

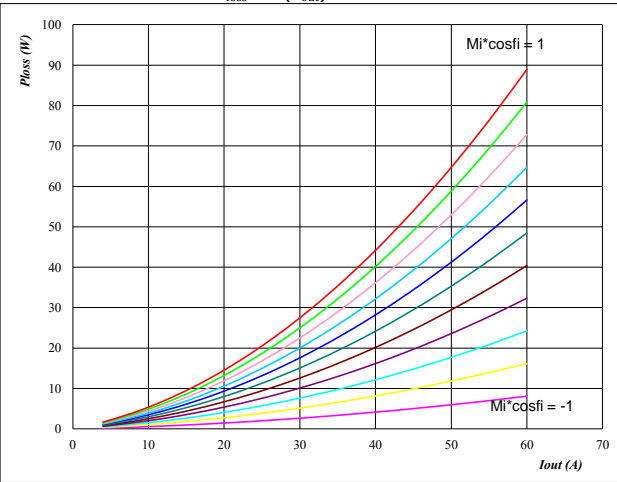


**flow 7PACK 1 Output Inverter Application 1200 V / 35 A**

**General conditions**

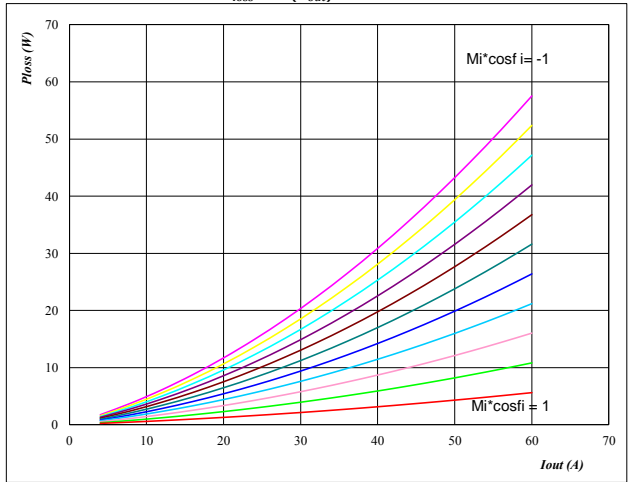
<b>3phase SPWM</b>	
$V_{GEon}$	= 15 V
$V_{GEoff}$	= -15 V
$R_{gon}$	= 16 $\Omega$
$R_{goff}$	= 16 $\Omega$

**Figure 1** IGBT  
**Typical average static loss as a function of output current**  
 $P_{loss} = f(I_{out})$



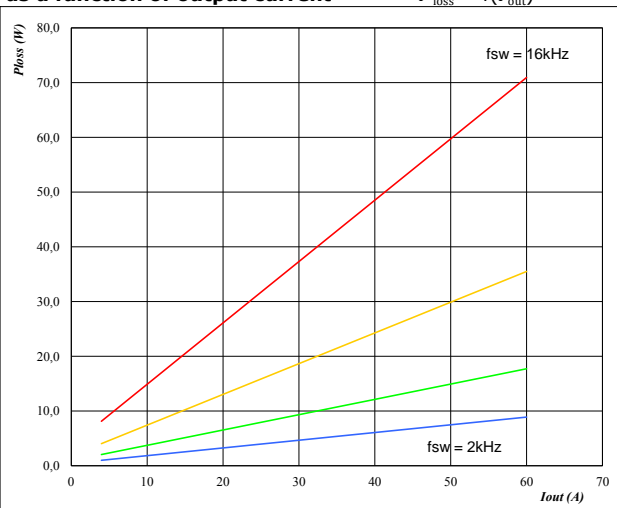
**At**  
 $T_j = 150 \text{ }^\circ\text{C}$   
 $Mi \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 2** FWD  
**Typical average static loss as a function of output current**  
 $P_{loss} = f(I_{out})$



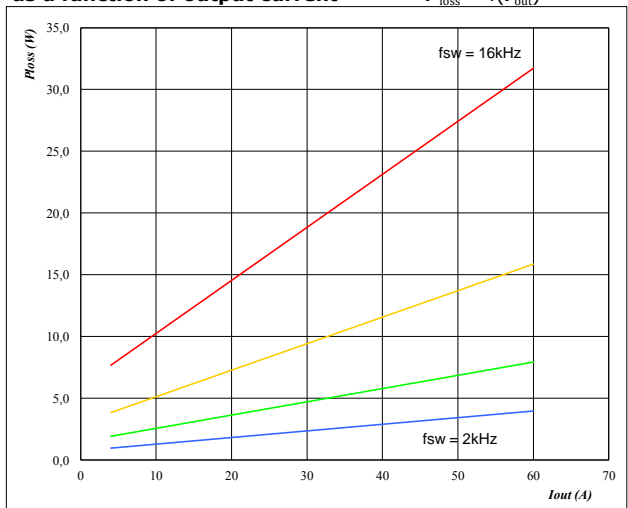
**At**  
 $T_j = 150 \text{ }^\circ\text{C}$   
 $Mi \cdot \cos\phi$  from -1 to 1 in steps of 0,2

**Figure 3** IGBT  
**Typical average switching loss as a function of output current**  
 $P_{loss} = f(I_{out})$



**At**  
 $T_j = 150 \text{ }^\circ\text{C}$   
 DC link = 600 V  
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 4** FWD  
**Typical average switching loss as a function of output current**  
 $P_{loss} = f(I_{out})$



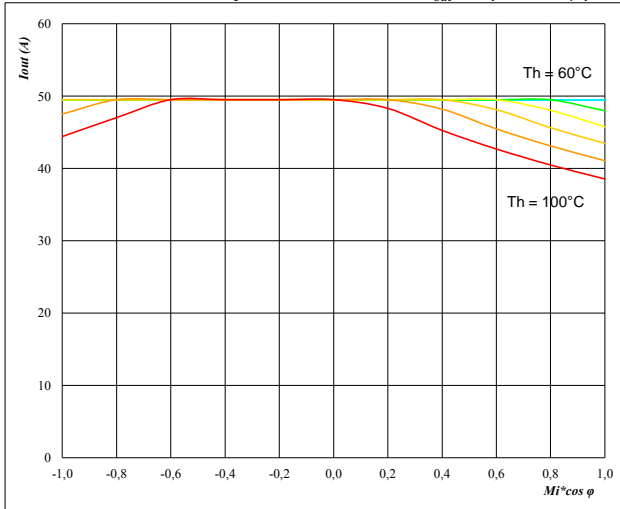
**At**  
 $T_j = 150 \text{ }^\circ\text{C}$   
 DC link = 600 V  
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2



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**Figure 5** Phase

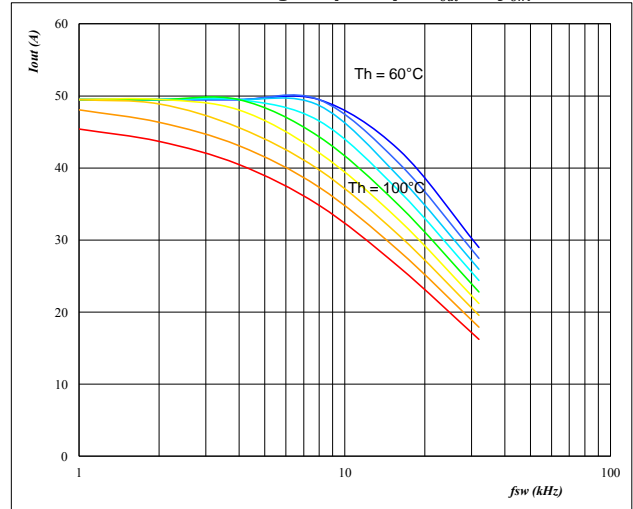
**Typical available 50Hz output current as a function  $Mi \cdot \cos \varphi$**   $I_{out} = f(Mi \cdot \cos \varphi)$



**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $f_{sw} = 4 \text{ kHz}$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 6** Phase

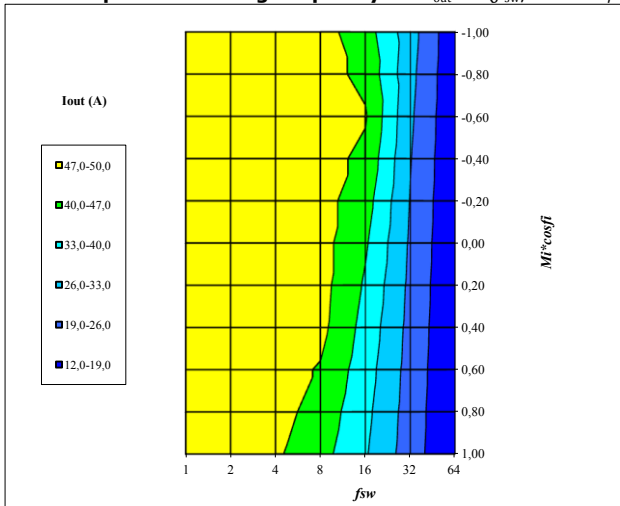
**Typical available 50Hz output current as a function of switching frequency**  $I_{out} = f(f_{sw})$



**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $Mi \cdot \cos \varphi : 0,8$   
 $T_h$  from 60 °C to 100 °C in steps of 5 °C

**Figure 7** Phase

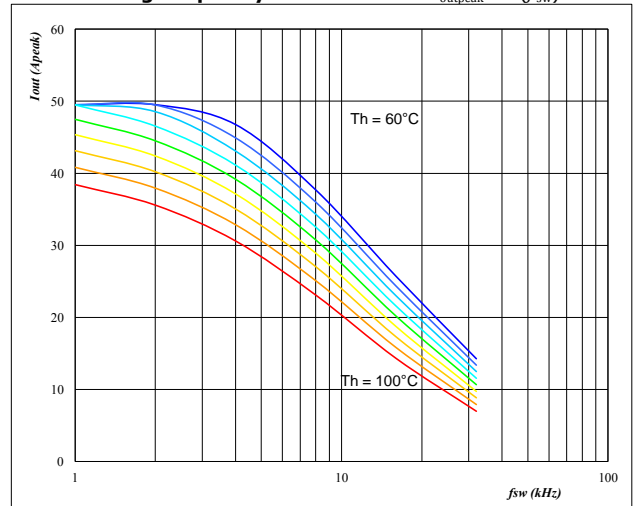
**Typical available 50Hz output current as a function of  $Mi \cdot \cos \varphi$  and switching frequency**  $I_{out} = f(f_{sw}, Mi \cdot \cos \varphi)$



**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h = 80 \text{ } ^\circ\text{C}$

**Figure 8** Phase

**Typical available 0Hz output current as a function of switching frequency**  $I_{outpeak} = f(f_{sw})$



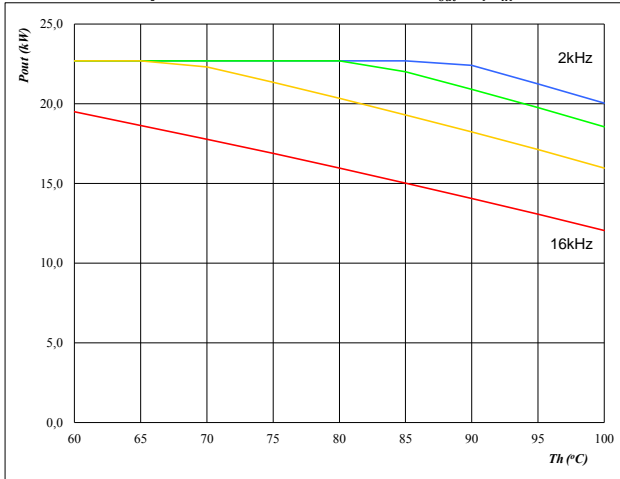
**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $T_h$  from 60 °C to 100 °C in steps of 5 °C  
 $Mi = 0$



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**Figure 9** Inverter

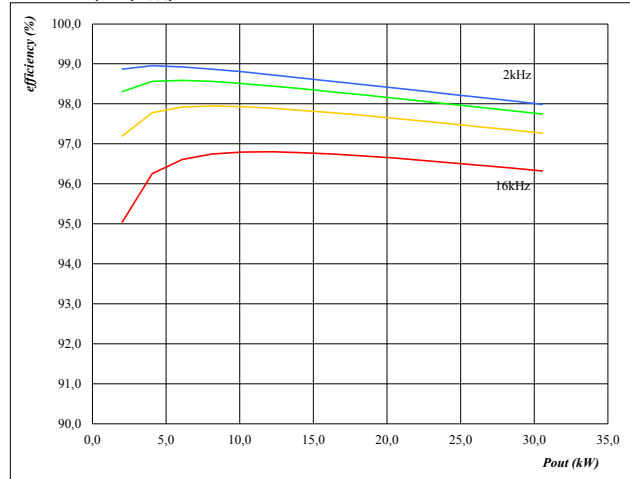
Typical available peak output power as a function of heatsink temperature  $P_{out} = f(T_h)$



**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos \varphi = 0,80$   
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 10** Inverter

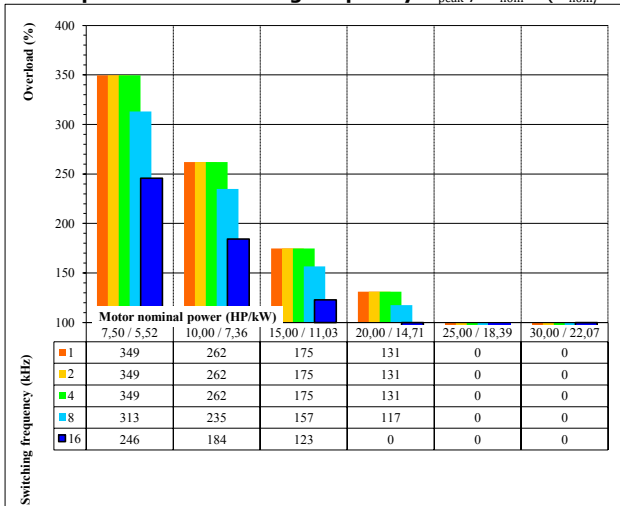
Typical efficiency as a function of output power  $\text{efficiency} = f(P_{out})$



**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos \varphi = 0,80$   
 $f_{sw}$  from 2 kHz to 16 kHz in steps of factor 2

**Figure 11** Inverter

Typical available overload factor as a function of motor power and switching frequency  $P_{peak} / P_{nom} = f(P_{nom}, f_{sw})$



**At**  
 $T_j = 150 \text{ } ^\circ\text{C}$   
 DC link = 600 V  
 $M_i = 1$   
 $\cos \varphi = 0,8$   
 $f_{sw}$  from 1 kHz to 16kHz in steps of factor 2  
 $T_h = 80 \text{ } ^\circ\text{C}$   
 Motor eff : 0,85