

flow3xPHASE SiC
Output Inverter Application
1200 V/80 mΩ
General conditions
3phase SPWM

$$V_{G\text{On}} = 20 \text{ V}$$

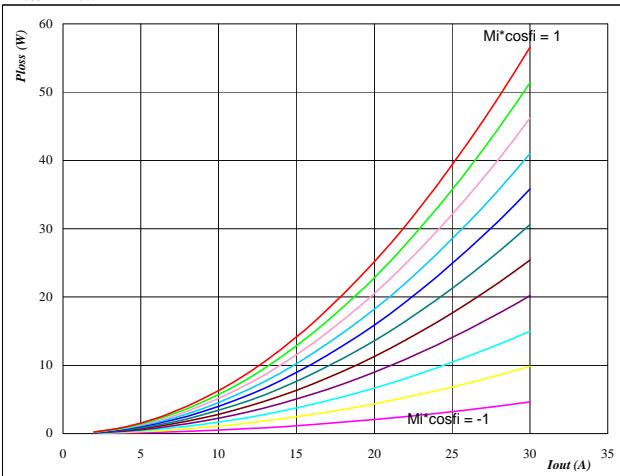
$$V_{G\text{Off}} = -5 \text{ V}$$

$$R_{g\text{on}} = 4 \Omega$$

$$R_{g\text{off}} = 4 \Omega$$

Splitted Configuration
Figure 1
Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

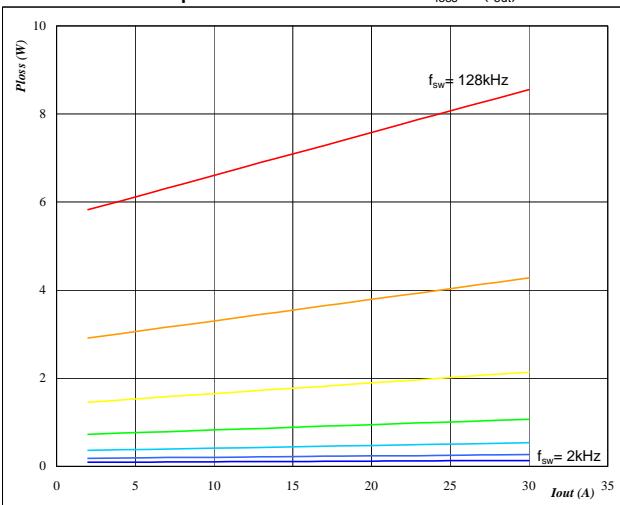

At

$$T_j = 126 \text{ } ^\circ\text{C}$$

 $Mi^*\cos\phi$ from -1 to 1 in steps of 0,2

Figure 3
MOSFET
Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$


At

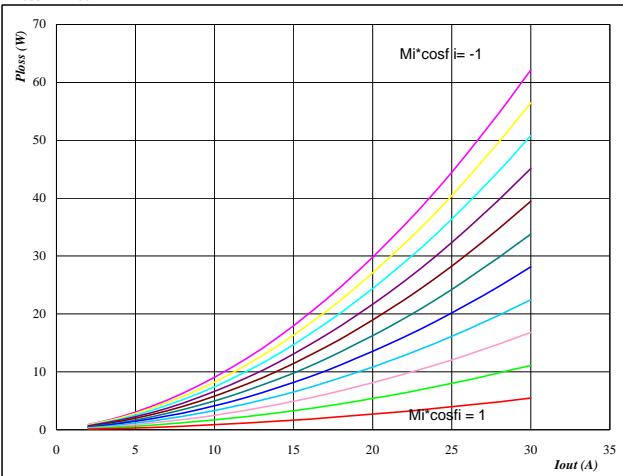
$$T_j = 126 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 700 \text{ V}$$

 f_{sw} from 2 kHz to 128 kHz in steps of factor 2

Figure 2
Typical average static loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$

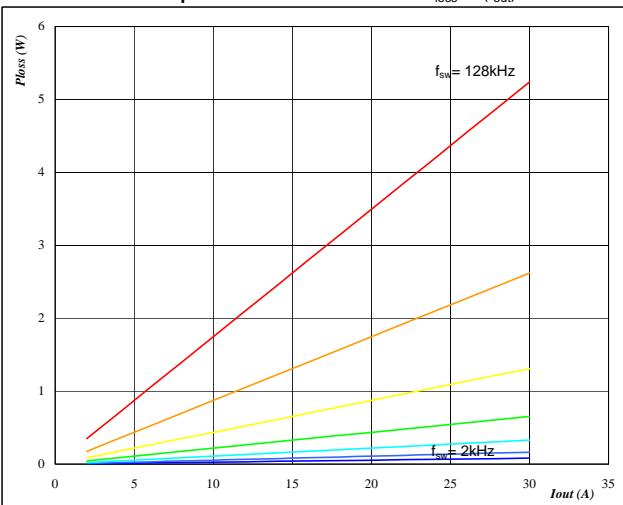

At

$$T_j = 126 \text{ } ^\circ\text{C}$$

 $Mi^*\cos\phi$ from -1 to 1 in steps of 0,2

Figure 4
FWD
Typical average switching loss as a function of output current

$$P_{\text{loss}} = f(I_{\text{out}})$$


At

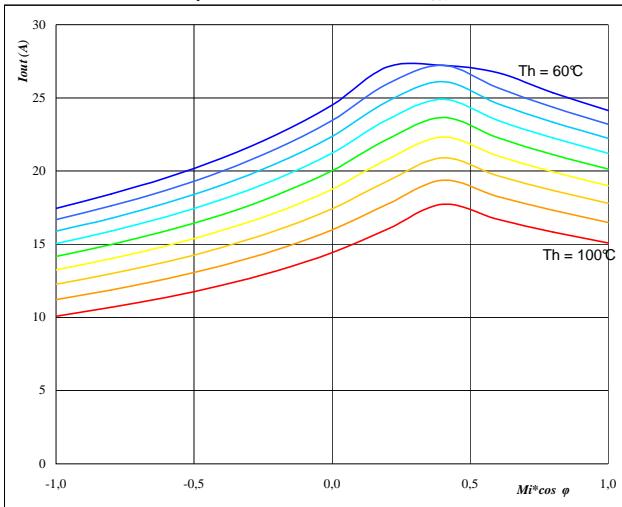
$$T_j = 126 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 700 \text{ V}$$

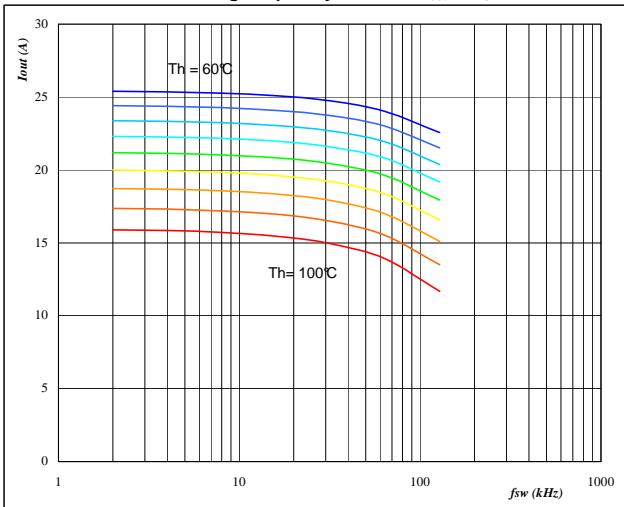
 f_{sw} from 2 kHz to 128 kHz in steps of factor 2

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Figure 5
**Typical available 50Hz output current
as a function $M_i \cos \varphi$**
Phase

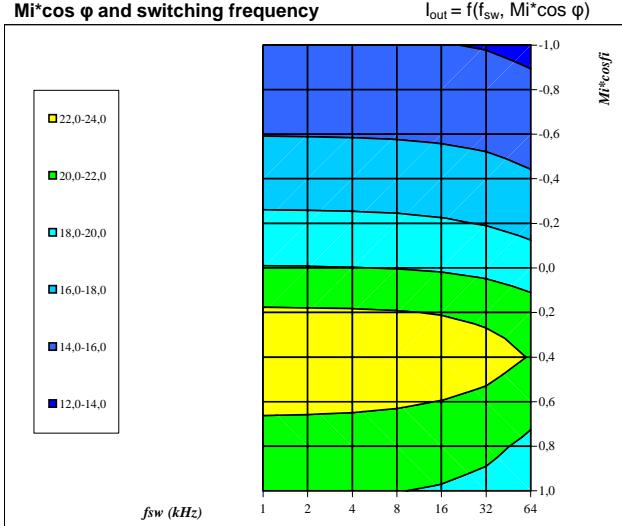
$$I_{out} = f(M_i \cos \varphi)$$


At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $f_{sw} = 4 \text{ } \text{kHz}$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
Figure 6
**Typical available 50Hz output current
as a function of switching frequency**
Phase

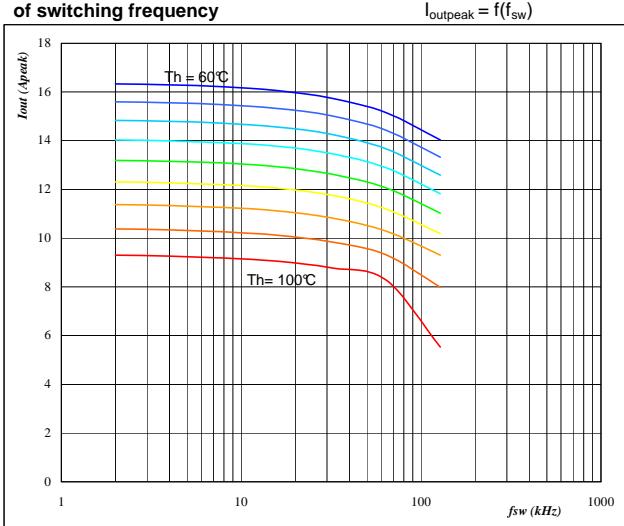
$$I_{out} = f(f_{sw})$$


At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $M_i \cos \varphi = 0,8$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
Figure 7
**Typical available 50Hz output current as a function of
 $M_i \cos \varphi$ and switching frequency**
Phase

$$I_{out} = f(f_{sw}, M_i \cos \varphi)$$

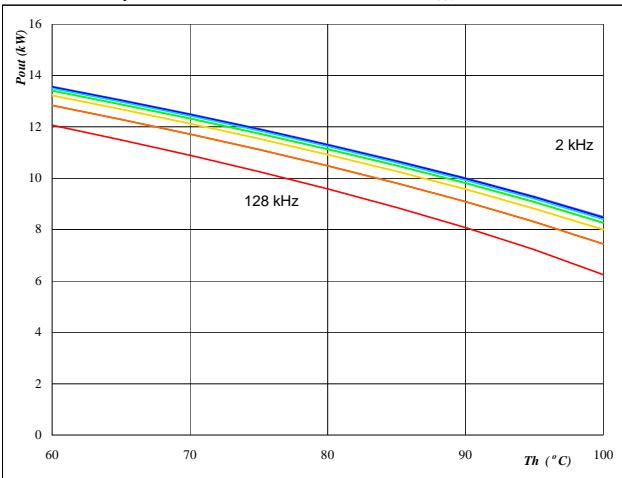

At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $T_h = 80 \text{ } ^\circ\text{C}$
Figure 8
**Typical available 0Hz output current as a function
of switching frequency**
Phase

$$I_{outpeak} = f(f_{sw})$$

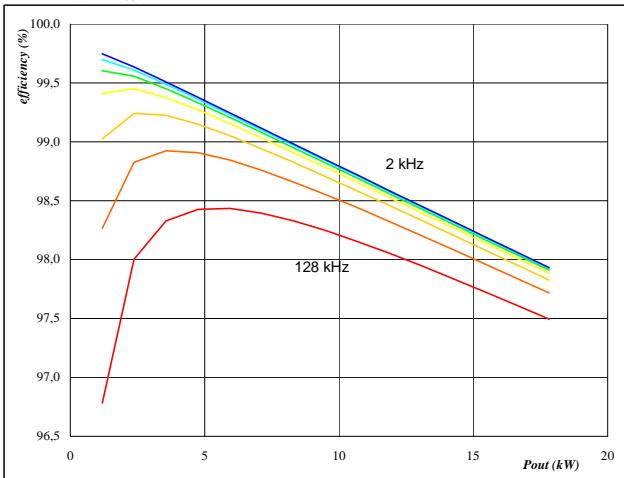

At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $T_h \text{ from } 60 \text{ } ^\circ\text{C to } 100 \text{ } ^\circ\text{C in steps of } 5 \text{ } ^\circ\text{C}$
 $M_i = 0$

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Figure 9
Inverter
Typical available peak output power as a function of heatsink temperature

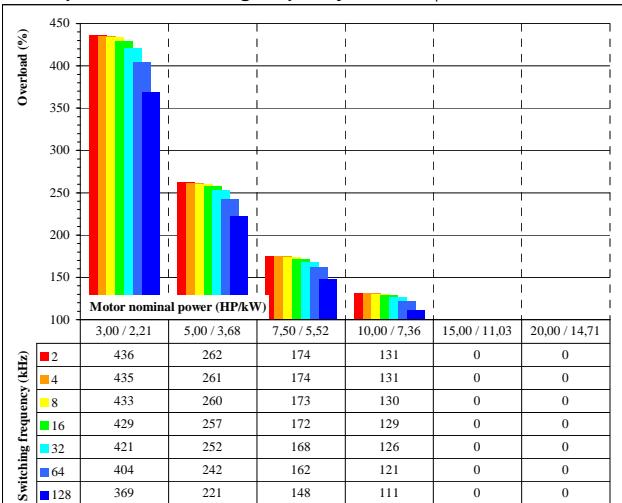
$$P_{out}=f(T_h)$$


At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $M_i = 1$
 $\cos \varphi = 0,80$
 $f_{sw} \text{ from } 2 \text{ kHz to } 128 \text{ kHz in steps of factor 2}$
Figure 10
Inverter
Typical efficiency as a function of output power

$$\text{efficiency}=f(P_{out})$$


At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $M_i = 1$
 $\cos \varphi = 0,80$
 $f_{sw} \text{ from } 2 \text{ kHz to } 128 \text{ kHz in steps of factor 2}$
Figure 11
Inverter
Typical available overload factor as a function of
motor power and switching frequency

$$P_{peak} / P_{nom}=f(P_{nom}, f_{sw})$$


At
 $T_j = 126 \text{ } ^\circ\text{C}$
 $\text{DC link} = 700 \text{ } \text{V}$
 $M_i = 1$
 $\cos \varphi = 0,8$
 $f_{sw} \text{ from } 2 \text{ kHz to } 128 \text{ kHz in steps of factor 2}$
 $T_h = 80 \text{ } ^\circ\text{C}$
 $\text{Motor eff} = 0,85$