

## General conditions

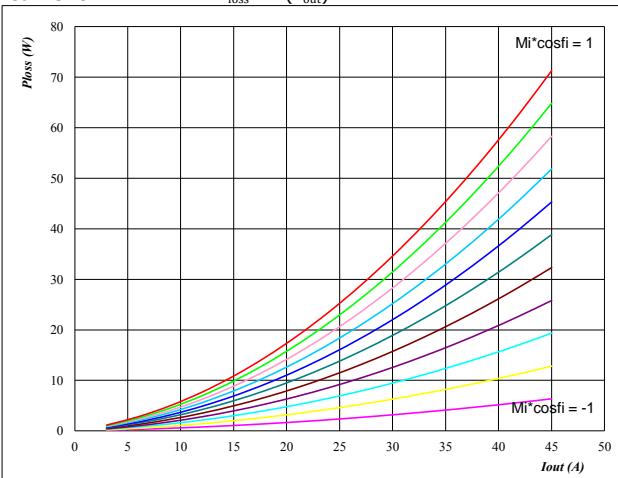
<b>3phase SPWM</b>
$V_{G\text{On}} = 15 \text{ V}$
$V_{G\text{Off}} = -15 \text{ V}$
$R_{g\text{on}} = 16 \Omega$
$R_{g\text{off}} = 16 \Omega$

**Figure 1**

IGBT

**Typical average static loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

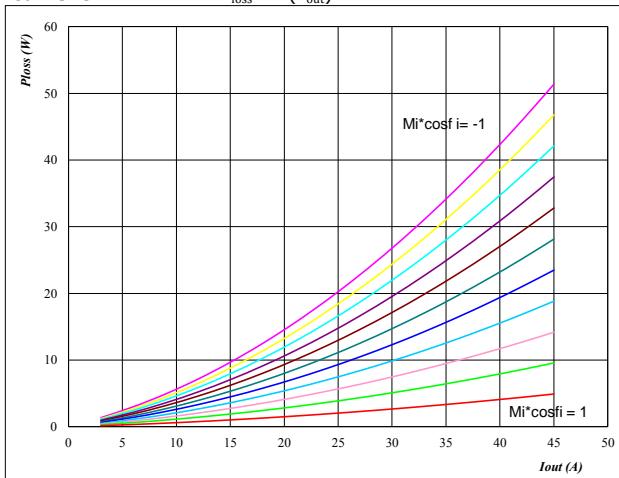
Mi\*cosphi from -1 to 1 in steps of 0,2

**Figure 2**

FWD

**Typical average static loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

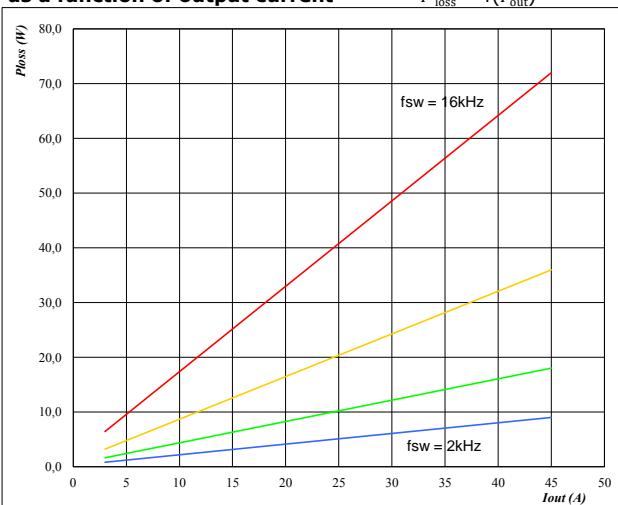
Mi\*cosphi from -1 to 1 in steps of 0,2

**Figure 3**

IGBT

**Typical average switching loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

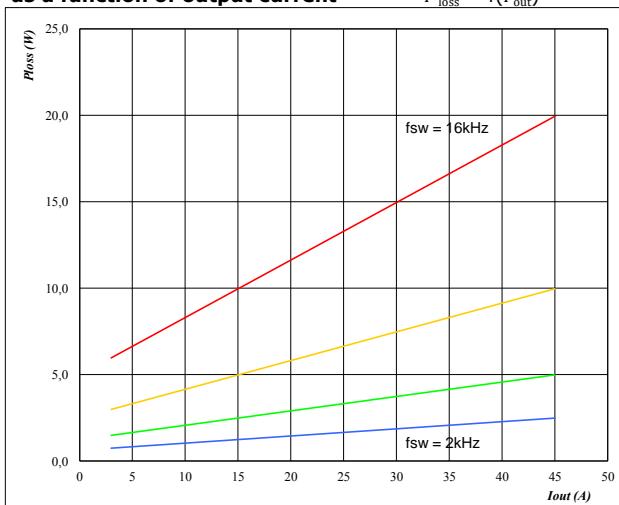
$f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 4**

FWD

**Typical average switching loss as a function of output current**

$$P_{\text{loss}} = f(I_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

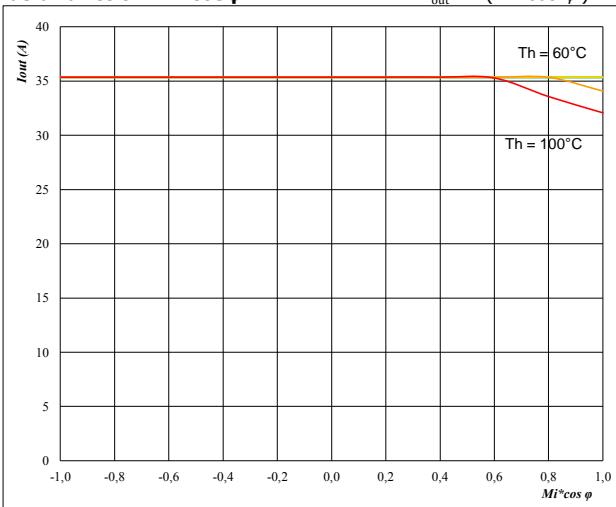
$f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 5**

Phase

**Typical available 50Hz output current  
as a function  $M_i \cdot \cos \varphi$**

$$I_{out} = f(M_i \cdot \cos \varphi)$$

**At**

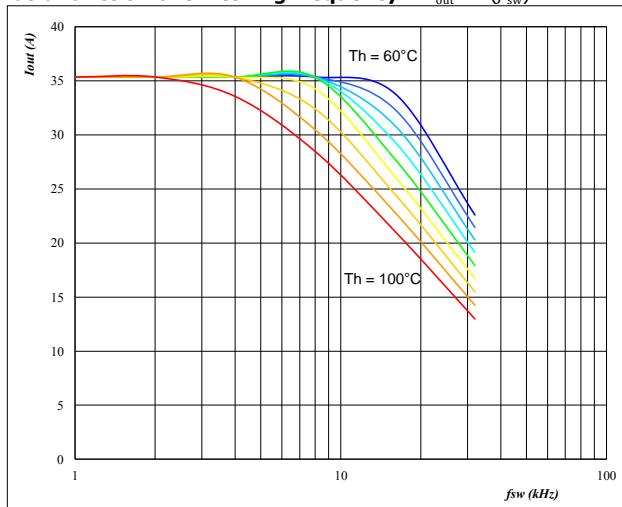
$T_j = 150 \text{ } ^\circ\text{C}$   
DC link = 600 V  
 $f_{sw} = 4 \text{ kHz}$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 6**

Phase

**Typical available 50Hz output current  
as a function of switching frequency**

$$I_{out} = f(f_{sw})$$

**At**

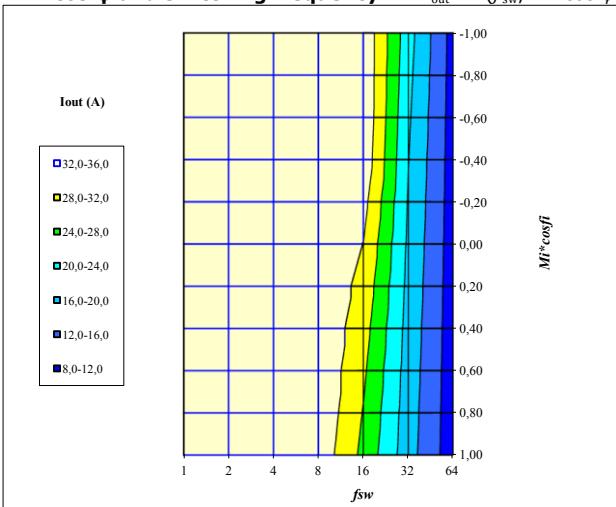
$T_j = 150 \text{ } ^\circ\text{C}$   
DC link = 600 V  
 $M_i \cdot \cos \varphi : 0,8$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 7**

Phase

**Typical available 50Hz output current as a function of  
 $M_i \cdot \cos \varphi$  and switching frequency**

$$I_{out} = f(f_{sw}, M_i \cdot \cos \varphi)$$

**At**

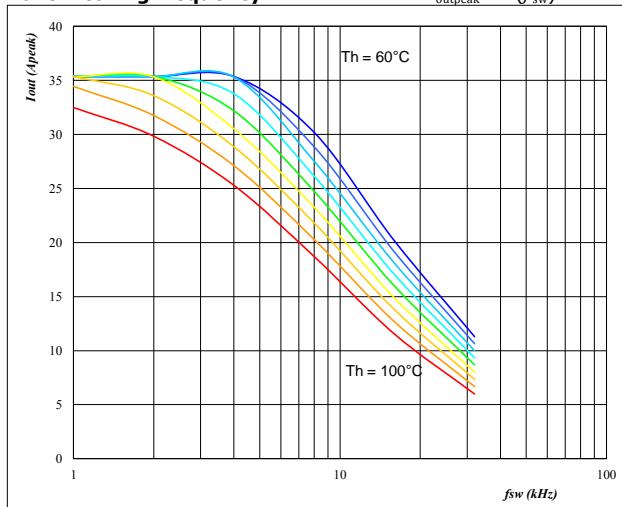
$T_j = 150 \text{ } ^\circ\text{C}$   
DC link = 600 V  
 $T_h = 80 \text{ } ^\circ\text{C}$

**Figure 8**

Phase

**Typical available 0Hz output current as a function  
of switching frequency**

$$I_{outpeak} = f(f_{sw})$$

**At**

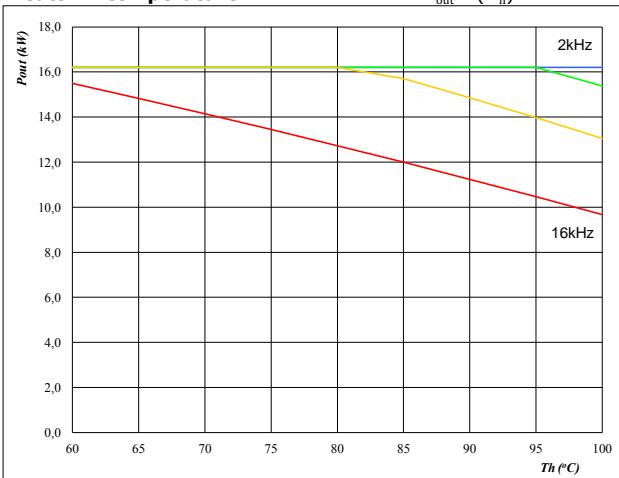
$T_j = 150 \text{ } ^\circ\text{C}$   
DC link = 600 V  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C  
 $M_i = 0$

**Figure 9**

Inverter

**Typical available peak output power as a function of heatsink temperature**

$$P_{\text{out}} = f(T_h)$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

$$M_i = 1$$

$$\cos \varphi = 0,80$$

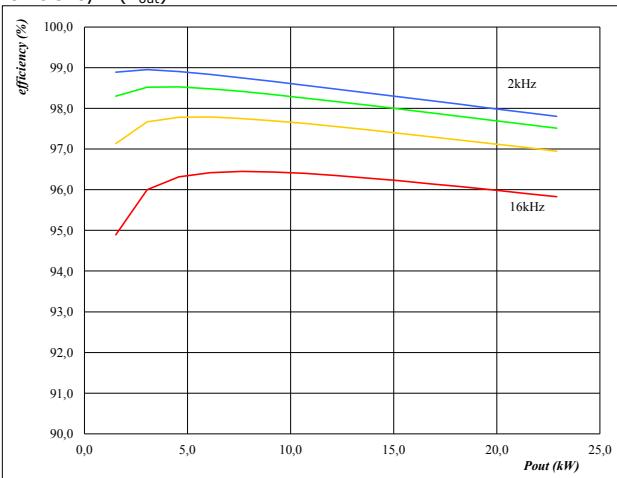
$f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 10**

Inverter

**Typical efficiency as a function of output power**

$$\text{efficiency} = f(P_{\text{out}})$$

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

$$M_i = 1$$

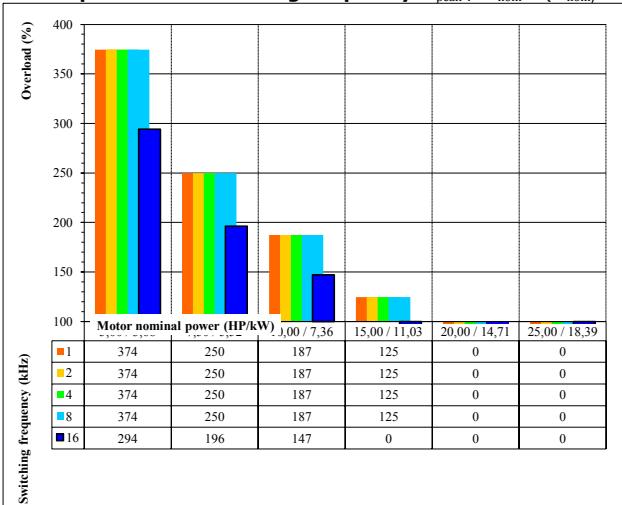
$$\cos \varphi = 0,80$$

$f_{\text{sw}}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 11**

Inverter

**Typical available overload factor as a function of motor power and switching frequency**

**At**

$$T_j = 150 \text{ } ^\circ\text{C}$$

$$\text{DC link} = 600 \text{ V}$$

$$M_i = 1$$

$$\cos \varphi = 0,8$$

$f_{\text{sw}}$  from 1 kHz to 16 kHz in steps of factor 2

$$T_h = 80 \text{ } ^\circ\text{C}$$

$$\text{Motor eff} = 0,85$$