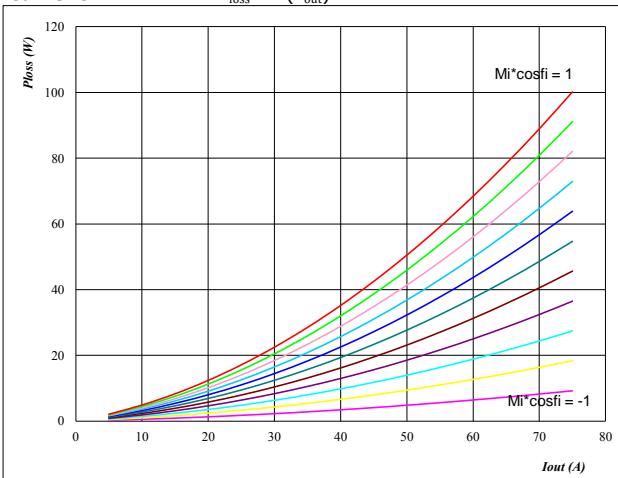
## General conditions

<b>3phase SPWM</b>
$V_{G\text{On}} = 15 \text{ V}$
$V_{G\text{Off}} = -15 \text{ V}$
$R_{g\text{on}} = 8 \Omega$
$R_{g\text{off}} = 8 \Omega$

**Figure 1**

IGBT

Typical average static loss as a function of output current  
 $P_{\text{loss}} = f(I_{\text{out}})$

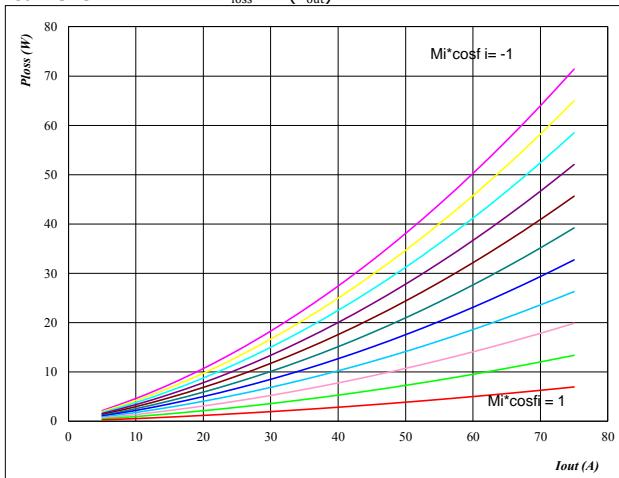
**At** $T_j = 150 \text{ }^\circ\text{C}$ 

Mi\*cosphi from -1 to 1 in steps of 0,2

**Figure 2**

FWD

Typical average static loss as a function of output current  
 $P_{\text{loss}} = f(I_{\text{out}})$

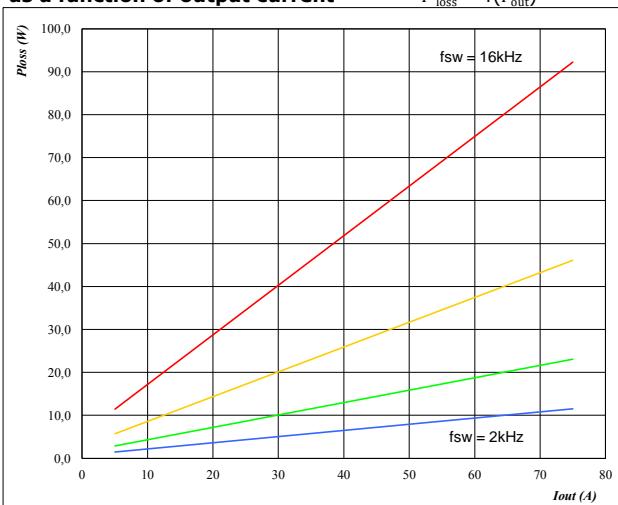
**At** $T_j = 150 \text{ }^\circ\text{C}$ 

Mi\*cosphi from -1 to 1 in steps of 0,2

**Figure 3**

IGBT

Typical average switching loss as a function of output current  
 $P_{\text{loss}} = f(I_{\text{out}})$

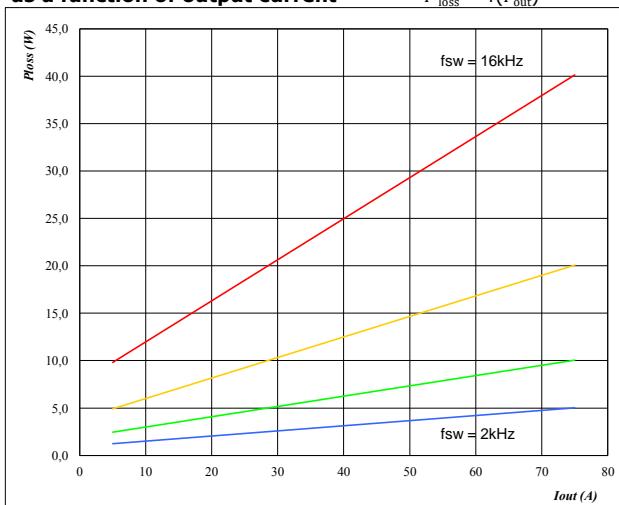
**At** $T_j = 150 \text{ }^\circ\text{C}$ 

DC link = 600 V

 $f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2**Figure 4**

FWD

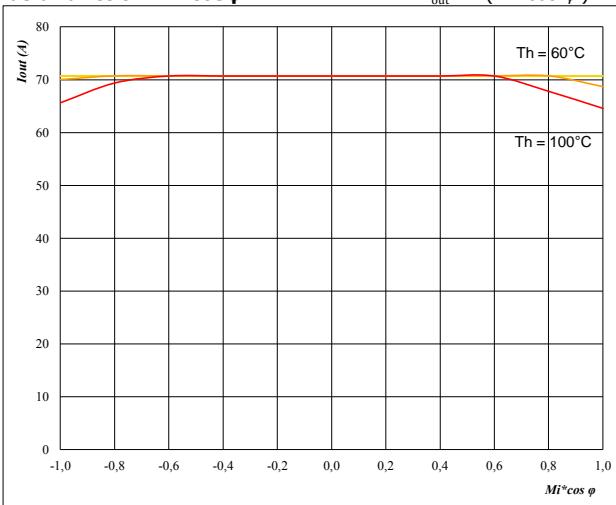
Typical average switching loss as a function of output current  
 $P_{\text{loss}} = f(I_{\text{out}})$

**At** $T_j = 150 \text{ }^\circ\text{C}$ 

DC link = 600 V

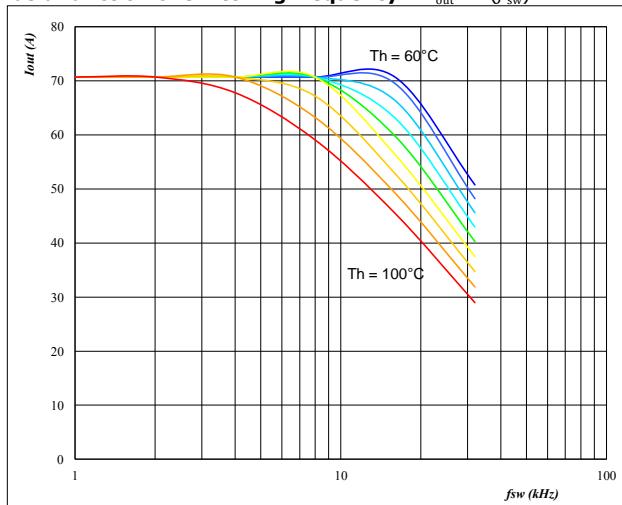
 $f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 5** Phase  
**Typical available 50Hz output current as a function  $M_i \cdot \cos \varphi$**   
 $I_{out} = f(M_i \cdot \cos \varphi)$



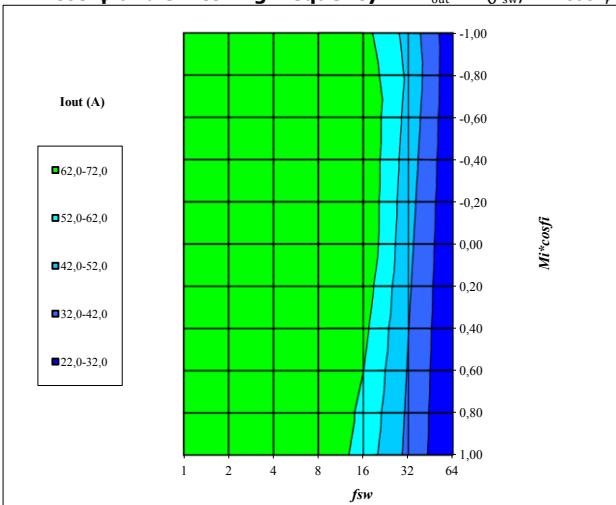
**At**  
 $T_j = 150 \quad ^\circ\text{C}$   
DC link = 600 V  
 $f_{sw} = 4 \quad \text{kH}\zeta$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 6** Phase  
**Typical available 50Hz output current as a function of switching frequency**  
 $I_{out} = f(f_{sw})$



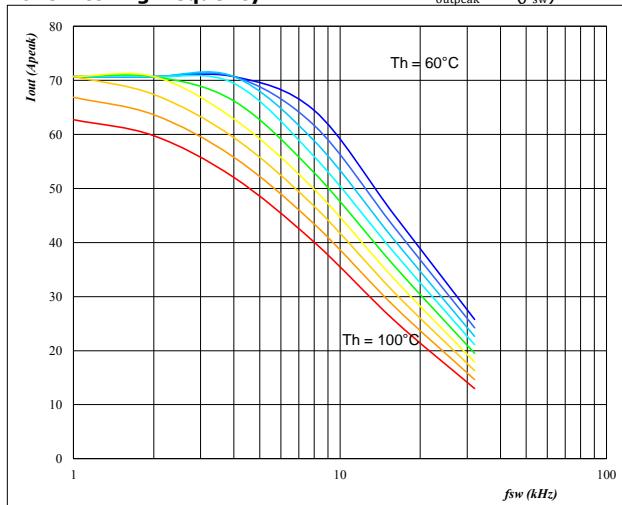
**At**  
 $T_j = 150 \quad ^\circ\text{C}$   
DC link = 600 V  
 $M_i \cdot \cos \varphi : 0,8$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 7** Phase  
**Typical available 50Hz output current as a function of  $M_i \cdot \cos \varphi$  and switching frequency**  
 $I_{out} = f(f_{sw}, M_i \cdot \cos \varphi)$



**At**  
 $T_j = 150 \quad ^\circ\text{C}$   
DC link = 600 V  
 $T_h = 80 \quad ^\circ\text{C}$

**Figure 8** Phase  
**Typical available 0Hz output current as a function of switching frequency**  
 $I_{outpeak} = f(f_{sw})$



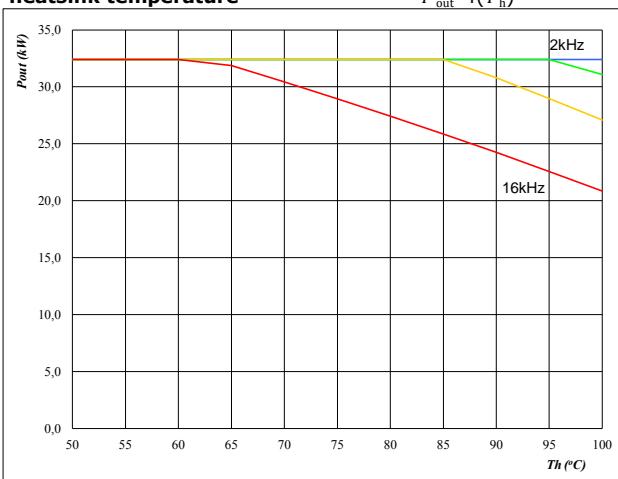
**At**  
 $T_j = 150 \quad ^\circ\text{C}$   
DC link = 600 V  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C  
 $M_i = 0$

**Figure 9**

Inverter

**Typical available peak output power as a function of heatsink temperature**

$$P_{\text{out}} = f(T_h)$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ } \text{V}$$

$$M_i = 1$$

$$\cos \varphi = 0,80$$

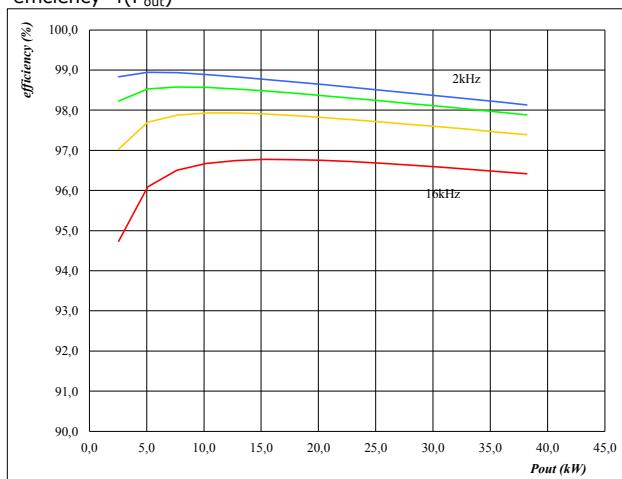
$f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 10**

Inverter

**Typical efficiency as a function of output power**

$$\text{efficiency} = f(P_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ } \text{V}$$

$$M_i = 1$$

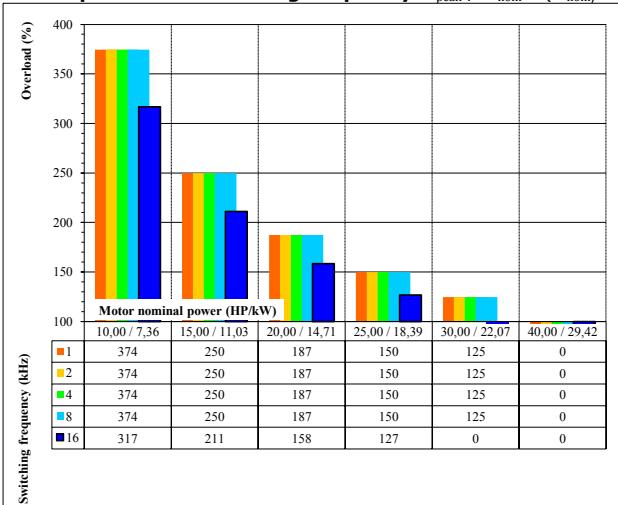
$$\cos \varphi = 0,80$$

$f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 11**

Inverter

**Typical available overload factor as a function of motor power and switching frequency**  $P_{\text{peak}} / P_{\text{nom}} = f(P_{\text{nom}}, f_{\text{sw}})$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ } \text{V}$$

$$M_i = 1$$

$$\cos \varphi = 0,8$$

$f_{\text{sw}}$  from 1 kHz to 16 kHz in steps of factor 2

$$T_h = 80 \text{ } ^\circ\text{C}$$

$$\text{Motor eff} = 0,85$$