

**General conditions**

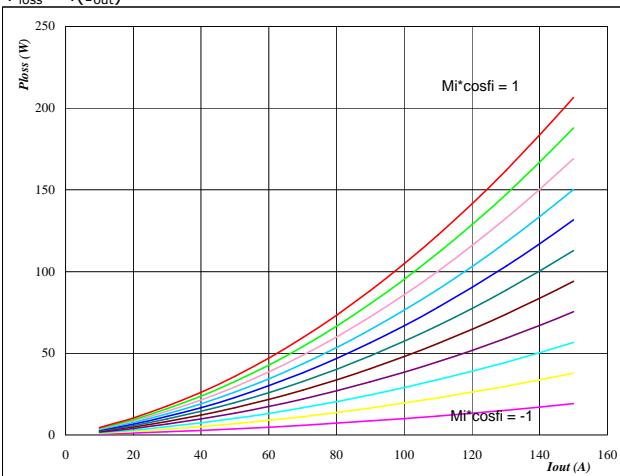
3phase SPWM	
$V_{GEon}$	= 15 V
$V_{GOff}$	= -15 V
$R_{gon}$	= 1 Ω
$R_{goff}$	= 1 Ω

**Figure 1**

IGBT

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

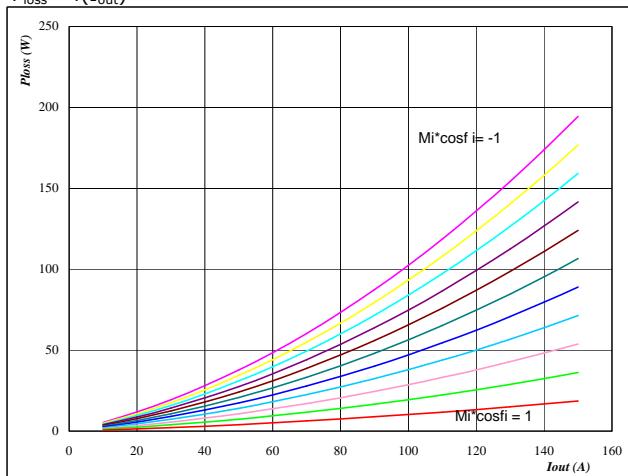
Mi\*cosphi from -1 to 1 in steps of 0,2

**Figure 2**

FWD

**Typical average static loss as a function of output current**

$$P_{loss} = f(I_{out})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

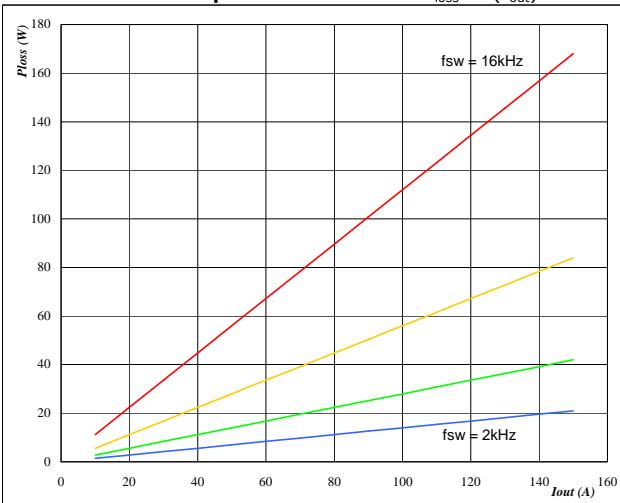
Mi\*cosphi from -1 to 1 in steps of 0,2

**Figure 3**

IGBT

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

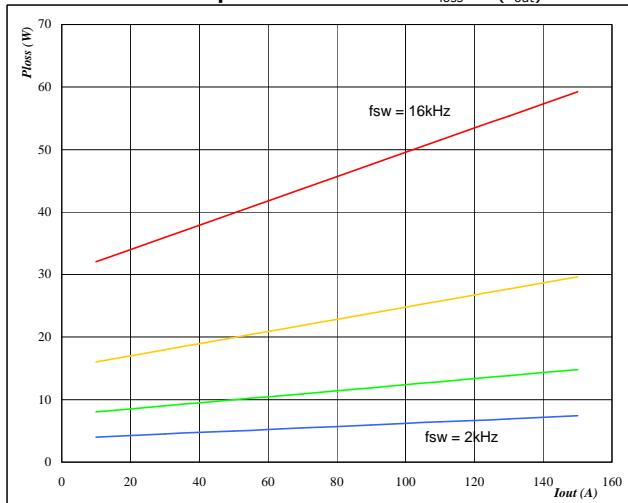
$$\text{DC link} = 600 \text{ } \text{V}$$

f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2**Figure 4**

FWD

**Typical average switching loss as a function of output current**

$$P_{loss} = f(I_{out})$$

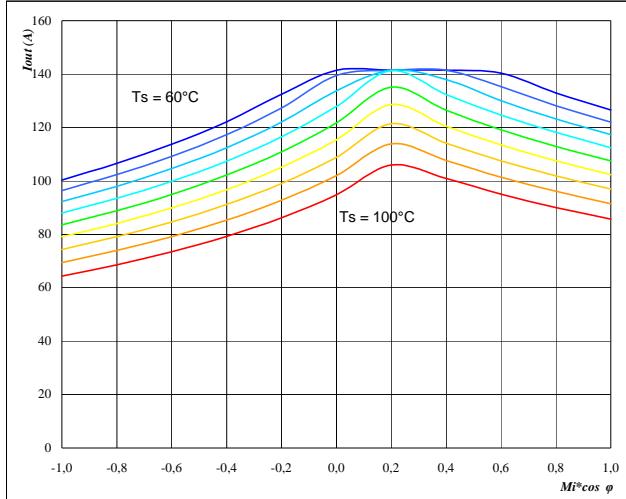
**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ } \text{V}$$

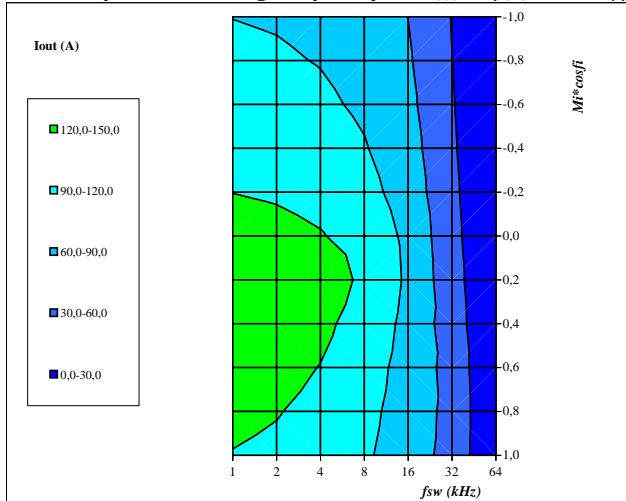
f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

**Figure 5** Phase  
Typical available 50Hz output current as a function  $M_i \cos \phi$



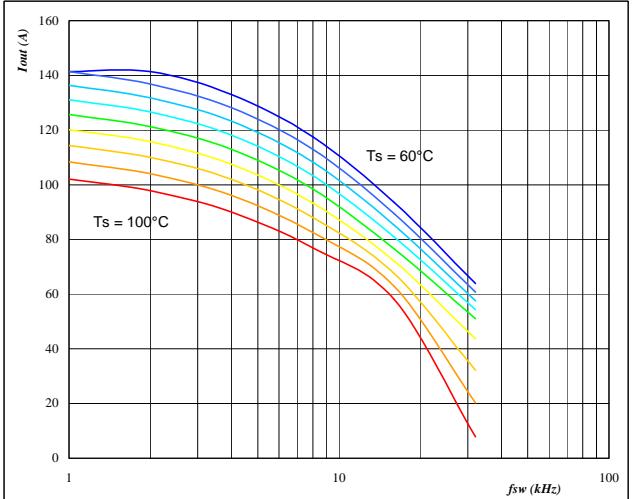
**At**  
 $T_j = 150^\circ C$   
DC link = 600 V  
 $f_{sw} = 4 \text{ kHz}$   
 $T_s$  from  $60^\circ C$  to  $100^\circ C$  in steps of  $5^\circ C$

**Figure 7** Phase  
Typical available 50Hz output current as a function of  $M_i \cos \phi$  and switching frequency



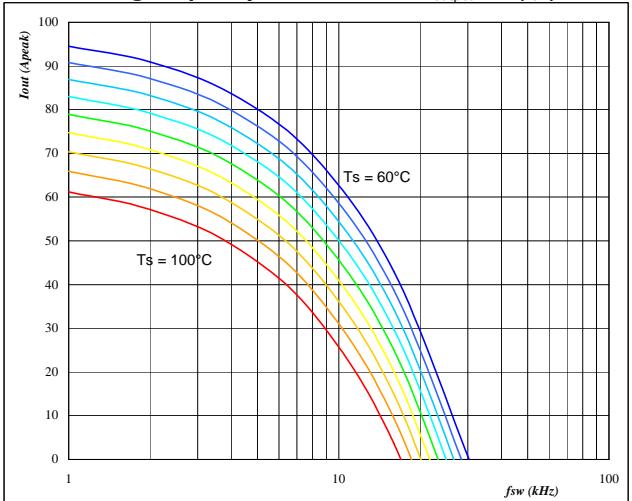
**At**  
 $T_j = 150^\circ C$   
DC link = 600 V  
 $T_s = 80^\circ C$

**Figure 6** Phase  
Typical available 50Hz output current as a function of switching frequency



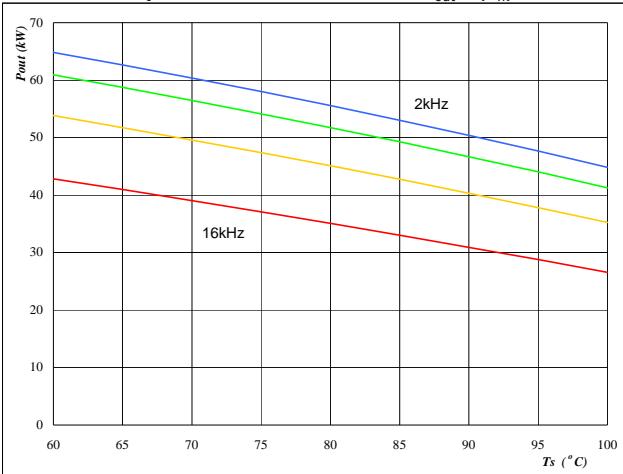
**At**  
 $T_j = 150^\circ C$   
DC link = 600 V  
 $M_i \cos \phi = 0.8$   
 $T_s$  from  $60^\circ C$  to  $100^\circ C$  in steps of  $5^\circ C$

**Figure 8** Phase  
Typical available 0Hz output current as a function of switching frequency



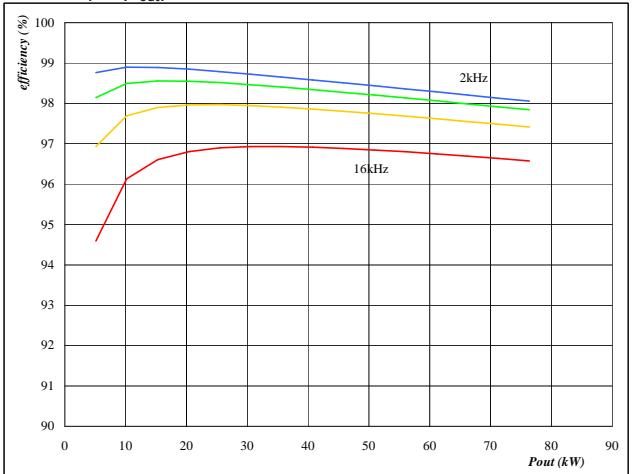
**At**  
 $T_j = 150^\circ C$   
DC link = 600 V  
 $T_s$  from  $60^\circ C$  to  $100^\circ C$  in steps of  $5^\circ C$   
 $M_i = 0$

**Figure 9** Inverter  
**Typical available peak output power as a function of heatsink temperature**  
 $P_{out}=f(T_h)$



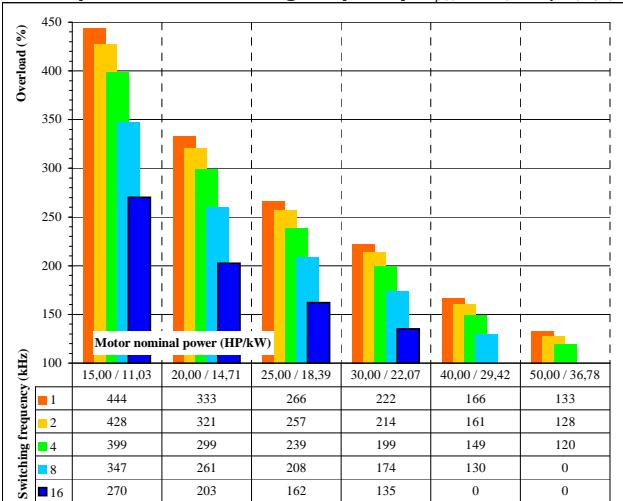
**At**  
T<sub>j</sub> = 150 °C  
DC link = 600 V  
Mi = 1  
cos φ = 0,80  
f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

**Figure 10** Inverter  
**Typical efficiency as a function of output power**  
efficiency=f(P<sub>out</sub>)



**At**  
T<sub>j</sub> = 150 °C  
DC link = 600 V  
Mi = 1  
cos φ = 0,80  
f<sub>sw</sub> from 2 kHz to 16 kHz in steps of factor 2

**Figure 11** Inverter  
**Typical available overload factor as a function of motor power and switching frequency**  $P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$



**At**  
T<sub>j</sub> = 150 °C  
DC link = 600 V  
Mi = 1  
cos φ = 0,8  
f<sub>sw</sub> from 1 kHz to 16 kHz in steps of factor 2  
T<sub>s</sub> = 80 °C  
Motor eff = 0,85